

Leading performance 240-MHz ARM Cortex-M4 microcontroller, up to 4-MB code flash memory, 640-KB SRAM, Graphics LCD Controller, 2D Drawing Engine, Capacitive Touch Sensing Unit, Ethernet MAC Controller with IEEE 1588 PTP, USB 2.0 High-Speed, USB 2.0 Full-Speed, SDHI, Quad SPI, security and safety features, and advanced analog.

## Features

### ■ ARM Cortex-M4 Core with Floating Point Unit (FPU)

- ARMv7E-M architecture with DSP instruction set
- Maximum operating frequency: 240 MHz
- Support for 4-GB address space
- On-chip debugging system: JTAG, SWD, and ETM
- Boundary scan and ARM Memory Protection Unit (MPU)

### ■ Memory

- Up to 4-MB code flash memory (80 MHz zero wait states)
- 64-KB data flash memory (up to 100,000 erase/write cycles)
- Up to 640-KB SRAM
- Flash Cache (FCACHE)
- Memory Protection Units (MPU)
- Memory Mirror Function (MMF)
- 128-bit unique ID

### ■ Connectivity

- Ethernet MAC Controller (ETHERC) × 2
- Ethernet DMA Controller (EDMAC)
- Ethernet PTP Controller (EPTPC)
- USB 2.0 High-Speed Module (USBHS)
  - On-chip transceiver
  - USB battery charge version 1.2 supported
- USB 2.0 Full-Speed Module (USBFS)
  - On-chip transceiver
- Serial Communications Interface (SCI) with FIFO × 10
- Serial Peripheral Interface (SPI) × 2
- I<sup>2</sup>C Bus Interface (IIC) × 3
- CAN module (CAN) × 2
- Serial Sound Interface (SSI) × 2
- SD/MMC Host Interface (SDHI) × 2
- Quad Serial Peripheral Interface (QSPI)
- IrDA interface
- Sampling Rate Converter (SRC)
- External memory bus
  - 8-bit and 16-bit address width
  - SDRAM support

### ■ Analog

- 12-Bit A/D Converter (ADC12) with 3 sample-and-hold circuits each, x2
- 12-Bit D/A Converter (DAC12) × 2
- High-Speed Analog Comparator (ACMPHS) × 6
- Programmable Gain Amplifier (PGA) × 6
- Temperature sensor (TSN)

### ■ Timers

- General PWM Timer 32-Bit Enhanced High Resolution (GPT32EH) × 4
- General PWM Timer 32-Bit Enhanced (GPT32E) × 4
- General PWM Timer 32-Bit (GPT32) × 6
- Asynchronous General-Purpose Timer (AGT) × 2
- Watchdog Timer (WDT)

### ■ Safety

- SRAM parity error check
- Flash area protection
- ADC self-diagnosis function
- Clock Frequency Accuracy Measurement Circuit (CAC)
- Cyclic Redundancy Check (CRC) calculator
- Data Operation Circuit (DOC)
- Port Output Enable for GPT (POEG)
- Independent Watchdog Timer (IWDT)
- GPIO readback level detection
- Register write protection
- Main oscillator stop detection
- Illegal memory access

### ■ System and Power Management

- Low-power modes
- Switching regulator
- Realtime Clock (RTC) with calendar and VBATT support
- Event Link Controller (ELC)
- DMA Controller (DMAC) × 8
- Data Transfer Controller (DTC)
- Key interrupt function (KINT)
- Power-on reset
- Low Voltage Detection (LVD) with voltage settings

### ■ Security and Encryption

- AES128/192/256
- 3DES/ARC4
- SHA1/SHA224/SHA256
- GHASH
- RSA/DSA
- True Random Number Generator (TRNG)

### ■ Human Machine Interface (HMI)

- Graphics LCD Controller (GLCDC)
- JPEG Codec
- 2D Drawing Engine (DRW)
- Capacitive Touch Sensing Unit (CTSU)
- Parallel Data Capture Unit (PDC)

### ■ Multiple Clock Sources

- Main clock oscillator (MOSC) (8 to 24 MHz)
- Sub-clock oscillator (SOSC) (32.768 kHz)
- High-speed on-chip oscillator (HOCO) (16/18/20 MHz)
- Middle-speed on-chip oscillator (MOCO) (8 MHz)
- Low-speed on-chip oscillator (LOCO) (32.768 kHz)
- Independent Watchdog Timer OCO (15 kHz)
- Clock trim function for HOCO/MOCO/LOCO
- Clock out support

### ■ General-Purpose I/O Ports

- Up to 172 input/output pins
  - Up to 9 CMOS input
  - Up to 163 CMOS input/output
  - Up to 22 5-V tolerant input/output
  - Up to 24 high current (20 mA)

### ■ Operating Voltage

- VCC: 2.7 to 3.6 V

### ■ Operating Temperature and Packages

- Ta = -40°C to +85°C
  - 224-pin BGA (13 mm × 13 mm, 0.8 mm pitch)
  - 176-pin BGA (13 mm × 13 mm, 0.8 mm pitch)
  - 145-pin LGA (7 mm × 7 mm, 0.5 mm pitch)
- Ta = -40°C to +105°C
  - 176-pin LQFP (24 mm × 24 mm, 0.5 mm pitch)
  - 144-pin LQFP (20 mm × 20 mm, 0.5 mm pitch)
  - 100-pin LQFP (14 mm × 14 mm, 0.5 mm pitch)

## 1. Overview

The S7G2 MCU integrates multiple series of software- and pin-compatible ARM®-based 32-bit MCUs that share the same set of Renesas peripherals to facilitate design scalability and efficient platform-based product development.

The MCU provides a high-performance ARM Cortex®-M4 core running up to 240 MHz with the following features:

- Up to 4-MB code flash memory
- 640-KB SRAM
- Graphics LCD Controller (GLCDC)
- 2D Drawing Engine (DRW)
- Capacitive Touch Sensing Unit (CTSU)
- Ethernet MAC Controller (ETHERC) with IEEE 1588 PTP, USBFS, USBHS, SD/MMC Host Interface
- Quad Serial Peripheral Interface (QSPI)
- Security and safety features
- Analog peripherals.

### 1.1 Function Outline

**Table 1.1 ARM core**

Feature	Functional description
ARM Cortex-M4	<ul style="list-style-type: none"> <li>• Maximum operating frequency: up to 240 MHz</li> <li>• ARM Cortex-M4 core:               <ul style="list-style-type: none"> <li>- Revision: r0p1-01rel0</li> <li>- ARMv7E-M architecture profile</li> <li>- Single precision floating point unit compliant with the ANSI/IEEE Std 754-2008</li> </ul> </li> <li>• ARM Memory Protection Unit (MPU):               <ul style="list-style-type: none"> <li>- ARMv7 Protected Memory System Architecture</li> <li>- 8 protect regions</li> </ul> </li> <li>• SysTick timer:               <ul style="list-style-type: none"> <li>- Driven by LOCO clock</li> </ul> </li> </ul>

**Table 1.2 Memory**

Feature	Functional description
Code flash memory	Maximum 4 MB of code flash memory. See section 54, Flash Memory in User's Manual.
Data flash memory	64 KB of data flash memory. See section 54, Flash Memory in User's Manual.
Memory Mirror Function (MMF)	The MMF can be configured to mirror the wanted application image load address in code flash memory to the application image link address in the 23-bit unused memory space (memory mirror space addresses). Your application code is developed and linked to run from this MMF destination address. The application code does not need to know the load location where it is stored in code flash memory. See section 5, Memory Mirror Function (MMF) in User's Manual.
SRAM	On-chip high-speed SRAM providing either parity-bit or double-bit error detection (DED). The first 32 KB of SRAM0 is subject to DED. Parity check is performed for other areas. See section 52, SRAM in User's Manual.
Standby SRAM	On-chip SRAM that can retain data in Deep Software Standby mode. See section 53, Standby SRAM in User's Manual.

**Table 1.3 System (1/2)**

Feature	Functional description
Operating modes	Two operating modes: <ul style="list-style-type: none"> <li>- Single-chip mode</li> <li>- SCI or USB boot mode.</li> </ul> See section 3, Operating Modes in User's Manual.

**Table 1.3 System (2/2)**

Feature	Functional description
Resets	<p>14 resets:</p> <ul style="list-style-type: none"> <li>• RES pin reset</li> <li>• Power-on reset</li> <li>• Voltage monitor reset 0</li> <li>• Voltage monitor reset 1</li> <li>• Voltage monitor reset 2</li> <li>• Independent Watchdog Timer reset</li> <li>• Watchdog Timer reset</li> <li>• Deep Software Standby reset</li> <li>• SRAM parity error reset</li> <li>• SRAM DED error reset</li> <li>• Bus master MPU error reset</li> <li>• Bus slave MPU error reset</li> <li>• Stack pointer error reset</li> <li>• Software reset.</li> </ul> <p>See section 6, Resets in User's Manual.</p>
Low Voltage Detection (LVD)	<p>The Low Voltage Detection (LVD) function monitors the voltage level input to the VCC pin, and the detection level can be selected in the software program. See section 8, Low Voltage Detection (LVD) in User's Manual.</p>
Clocks	<ul style="list-style-type: none"> <li>• Main clock oscillator (MOSC)</li> <li>• Sub-clock oscillator (SOSC)</li> <li>• High-speed on-chip oscillator (HOCO)</li> <li>• Middle-speed on-chip oscillator (MOCO)</li> <li>• Low-speed on-chip oscillator (LOCO)</li> <li>• PLL frequency synthesizer</li> <li>• Independent Watchdog Timer (WDT) on-chip oscillator</li> <li>• Clock out supports.</li> </ul> <p>See section 9, Clock Generation Circuit in User's Manual.</p>
Clock Frequency Accuracy Measurement Circuit (CAC)	<p>The CAC checks the system clock frequency with a reference clock signal by counting the number of pulses of the system clock to be measured. The reference clock can be provided externally through a CACREF pin or internally from various on-chip oscillators. Event signals can be generated when the clock does not match or measurement ends. This feature is particularly useful in implementing a fail-safe mechanism for home and industrial automation applications.</p> <p>See section 10, Clock Frequency Accuracy Measurement Circuit (CAC) in User's Manual.</p>
Low-power modes	<p>Power consumption can be reduced in multiple ways, including by setting clock dividers, controlling EBCLK output, controlling SDCLK output, stopping modules, selecting power control mode in normal operation, and transitioning to low-power modes. See section 11, Low-Power Modes in User's Manual.</p>
Battery backup function	<p>A battery backup function is provided for partial powering by a battery. The battery-powered area includes the RTC, SOSC, backup memory, and switch between VCC and VBATT. See section 12, Battery Backup Function in User's Manual.</p>
Register write protection	<p>The register write protection function protects important registers from being overwritten because of software errors. See section 13, Register Write Protection in User's Manual.</p>
Memory Protection Unit (MPU)	<p>Two MPUs and a CPU stack pointer monitor functions are provided for memory protection. See section 16, Memory Protection Unit (MPU) in User's Manual.</p>
Watchdog Timer (WDT)	<p>The WDT is a 14-bit down-counter. It can be used to reset the MCU when the counter underflows because the system has run out of control and is unable to refresh the WDT. In addition, a non-maskable interrupt or interrupt can be generated by an underflow. A refresh-permitted period can be set to refresh the counter and be used as the condition for detecting when the system runs out of control. See section 27, Watchdog Timer (WDT) in User's Manual.</p>
Independent Watchdog Timer (IWDT)	<p>The IWDT consists of a 14-bit down-counter that must be serviced periodically to prevent counter underflow. The IWDT provides functionality to reset the MCU or to generate a non-maskable interrupt or interrupt for a timer underflow. Because the timer operates with an independent, dedicated clock source, it is particularly useful in returning the MCU to a known state as a fail safe mechanism when the system runs out of control. The IWDT can be triggered automatically on a reset, underflow, or refresh error, or by a refresh of the count value in the registers. See section 28, Independent Watchdog Timer (IWDT) in User's Manual.</p>

**Table 1.4 Interrupt control**

Feature	Functional description
Interrupt Controller Unit (ICU)	The ICU controls which event signals are linked to the NVIC/DTC module and DMAC module. The ICU also controls NMI interrupts. See section 14, Interrupt Controller Unit (ICU) in User's Manual.

**Table 1.5 Event link**

Feature	Functional description
Event Link Controller (ELC)	The ELC uses the interrupt requests generated by various peripheral modules as event signals to connect them to different modules, enabling direct interaction between the modules without CPU intervention. See section 19, Event Link Controller (ELC) in User's Manual.

**Table 1.6 Direct memory access**

Feature	Functional description
Data Transfer Controller (DTC)	A DTC module is provided for transferring data when activated by an interrupt request. See section 18, Data Transfer Controller (DTC) in User's Manual.
DMA Controller (DMAC)	An 8-channel DMAC module is provided for transferring data without the CPU. When a DMA transfer request is generated, the DMAC transfers data stored at the transfer source address to the transfer destination address. See section 17, DMA Controller (DMAC) in User's Manual.

**Table 1.7 External bus interface**

Feature	Functional description
External buses	<ul style="list-style-type: none"> <li>• CS area (EXBIU): Connected to the external devices (external memory interface)</li> <li>• SDRAM area (EXBIU): Connected to the SDRAM (external memory interface)</li> <li>• QSPI area (EXBIUT2): Connected to the QSPI (external device interface).</li> </ul>

**Table 1.8 Timers**

Feature	Functional description
General PWM Timer (GPT)	The GPT is a 32-bit timer with 14 channels. PWM waveforms can be generated by controlling the up-counter, down-counter, or up- and down-counter. In addition, PWM waveforms can be generated for controlling brushless DC motors. The GPT can also be used as a general-purpose timer. See section 23, General PWM Timer (GPT) in User's Manual.
Port Output Enable for GPT (POEG)	Use the Port Output Enable (POEG) function to place the General PWM Timer (GPT) output pins in the output disable state.
Asynchronous General-Purpose Timer (AGT)	The AGT is a 16-bit timer that can be used for pulse output, external pulse width or period measurement, and counting of external events. This 16-bit timer consists of a reload register and a down-counter. The reload register and the down-counter are allocated to the same address, and can be accessed with the AGT register. See section 25, Asynchronous General-Purpose Timer (AGT) in User's Manual.
Realtime Clock (RTC)	The RTC has two counting modes, calendar count mode and binary count mode, that are controlled by the register settings. For calendar count mode, the RTC has a 100-year calendar from 2000 to 2099 and automatically adjusts dates for leap years. For binary count mode, the RTC counts seconds and retains the information as a serial value. Binary count mode can be used for calendars other than the Gregorian (Western) calendar. See section 26, Realtime Clock (RTC) in User's Manual.

**Table 1.9 Communication interfaces (1/2)**

Feature	Functional description
Serial Communications Interface (SCI)	<p>The SCI is configurable to five asynchronous and synchronous serial interfaces:</p> <ul style="list-style-type: none"> <li>• Asynchronous interfaces (UART and Asynchronous Communications Interface Adapter (ACIA))</li> <li>• 8-bit clock synchronous interface</li> <li>• Simple IIC (master-only)</li> <li>• Simple SPI</li> <li>• Smart card interface.</li> </ul> <p>The smart card interface complies with the ISO/IEC 7816-3 standard for electronic signals and transmission protocol.</p> <p>Each SCI has FIFO buffers to enable continuous and full-duplex communication, and the data transfer speed can be configured independently using an on-chip baud rate generator. See section 34, Serial Communications Interface (SCI) in User's Manual.</p>
IrDA Interface (IrDA)	<p>The IrDA interface sends and receives IrDA data communication waveforms in cooperation with the SCI1 based on the IrDA (Infrared Data Association) standard 1.0. See section 35, IrDA Interface in User's Manual.</p>
I <sup>2</sup> C Bus Interface (IIC)	<p>The three-channel IIC conforms with and provides a subset of the NXP I<sup>2</sup>C bus (Inter-Integrated Circuit bus) interface functions. See section 36, I<sup>2</sup>C Bus Interface (IIC) in User's Manual.</p>
Serial Peripheral Interface (SPI)	<p>Two independent SPI channels are capable of high-speed, full-duplex synchronous serial communications with multiple processors and peripheral devices. See section 38, Serial Peripheral Interface (SPI) in User's Manual.</p>
Serial Sound Interface (SSI)	<p>The SSI peripheral provides functionality to interface with digital audio devices for transmitting PCM audio data over a serial bus with the MCU. The SSI supports an audio clock frequency of up to 50 MHz, and can be operated as a slave or master receiver, transmitter, or transceiver to suit various applications. The SSI includes 8-stage FIFO buffers in the receiver and transmitter, and supports interrupts and DMA-driven data reception and transmission. See section 41, Serial Sound Interface (SSI) in User's Manual.</p>
Quad Serial Peripheral Interface (QSPI)	<p>The QSPI is a memory controller for connecting a serial ROM (nonvolatile memory such as a serial flash memory, serial EEPROM, or serial FeRAM) that has an SPI-compatible interface. See section 39, Quad Serial Peripheral Interface (QSPI) in User's Manual.</p>
Controller Area Network (CAN) Module	<p>The CAN module provides functionality to receive and transmit data using a message-based protocol between multiple slaves and masters in electromagnetically-noisy applications. The CAN module complies with the ISO 11898-1 (CAN 2.0A/CAN 2.0B) standard and supports up to 32 mailboxes, which can be configured for transmission or reception in normal mailbox and FIFO modes. Both standard (11-bit) and extended (29-bit) messaging formats are supported. See section 37, Controller Area Network (CAN) Module in User's Manual.</p>
USB 2.0 Full-Speed Module (USBFS)	<p>Full-Speed USB controller that can operate as a host controller or device controller. The module supports full-speed and low-speed (host controller only) transfer as defined in Universal Serial Bus Specification 2.0. The module has an internal USB transceiver and supports all of the transfer types defined in Universal Serial Bus Specification 2.0. The USB has buffer memory for data transfer, providing a maximum of 10 pipes. Pipes 1 to 9 can be assigned any endpoint number based on the peripheral devices used for communication or based on your system. See section 32, USB 2.0 Full-Speed Module (USBFS) in User's Manual.</p>
USB 2.0 High-Speed Module (USBHS)	<p>High-Speed USB controller that can operate as a host controller or a device controller. As a host controller, the USBHS supports high-speed transfer, full-speed transfer, and low-speed transfer as defined in Universal Serial Bus Specification 2.0. As a device controller, the USBHS supports high-speed transfer and full-speed transfer as defined in Universal Serial Bus Specification 2.0. The USBHS has an internal USB transceiver and supports all of the transfer types defined in Universal Serial Bus Specification 2.0. The USBHS has FIFO buffers for data transfer, providing a maximum of 10 pipes. Any endpoint number can be assigned to pipes 1 to 9, based on the peripheral devices or your system for communication. See section 33, USB 2.0 High-Speed Module (USBHS) in User's Manual.</p>

**Table 1.9 Communication interfaces (2/2)**

Feature	Functional description
Ethernet MAC with IEEE 1588 PTP (ETHERC)	<p>Two-channel Ethernet MAC Controller (ETHERC) compliant with the Ethernet/IEEE802.3 Media Access Control (MAC) layer protocol. Each ETHERC channel provides one channel of the MAC layer interface, connecting the MCU to the physical layer LSI (PHY-LSI) that allows transmission and reception of frames compliant with the Ethernet and IEEE802.3 standards. The ETHERC is connected to the Ethernet DMA Controller (EDMAC) so data can be transferred without using the CPU.</p> <p>To handle timing and synchronization between devices, an on-chip Precision Time Protocol (PTP) module for the Ethernet PTP Controller (EPTPC) applies the PTP defined in the IEEE 1588-2008 version 2.0 standard.</p> <p>The EPTPC is composed of:</p> <ul style="list-style-type: none"> <li>• Synchronization Frame Processing units (SYNFP0 and SYNFP1)</li> <li>• A Packet Relation Controller unit (PRC-TC)</li> <li>• A Statistical Time Correction Algorithm unit (STCA).</li> </ul> <p>Use the EPTPC in combination with the on-chip Ethernet MAC Controller (ETHERC) and the DMA Controller for the PTP Ethernet Controller (PTPEDMAC). See section 29, Ethernet MAC Controller (ETHERC) in User's Manual.</p>
SD/MMC Host Interface (SDHI)	<p>The SDHI and MultiMediaCard (MMC) interface provide the functionality required to connect a variety of external memory cards to the MCU. The SDHI supports both 1- and 4-bit buses for connecting memory cards that support SD, SDHC, and SDXC formats. When developing host devices that are compliant with the SD Specifications, you must comply with the SD Host/Ancillary Product License Agreement (SD HALA).</p> <p>The MMC interface supports 1-, 4-, and 8-bit MMC buses that provide eMMC 4.51 (JEDEC Standard JESD 84-B451) device access. This interface also provides backward compatibility and supports high-speed SDR transfer modes. See section 43, SD/MMC Host Interface (SDHI) in User's Manual.</p>

**Table 1.10 Analog**

Feature	Functional description
12-Bit A/D Converter (ADC12)	<p>Up to two successive approximation 12-Bit A/D Converters are provided. In unit 0, up to 13 analog input channels are selectable. In unit 1, up to 12 analog input channels, the temperature sensor output, and an internal reference voltage are selectable for conversion. The A/D conversion accuracy is selectable from 12-, 10-, and 8-bit conversion, making it possible to optimize the tradeoff between speed and resolution in generating a digital value. See section 46, 12-Bit A/D Converter (ADC12) in User's Manual.</p>
12-Bit D/A Converter (DAC12)	<p>The DAC12 D/A converts data and includes an output amplifier. See section 47, 12-Bit D/A Converter (DAC12) in User's Manual.</p>
Temperature sensor (TSN)	<p>The on-chip temperature sensor can determine and monitor the die temperature for reliable operation of the device. The sensor outputs a voltage directly proportional to the die temperature, and the relationship between the die temperature and the output voltage is linear. The output voltage is provided to the ADC12 for conversion and can also be used by the end application. See section 48, Temperature Sensor (TSN) in User's Manual.</p>
High-Speed Analog Comparator (ACMPHS)	<p>Analog comparators can be used to compare a test voltage with a reference voltage and to provide a digital output based on the conversion result.</p> <p>Both the test and reference voltages can be provided to the comparator from internal sources such as the DAC12 output and internal reference voltage, and an external source with or without an internal PGA.</p> <p>Such flexibility is useful in applications that require go/no-go comparisons to be performed between analog signals without necessarily requiring A/D conversion. See section 49, High-Speed Analog Comparator (ACMPHS) in User's Manual.</p>

**Table 1.11 Human machine interfaces (1/2)**

Feature	Functional description
Key interrupt function (KINT)	<p>A key interrupt can be generated by setting the Key Return Mode register (KRM) and inputting a rising or falling edge to the key interrupt input pins. See section 21, Key Interrupt Function (KINT) in User's Manual.</p>

**Table 1.11 Human machine interfaces (2/2)**

Feature	Functional description
Capacitive Touch Sensing Unit (CTSUS)	The CTSUS measures the electrostatic capacitance of the touch sensor. Changes in the electrostatic capacitance are determined by the software, which enables the CTSUS to detect whether a finger is in contact with the touch sensor. The electrode surface of the touch sensor is usually enclosed with an electrical conductor so that fingers do not come into direct contact with the electrodes. See section 50, Capacitive Touch Sensing Unit (CTSUS) in User's Manual.

**Table 1.12 Graphics**

Feature	Functional description
Graphics LCD Controller (GLCDC)	The GLCDC provides multiple functions and supports various data formats and panels. Key GLCDC features include: <ul style="list-style-type: none"> <li>• GPX bus master function for accessing graphics data</li> <li>• Superimposition of three planes (single color background plane, graphic 1 plane, and graphic 2 plane)</li> <li>• Support for many types of 32- or 16-bit per pixel graphics data and 8-, 4-, or 1-bit LUT data format</li> <li>• Digital interface signal output supporting a video image size of WVGA or greater.</li> </ul> See section 57, Graphics LCD Controller (GLCDC) in User's Manual.
2D Drawing Engine (DRW)	The 2D Drawing Engine (DRW) provides flexible functions that can support almost any object geometry rather than being bound to only a few specific geometries such as lines, triangles, or circles. The edges of every object can be independently blurred or antialiased. Rasterization is executed at one pixel per clock on the bounding box of the object from left to right and top to bottom. The DRW can also raster from bottom to top to optimize the performance in certain cases. In addition, optimization methods are available to avoid rasterization of many empty pixels of the bounding box. The distances to the edges of the object are calculated by a set of edge equations for every pixel of the bounding box. These edge equations can be combined to describe the entire object. If a pixel is inside the object, it is selected for rendering. If it is outside it is discarded. If it is on the edge, an alpha value can be chosen proportional to the distance of the pixel to the nearest edge for antialiasing. Every pixel that is selected for rendering can be textured. The resulting aRGB quadruple can be modified by a general raster operation approach independently for each of the four channels. The aRGB quadruples can then be blended with one of the multiple blend modes of the DRW. The DRW provides two inputs (texture read and framebuffer read), and one output (framebuffer write). The internal color format is always aRGB (8888). The color formats from the inputs are converted to the internal format on read and a conversion back is made on write. See section 55, 2D Drawing Engine (DRW) in User's Manual.
JPEG Codec (JPEG)	The JPEG Codec (JPEG) incorporates a JPEG codec that conforms to the JPEG baseline compression and decompression standard. This provides high-speed compression of image data and high-speed decoding of JPEG data. See section 56, JPEG Codec in User's Manual.
Parallel Data Capture Unit (PDC)	One PDC unit is provided for communicating with external I/O devices, including image sensors, and transferring parallel data such as an image output from the external I/O device through the DTC or DMAC to the on-chip SRAM and external address spaces (the CS and SDRAM areas). See section 44, Parallel Data Capture Unit (PDC) in User's Manual.

**Table 1.13 Data processing (1/2)**

Feature	Functional description
Cyclic Redundancy Check (CRC) calculator	The CRC calculator generates CRC codes to detect errors in the data. The bit order of CRC calculation results can be switched for LSB-first or MSB-first communication. Additionally, various CRC-generating polynomials are available. The snoop function allows monitoring reads from and writes to specific addresses. This function is useful in applications that require CRC code to be generated automatically in certain events, such as monitoring writes to the serial transmit buffer and reads from the serial receive buffer. See section 40, Cyclic Redundancy Check (CRC) Calculator in User's Manual.
Data Operation Circuit (DOC)	The DOC compares, adds, and subtracts 16-bit data. See section 51, Data Operation Circuit (DOC) in User's Manual.

**Table 1.13 Data processing (2/2)**

Feature	Functional description
Sampling Rate Converter (SRC)	<p>The SRC converts the sampling rate of data produced by various audio decoders, such as the WMA, MP3, and AAC. Both 16-bit stereo and monaural data are supported. The sampling rate of the input signal can be one of the following:</p> <ul style="list-style-type: none"> <li>• 8 kHz</li> <li>• 11.025 kHz</li> <li>• 12 kHz</li> <li>• 16 kHz</li> <li>• 22.05 kHz</li> <li>• 24 kHz</li> <li>• 32 kHz</li> <li>• 44.1 kHz</li> <li>• 48 kHz.</li> </ul> <p>The sampling rate of the output signal can be one of the following:</p> <ul style="list-style-type: none"> <li>• 8 kHz</li> <li>• 16 kHz</li> <li>• 32 kHz</li> <li>• 44.1 kHz</li> <li>• 48 kHz.</li> </ul> <p>Independent FIFOs are provided for input and output. In a typical application, a DMA controller can be used to transfer PCM audio data from SRAM, for example, to the SRC. Sample-converted audio data from the SRC can then be transferred using the DMA Controller to the SSI, from where it can be transmitted to an external audio codec. See section 42, Sampling Rate Converter (SRC) in User's Manual.</p>

**Table 1.14 Security**

Feature	Functional description
Secure Crypto Engine 7 (SCE7)	<ul style="list-style-type: none"> <li>• Security algorithms: <ul style="list-style-type: none"> <li>- Symmetric algorithms: AES, 3DES, and ARC4</li> <li>- Asymmetric algorithms: RSA, DSA, and DLP.</li> </ul> </li> <li>• Other support features: <ul style="list-style-type: none"> <li>- TRNG (True Random Number Generator)</li> <li>- Hash-value generation: SHA1, SHA224, SHA256, GHASH</li> <li>- 128-bit unique ID.</li> </ul> </li> </ul>



## 1.2 Block Diagram

Figure 1.1 shows the block diagram of the MCU superset. Some individual devices within the group have a subset of the features.

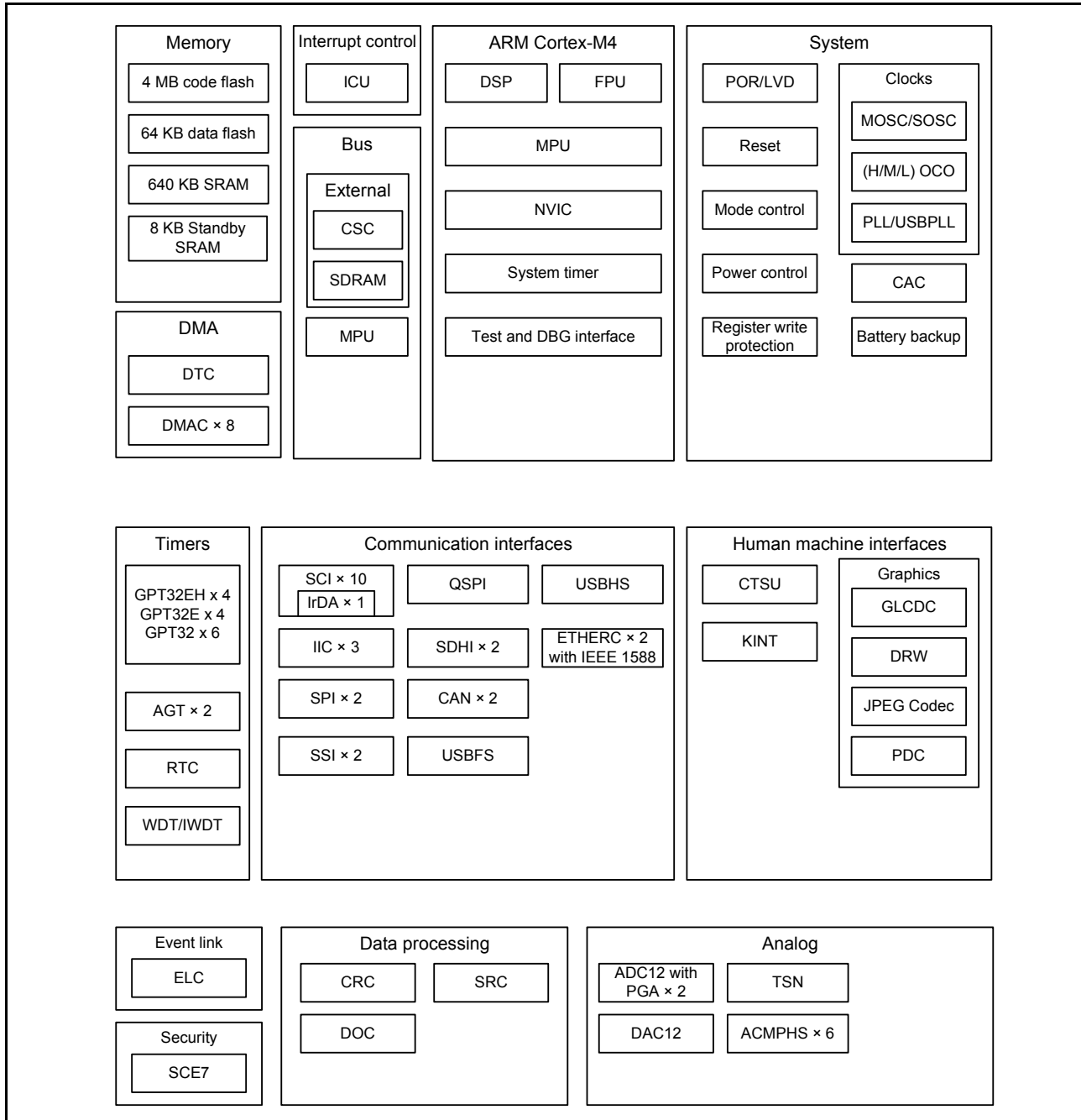


Figure 1.1 Block diagram

## 1.3 Part Numbering

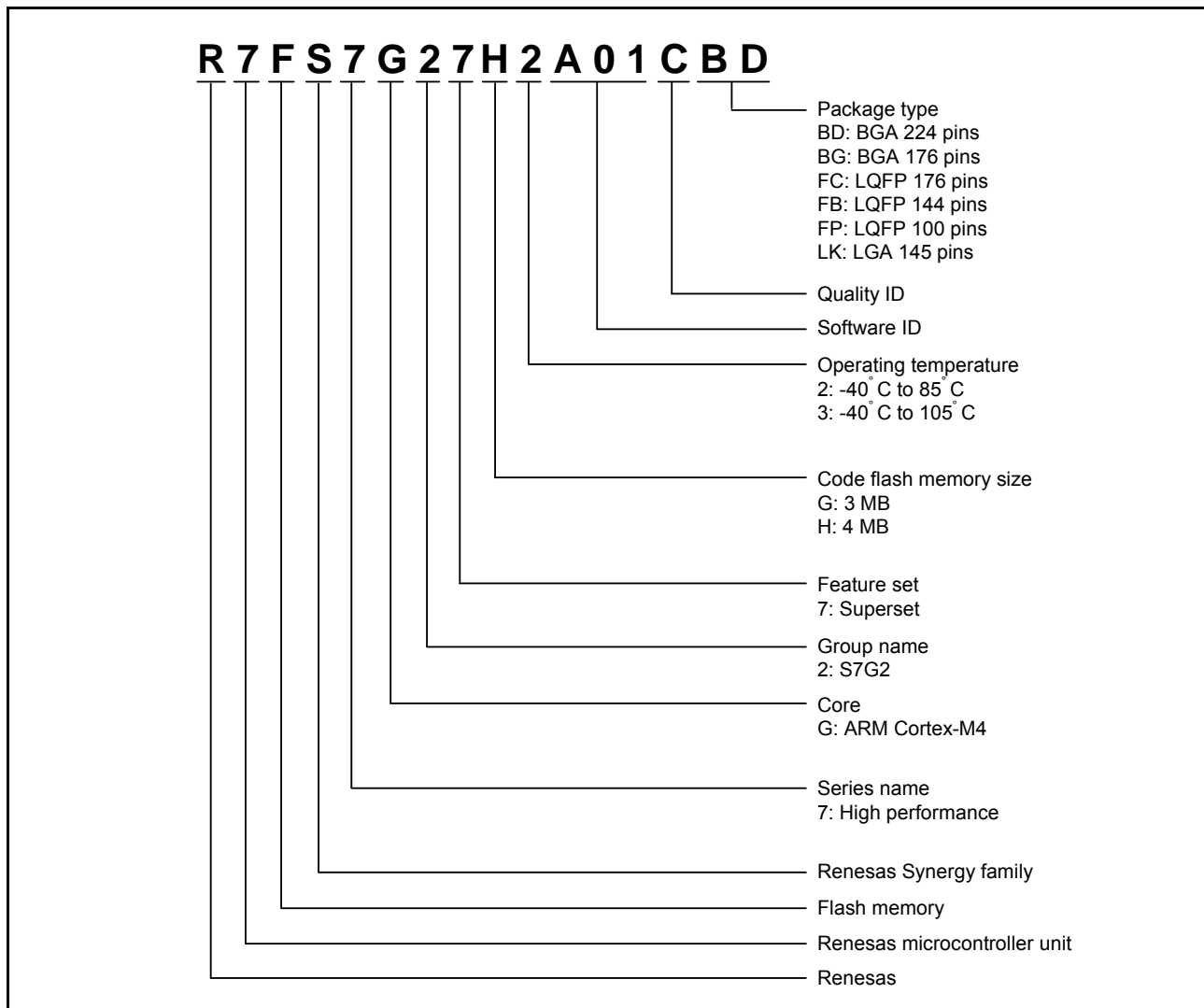


Figure 1.2 Part numbering scheme

## 1.4 Function Comparison

Table 1.15 Functional comparison

Function	Part numbers							
	R7FS7G27H2A01CBD/ R7FS7G27G2A01CBD	R7FS7G27H2A01CBG/ R7FS7G27G2A01CBG	R7FS7G27H3A01CFC/ R7FS7G27G3A01CFC	R7FS7G27H2A01CLK/ R7FS7G27G2A01CLK	R7FS7G27H3A01CFB/ R7FS7G27G3A01CFB	R7FS7G27G3A01CFP		
Pin count	224	176	176	145	144	100		
Package	BGA	BGA	LQFP	LGA	LQFP	LQFP		
Code flash memory	4/3 MB					3 MB		
Data flash memory	64 KB							
SRAM	640 KB							
	Parity						608 KB	
	DED						32 KB	
Standby SRAM	8 KB							
System	CPU clock	240 MHz						
	Backup registers	512 bytes						
Interrupt control	ICU	Yes						
Event link	ELC	Yes						
DMA	DTC	Yes						
	DMAC	8						
BUS	External bus	16-bit bus				8-bit bus		
	SDRAM	Yes					No	
Timers	GPT32EH	4	4	4	4	4	4	
	GPT32E	4	4	4	4	4	3	
	GPT32	6	6	6	6	6	5	
	AGT	2	2	2	2	2	2	
	RTC	Yes						
	WDT/IWDT	Yes						
Communication	SCI	10						
	IIC	3					2	
	SPI	2						
	SSI	2					1	
	QSPI	1					Dual-SPI 1	
	SDHI	2						
	CAN	2						
	USBFS	Yes						
	USBHS	Yes			No			
	ETHERC	2	RMII 2	RMII 2	RMII 2/MII 1		RMII 1	
Analog	ADC12	25	21	21	19	19	16	
	DAC12	2						
	ACMPHS	6						
	TSN	Yes						
HMI	CTSUS	18	12	12	18		12	
	KINT	8						
	Graphics	GLCDC	RGB888				RGB565	
		DRW	Yes					
		JPEG	Yes					
		PDC	Yes				No	
Data processing	CRC	Yes						
	DOC	Yes						
	SRC	Yes						
Security		SCE7						

## 1.5 Pin Functions

**Table 1.16 Pin functions (1/5)**

Function	Signal	I/O	Description
Power supply	VCC	Input	Power supply pin. Connect to the system power supply. Connect this pin to VSS through a 0.1- $\mu$ F capacitor. Place the capacitor close to the pin.
	VCC_DCDC	Input	Switching regulator power supply pin.
	VLO	I/O	Switching regulator pin.
	VCL0 to VCL2	Input	Connect this pin to VSS through the smoothing capacitor used to stabilize the internal power supply. Place the capacitor close to the pin.
	VCL_F	Input	
	VSS	Input	Ground pin. Connect to the system power supply (0 V).
	VBATT	Input	Backup power pin.
Clock	XTAL	Output	Pins for a crystal resonator. An external clock signal can be input through the EXTAL pin.
	EXTAL	Input	
	XCIN	Input	Input/output pins for the sub-clock oscillator. Connect a crystal resonator between XCOOUT and XCIN.
	XCOOUT	Output	
	EBCLK	Output	Outputs the external bus clock for external devices.
	SDCLK	Output	Outputs the SDRAM-dedicated clock.
	CLKOUT	Output	Clock output pin.
Operating mode control	MD	Input	Pins for setting the operating mode. The signal levels on these pins must not be changed during operation mode transition on release from the reset state.
System control	RES	Input	Reset signal input pin. The MCU enters the reset state when this signal goes low.
CAC	CACREF	Input	Measurement reference clock input pin.
On-chip emulator	TMS	I/O	On-chip emulator or boundary scan pins.
	TDI	Input	
	TCK	Input	
	TDO	Output	
	TCLK	Output	This pin outputs the clock for synchronization with the trace data.
	TDATA0 to TDATA3	Output	These pins indicate that output from the TDATA0 to TDATA3 pins is valid.
	SWDIO	I/O	Serial wire debug data input/output pin.
	SWCLK	Input	Serial wire clock pin.
	SWO	Output	Serial wire trace output pin.
External bus interface	RD	Output	Strobe signal indicating that reading from the external bus interface space is in progress, active LOW.
	WR	Output	Strobe signal indicating that writing to the external bus interface space is in progress, in 1-write strobe mode, active LOW.
	WR0, WR1	Output	Strobe signals indicating that either group of data bus pins (D07 to D00 or D15 to D08) is valid in writing to the external bus interface space, in byte strobe mode, active LOW.
	BC0, BC1	Output	Strobe signals indicating that either group of data bus pins (D07 to D00 or D15 to D08) is valid in access to the external bus interface space, in 1-write strobe mode, active LOW.
	WAIT	Input	Input pin for wait request signals in access to the external space, active LOW.
	CS0 to CS7	Output	Select signals for CS areas, active LOW.
	A00 to A23	Output	Address bus.
	D00 to D15	I/O	Data bus.

**Table 1.16 Pin functions (2/5)**

Function	Signal	I/O	Description
SDRAM interface	CKE	Output	SDRAM clock enable signal.
	SDCS	Output	SDRAM chip select signal, active LOW.
	RAS	Output	SDRAM low address strobe signal, active LOW.
	CAS	Output	SDRAM column address strobe signal, active LOW.
	WE	Output	SDRAM write enable signal, active LOW.
	DQM0	Output	SDRAM I/O data mask enable signal for DQ07 to DQ00.
	DQM1	Output	SDRAM I/O data mask enable signal for DQ15 to DQ08.
	A00 to A15	Output	Address bus.
DQ00 to DQ15	I/O	Data bus.	
Interrupt	NMI	Input	Non-maskable interrupt request pin.
	IRQ0 to IRQ15	Input	Maskable interrupt request pins.
GPT	GTETRGA, GTETRGB, GTETRGC, GTETRGD	Input	External trigger input pins.
	GTIOC0A to GTIOC13A, GTIOC0B to GTIOC13B	I/O	Input capture, output compare, or PWM output pins.
	GTIU	Input	Hall sensor input pin U.
	GTIV	Input	Hall sensor input pin V.
	GTIW	Input	Hall sensor input pin W.
	GTOUUP	Output	Three-phase PWM output for BLDC motor control (positive U phase).
	GTOULO	Output	Three-phase PWM output for BLDC motor control (negative U phase).
	GTOVUP	Output	Three-phase PWM output for BLDC motor control (positive V phase).
	GTOVLO	Output	Three-phase PWM output for BLDC motor control (negative V phase).
	GTOVUP	Output	Three-phase PWM output for BLDC motor control (positive W phase).
	GTOVLO	Output	Three-phase PWM output for BLDC motor control (negative W phase).
AGT	AGTEE0, AGTEE1	Input	External event input enable signals.
	AGTIO0, AGTIO1	I/O	External event input and pulse output pins.
	AGTO0, AGTO1	Output	Pulse output pins.
	AGTOA0, AGTOA1	Output	Output compare match A output pins.
	AGTOB0, AGTOB1	Output	Output compare match B output pins.
RTC	RTCCOUT	Output	Output pin for 1-Hz or 64-Hz clock.
	RTCIC0 to RTCIC2	Input	Time capture event input pins.
SCI	SCK0 to SCK9	I/O	Input/output pins for the clock (clock synchronous mode).
	RXD0 to RXD9	Input	Input pins for received data (asynchronous mode/clock synchronous mode).
	TXD0 to TXD9	Output	Output pins for transmitted data (asynchronous mode/clock synchronous mode).
	CTS0_RTS0 to CTS9_RTS9	I/O	Input/output pins for controlling the start of transmission and reception (asynchronous mode/clock synchronous mode), active LOW.
	SCL0 to SCL9	I/O	Input/output pins for the IIC clock (simple IIC).
	SDA0 to SDA9	I/O	Input/output pins for the IIC data (simple IIC).
	SCK0 to SCK9	I/O	Input/output pins for the clock (simple SPI).
	MISO0 to MISO9	I/O	Input/output pins for slave transmission of data (simple SPI).
	MOSI0 to MOSI9	I/O	Input/output pins for master transmission of data (simple SPI).
SS0 to SS9	Input	Chip-select input pins (simple SPI), active LOW.	
IIC	SCL0 to SCL2	I/O	Input/output pins for the clock.
	SDA0 to SDA2	I/O	Input/output pins for data.

**Table 1.16 Pin functions (3/5)**

Function	Signal	I/O	Description
SSI	SSISCK0	I/O	SSI serial bit clock pin.
	SSISCK1		
	SSIWS0	I/O	Word select pins.
	SSIWS1		
	SSITXD0	Output	Serial data output pins.
	SSIRXD0	Input	Serial data input pins.
	SSIDATA1	I/O	Serial data input/output pins.
	AUDIO_CLK	Input	External clock pin for audio (input oversampling clock).
SPI	RSPCKA, RSPCKB	I/O	Clock input/output pin.
	MOSIA, MOSIB	I/O	Input or output pins for data output from the master.
	MISOA, MISOB	I/O	Input or output pins for data output from the slave.
	SSLA0, SSLB0	I/O	Input or output pin for slave selection.
	SSLA1 to SSILA3, SSLB1 to SSLB3	Output	Output pin for slave selection.
QSPI	QSPCLK	Output	QSPI clock output pin.
	QSSL	Output	QSPI slave output pin.
	QIO0 to QIO3	I/O	Data0 to Data3.
CAN	CRX0, CRX1	Input	Receive data.
	CTX0, CTX1	Output	Transmit data.
USBFS	VCC_USB	Input	Power supply pins.
	VSS_USB	Input	Ground pins.
	USB_DP	I/O	D+ I/O pin of the USB on-chip transceiver. Connect this pin to the D+ pin of the USB bus.
	USB_DM	I/O	D- I/O pin of the USB on-chip transceiver. Connect this pin to the D- pin of the USB bus.
	USB_VBUS	Input	USB cable connection monitor pin. Connect this pin to VBUS of the USB bus. The VBUS pin status (connected or disconnected) can be detected when the USB module is operating as a function controller.
	USB_EXICEN	Output	Low-power control signal for external power supply (OTG) chip.
	USB_VBUSEN	Output	VBUS (5 V) supply enable signal for external power supply chip.
	USB_OVRCURA, USB_OVRCURB	Input	Connect the external overcurrent detection signals to these pins. Connect the VBUS comparator signals to these pins when the OTG power supply chip is connected.
USBHS	USB_ID	Input	Connect the MicroAB connector ID input signal to this pin during operation in OTG mode.
	VCC_USBHS	Input	Power supply pin.
	VSS1_USBHS	Input	Ground pin.
	VSS2_USBHS	Input	Ground pin.
	AVCC_USBHS	Input	Analog power supply pin for the USBHS.
	AVSS_USBHS	Input	Analog ground pin for the USBHS. Must be shorted to the PVSS_USBHS pin.
	PVSS_USBHS	Input	PLL circuit ground pin for the USBHS. Must be shorted to the AVSS_USBHS pin.
	USBHS_RREF	I/O	USBHS reference current source pin. Connect this pin to the AVSS_USBHS pin through a 2.2-kΩ resistor ( $\pm 1\%$ ).
	USBHS_DP	I/O	USB bus D+ data pin.
	USBHS_DM	I/O	USB bus D- data pin.
	USBHS_EXICEN	Output	Connect this pin to the OTG power supply IC.
	USBHS_ID	Input	Connect this pin to the OTG power supply IC.
	USBHS_VBUSEN	Output	VBUS power enable signal for USB.
	USBHS_OVRCURA, USBHS_OVRCURB	Input	Overcurrent pin for USB.
USBHS_VBUS	Input	USB cable connection monitor input pin.	

**Table 1.16 Pin functions (4/5)**

Function	Signal	I/O	Description
ETHERC	REF50CK0, REF50CK1	Input	50-MHz reference clocks. These pins input reference signals for transmission/reception timing in RMII mode.
	RMII0_CRS_DV, RMII1_CRS_DV	Input	Indicate carrier detection signals and valid receive data on RMII_RXD1 and RMII_RXD0 in RMII mode.
	RMII0_TXD0, RMII0_TXD1, RMII1_TXD0, RMII1_TXD1	Output	2-bit transmit data in RMII mode.
	RMII0_RXD0, RMII0_RXD1, RMII1_RXD0, RMII1_RXD1	Input	2-bit receive data in RMII mode.
	RMII0_TXD_EN, RMII1_TXD_EN	Output	Output pins for data transmit enable signals in RMII mode.
	RMII0_RX_ER, RMII1_RX_ER	Input	Indicate an error occurred during reception of data in RMII mode.
	ET0_CRS, ET1_CRS	Input	Carrier detection/data reception enable signals.
	ET0_RX_DV, ET1_RX_DV	Input	Indicate valid receive data on ET_ERXD3 to ET_ERXD0.
	ET0_EXOUT, ET1_EXOUT	Input	General-purpose external output pins.
	ET0_LINKSTA, ET1_LINKSTA	Output	Input link status from the PHY-LSI.
	ET0_ETXD0 to ET0_ETXD3, ET1_ETXD0 to ET1_ETXD3	output	4 bits of MII transmit data.
	ET0_ERXD0 to ET0_ERXD3, ET1_ERXD0 to ET1_ERXD3	Input	4 bits of MII receive data.
	ET0_TX_EN, ET1_TX_EN	Output	Transmit enable signals. Function as signals indicating that transmit data is ready on ET_ETXD3 to ET_ETXD0.
	ET0_TX_ER, ET1_TX_ER	Output	Transmit error pins. Function as signals notifying the PHY_LSI of an error during transmission.
	ET0_RX_ER, ET1_RX_ER	Input	Receive error pins. Function as signals to recognize an error during reception.
	ET0_TX_CLK, ET1_TX_CLK	Input	Transmit clock pins. These pins input reference signals for output timing from ET_TX_EN, ET_ETXD3 to ET_ETXD0, and ET_TX_ER.
	ET0_RX_CLK, ET1_RX_CLK	Input	Receive clock pins. These pins input reference signals for input timing to ET_RX_DV, ET_ERXD3 to ET_ERXD0, and ET_RX_ER.
	ET0_COL, ET1_COL	Input	Input collision detection signals.
	ET0_WOL, ET1_WOL	Output	Receive Magic packets.
	ET0_MDC, ET1_MDC	Output	Output reference clock signals for information transfer through ET_MDIO.
ET0_MDIO, ET1_MDIO	I/O	Input or output bidirectional signals for exchange of management data with PHY-LSI.	
SDHI	SD0CLK, SD1CLK	Output	SD clock output pin.
	SD0CMD, SD1CMD	I/O	Command output pin and response input signal pin.
	SD0DAT0 to SD0DAT7, SD1DAT0 to SD1DAT7	I/O	SD and MMC data bus pins.
	SD0CD, SD1CD	Input	SD card detection pin.
	SD0WP, SD1WP	Input	SD write-protect signal.

**Table 1.16 Pin functions (5/5)**

Function	Signal	I/O	Description
Analog power supply	AVCC0	Input	Analog voltage supply pin for the analog. Connect this pin to VCC.
	AVSS0	Input	Analog ground pin. Connect this pin to VSS.
	VREFH0	Input	Analog reference voltage supply pin for the ADC12. Connect this pin to VCC when not using the ADC12.
	VREFL0	Input	Analog reference ground pin for the ADC12. Connect this pin to VSS when not using the ADC12.
	VREFH	Input	Reference voltage input pin for the ADC12 (unit 1) and D/A converter. This is used as the analog power supply for the respective modules. Connect this pin to VCC if the ADC12 (unit 1) or DAC12 is not in use.
	VREFL	Input	Reference ground pin for the ADC12 and D/A converter. This is used as the analog ground for the respective modules. Set this pin to the same potential as the VSS pin.
ADC12	AN000 to AN006, AN016 to AN021	Input	Input pins for the analog signals to be processed by the ADC12.
	AN100 to AN106, AN116 to AN120	Input	
	ADTRG0	Input	Input pins for the external trigger signals that start the A/D conversion, active LOW.
	ADTRG1	Input	
	PGAVSS000/PGAVS S100	Input	Differential input pins.
DAC12	DA0, DA1	Output	Output pins for the analog signals to be processed by the D/A converter.
ACMPHS	VCOU	Output	Comparator output pin.
	IVREF0 to IVREF3	Input	Reference voltage input pin for comparator.
	IVCMP0 to IVCMP2	Input	Analog voltage input pins for comparator.
CTSU	TS00 to TS17	Input	Capacitive touch detection pins (touch pins).
	TSCAP	–	Secondary power supply pin for the touch driver.
KINT	KR00 to KR07	Input	A key interrupt (KINT) can be generated by inputting a falling edge to the key interrupt input pins.
I/O ports	P000 to P007	Input	General-purpose input pin.
	P008 to P011, P014, P015	I/O	General-purpose input/output pins.
	P100 to P115	I/O	General-purpose input/output pins.
	P200	Input	General-purpose input pin.
	P201 to P207, P212, P213	I/O	General-purpose input/output pins.
	P300 to P315	I/O	General-purpose input/output pins.
	P400 to P415	I/O	General-purpose input/output pins.
	P500 to P515	I/O	General-purpose input/output pins.
	P600 to P615	I/O	General-purpose input/output pins.
	P700 to P713	I/O	General-purpose input/output pins.
	P800 to P813	I/O	General-purpose input/output pins.
	P900 to P915	I/O	General-purpose input/output pins.
	PA00 to PA15	I/O	General-purpose input/output pins.
	PB00 to PB07	I/O	General-purpose input/output pins.
GLCDC	LCD_DATA00 to LCD_DATA23	Output	Data output pin for panel.
	LCD_TCON0 to LCD_TCON3	Output	Output pins for panel timing adjustment.
	LCD_CLK	Output	Panel clock output pin.
	LCD_EXTCLK	Input	Panel clock source input pin.
PDC	PIXCLK	Input	Image transfer clock pin.
	VSYNC	Input	Vertical synchronization signal pin.
	HSYNC	Input	Horizontal synchronization signal pin.
	PIXD0 to PIXD7	Input	8-bit image data pins.
	PCKO	Output	Output pin for dot clock.



### 1.6 Pin Assignments

Figure 1.3 to Figure 1.8 show the pin assignments.

R7FS7G2xxxA01CBD																
	A	B	C	D	E	F	G	H	J	K	L	M	N	P	R	
15	P407	P408	P410	P708	VSS	USBHS_DM	PVSS_USBHS	P212/EXTAL	XCIN	VCL0	P707	P701	P403	P401	P511	15
14	USB_DP	USB_DM	P409	P411	P415	USBHS_DP	AVSS_USBHS	P213/XTAL	XCOUT	VBATT	P706	P700	P402	P514	P512	14
13	VCC_USB	VSS_USB	P207	P412	P709	VCC_USBHS	USBHS_RREF	AVCC_USBHS	VSS	PB01	P705	P405	P400	P513	P805	13
12	P202	P203	P205	P413	P711	VSS1_USBHS	VSS2_USBHS	VCC	PB05	PB03	VCC	P806	P002	P807	P000	12
11	P902	P901	P315	P204	P414	P712	PB07	PB06	PB02	P702	VSS	P004	P008	P001	P005	11
10	VCL1	VSS	VSS	VCC	P313	P710	P713	PB04	P704	P404	P003	P010	P011	P006	P009	10
9	VLO	VLO	P904	P903	P900	P314	P206	PB00	P406	P515	P007	P014	AVSS0	VREFL0	VREFH0	9
8	VCC_DCDC	P200	P201/MD	P910	P909	RES	P615	P913	P703	P809	VSS	P015	VREFL	AVCC0	VREFH	8
7	P911	P912	P311	P308	P908	P907	PA08	PA13	PA00	P808	VCC	P508	P510	VCC	VSS	7
6	P905	P312	P310	P307	P915	P906	PA11	PA02	PA01	P606	P812	P506	P507	P509	VCL2	6
5	VSS	VCC	P309	P306	P914	P300/TCK/SWCLK	PA12	PA10	PA03	P607	P811	P505	P502	P503	P504	5
4	VSS	VCC	P304	P305	P114	P608	P609	PA09	PA04	P107	P106	P804	P501	P803	P500	4
3	P303	P301	P112	P113	P115	P613	PA14	VCC	PA05	P603	P600	P105	P104	P810	P802	3
2	P302	P108/TMS/SWDIO	P110/TDI	VSS	P611	P612	PA15	VSS	PA06	P604	P601	VCC	P103	P800	P801	2
1	NC	P109/TDO	P111	VCC	P610	P614	P813	VCL_F	PA07	P605	P602	VSS	P102	P101	P100	1
	A	B	C	D	E	F	G	H	J	K	L	M	N	P	R	

Figure 1.3 Pin assignment for 224-pin BGA (top view)

R7FS7G2xxxA01CBG																
	A	B	C	D	E	F	G	H	J	K	L	M	N	P	R	
15	P407	P409	P411	P414	VSS	USBHS_DM	PVSS_USBHS	P212/EXTAL	XCIN	VCL0	P707	P703	P700	P405	P401	15
14	USB_DP	USB_DM	P410	P412	P415	USBHS_DP	AVSS_USBHS	P213/XTAL	XCOUT	VBATT	P706	P701	P406	P402	P512	14
13	P204	VCC_USB	VSS_USB	P408	P413	VCC_USBHS	USBHS_RREF	AVCC_USBHS	VSS	PB01	P704	P404	P400	P511	P805	13
12	P313	P202	P207	P206	P205	VSS1_USBHS	VSS2_USBHS	VCC	PB00	P705	P702	P403	P513	P806	P000	12
11	P900	P315	P314	P203								VCC	P001	P004	P002	11
10	VCL1	VSS	P901	VSS								VSS	P006	P008	P005	10
9	VLO	VLO	RES	VCC								P009	AVSS0	VREFL0	VREFH0	9
8	VCC_DCDC	P201/MD	P200	P908								P010	AVCC0	VREFL	VREFH	8
7	P906	P905	P312	P907								VCC	VSS	P015	P014	7
6	P310	P309	P307	P311								P007	P507	P505	VCL2	6
5	P308	P305	VSS	VCC								P003	P503	P504	P506	5
4	P306	P304	P300/TCK/SWCLK	P111	VSS	P613	PA09	PA00	P607	VCC	VSS	VSS	VCC	P501	P502	4
3	P303	P302	P108/TMS/SWDIO	P110/TDI	VCC	P610	VCC	VSS	P604	P603	P105	P102	P800	P804	P500	3
2	P301	P112	P114	P608	P611	P614	PA10	PA01	P605	P601	P107	P104	P101	P802	P803	2
1	P109/TDO	P113	P115	P609	P612	P615	PA08	VCL_F	P606	P602	P600	P106	P103	P100	P801	1
	A	B	C	D	E	F	G	H	J	K	L	M	N	P	R	

Figure 1.4 Pin assignment for 176-pin BGA (top view)

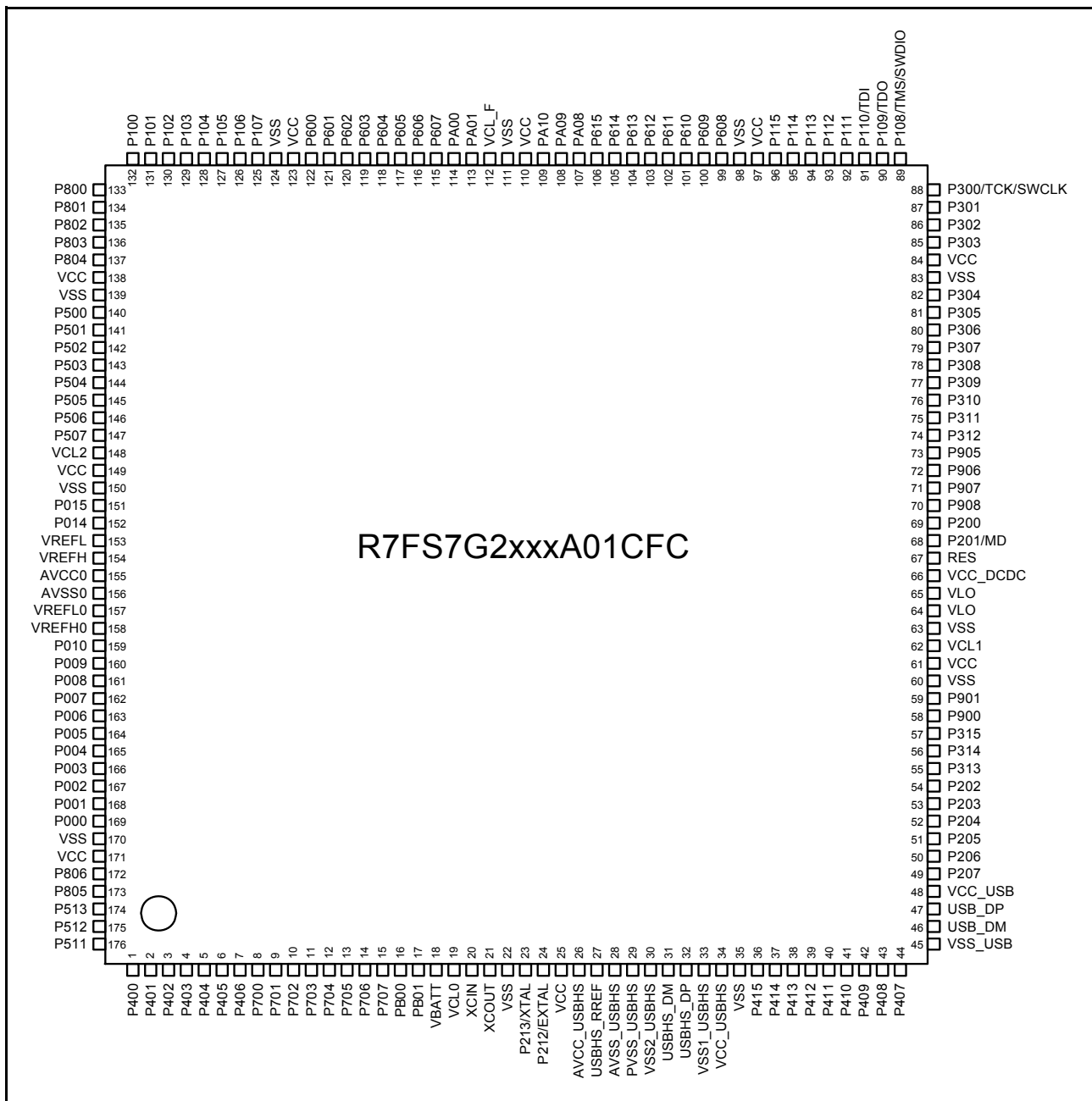


Figure 1.5 Pin assignment for 176-pin LQFP (top view)

**R7FS7G2xxxA01CLK**

	A	B	C	D	E	F	G	H	J	K	L	M	N		
13	P407	P409	P412	P708	P711	VCC	P212 /EXTAL	XCIN	VCL0	P702	P405	P402	P400	13	
12	USB_DM	USB_DP	P410	P414	P710	VSS	P213 /XTAL	XCOOUT	VBATT	P701	P404	P511	VCC	12	
11	VCC_USB	VSS_USB	P207	P411	P415	P712	P705	P704	P703	P403	P401	P512	VSS	11	
10	P205	P206	P204	P408	P413	P709	P713	P700	P406	P003	P000	P002	P001	10	
9	P203	P313	P202	VSS						P004	P006	P009	P008	9	
8	VCL1	VSS	P200	VCC						P005	AVSS0	VREFL0	VREFH0	8	
7	VLO	VLO	RES	P310						P007	AVCC0	VREFL	VREFH	7	
6	VCC_DCDC	P201/MD	P312	P305						P505	P506	F015	P014	6	
5	P309	P311	P308	P303	NC						P503	P504	VSS	VCC	5
4	P307	P306	P304	P109/TDO	P114	P608	P604	P600	P105	P500	P502	P501	VCL2	4	
3	VSS	VCC	P301	P112	P115	P610	P614	P603	P107	P106	P104	VSS	VCC	3	
2	P302	P300/TCK /SWCLK	P111	VCC	P609	P612	VSS	P605	P601	VCC	P800	P101	P801	2	
1	P108/TMS /SWDIO	P110/TDI	P113	VSS	P611	P613	VCC	VCL_F	P602	VSS	P103	P102	P100	1	

**Figure 1.6 Pin assignment for 145-pin LGA (top view)**

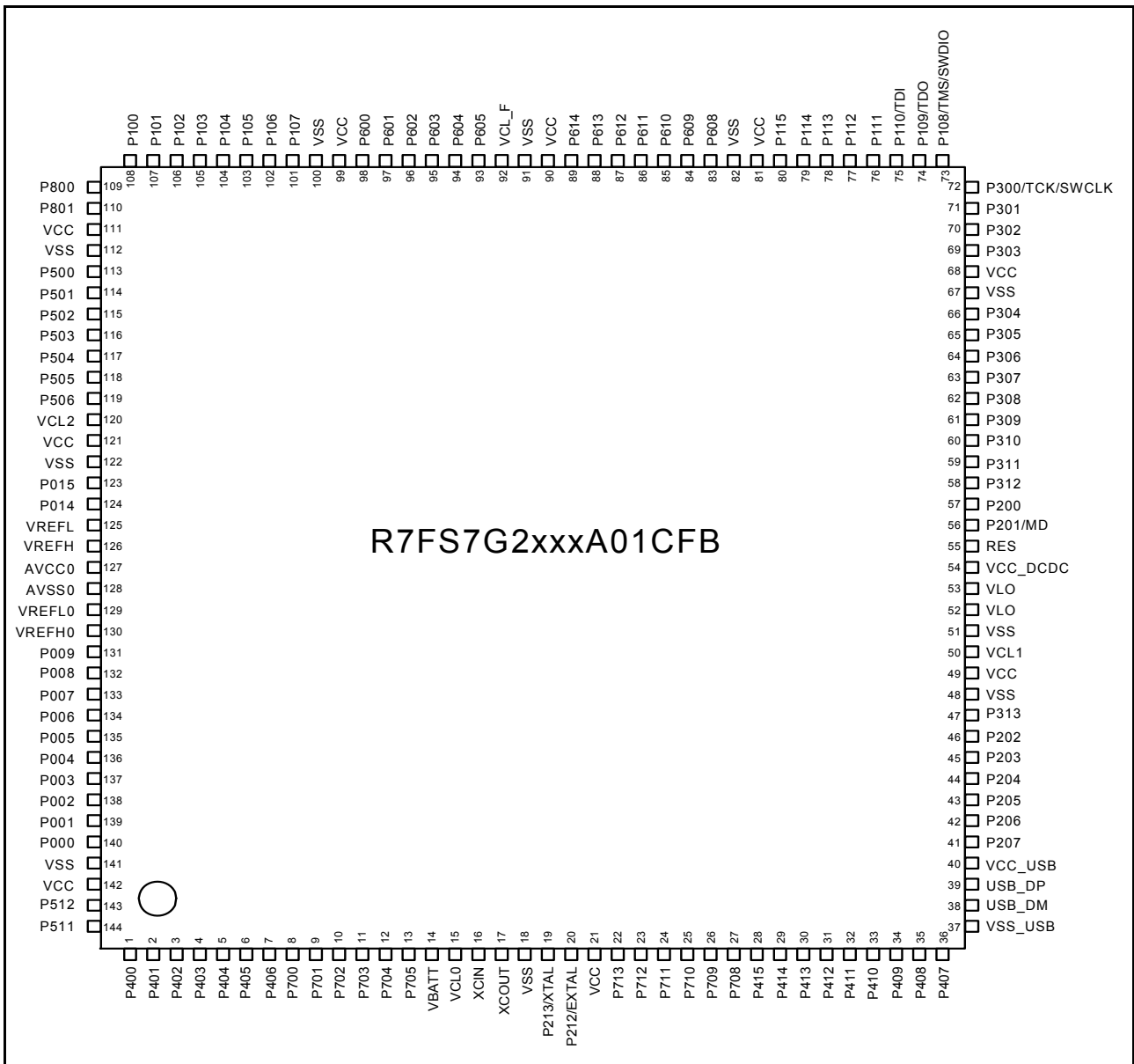


Figure 1.7 Pin assignment for 144-pin LQFP (top view)

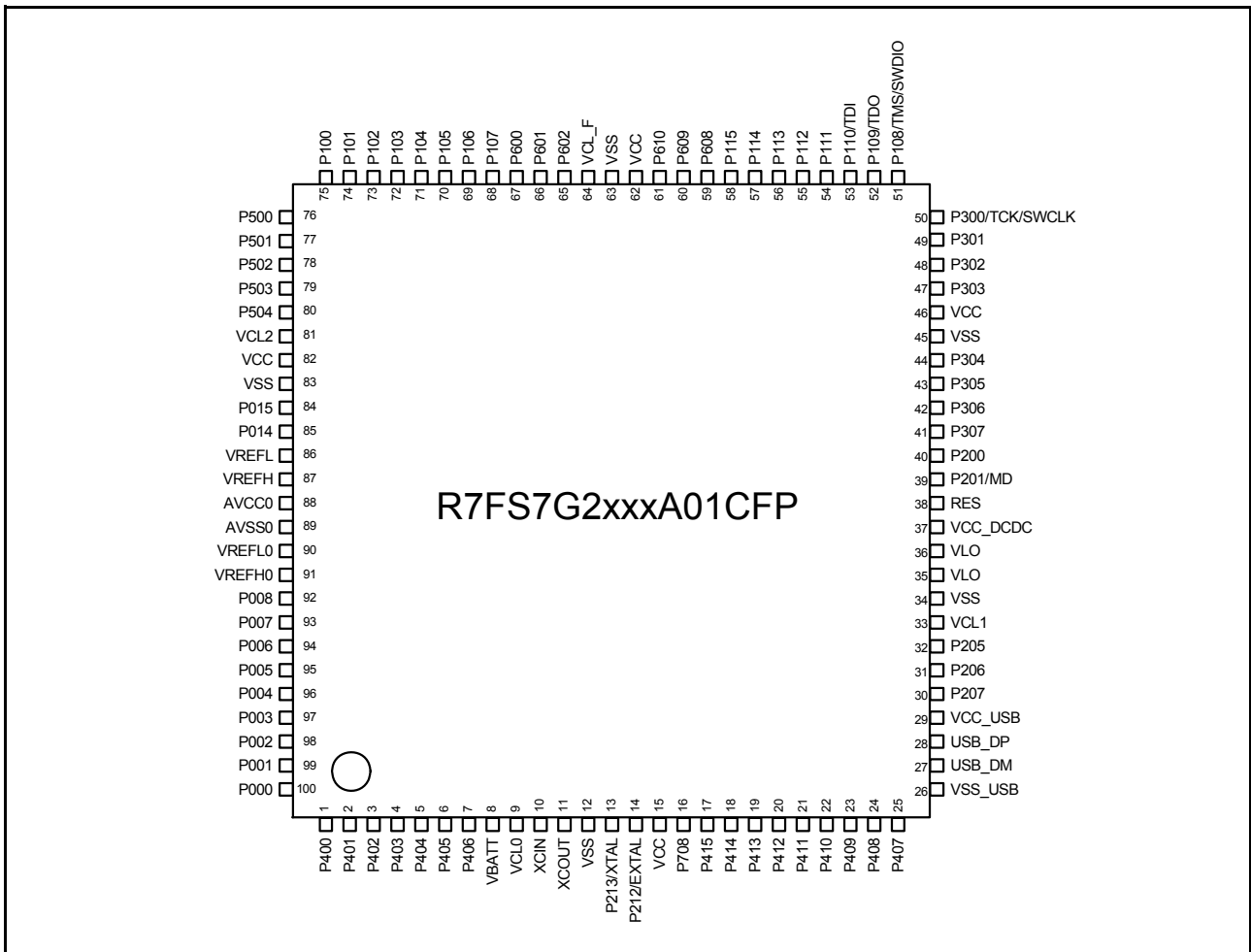


Figure 1.8 Pin assignment for 100-pin LQFP (top view)

## 1.7 Pin Lists

Table 1.17 Pin list (1/12)

Pin number						Power, System, Clock, Debug, I/O port	Extbus		Timers				Communication interfaces										Analog		HMI		GLCDC, PDC
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100		External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MII (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt	
N13	N13	1	N13	1	1	P40 0	-	-	-	-	GTI OC 6A_ A	-	SC K4_ B	SC K7_ A	SC L0_ A	-	AU DIO _CL K	ET1 _TX _CL K	-	-	-	AD TR G1_ B	-	-	-	IRQ 0	-
P15	R15	2	L11	2	2	P40 1	-	-	-	GT ET RG A_ B	GTI OC 6B_ A	-	CT X0_ B	CT S4_ RT S4_ S4_ SS 4_B	TX D7_ A/ MO S17 A/ SD A7_ A	SD A0_ A	-	-	ET0 _M DC	ET0 _M DC	-	-	-	-	IRQ 5- DS	-	
N14	P14	3	M1 3	3	3	P40 2	-	-	AG TIO 0_B / AG TIO 1_B	-	-	RT CIC 0	CR X0_ B	-	RX D7_ A/ MIS O7 _A/ SC L7_ A	-	-	-	ET0 _M DIO	ET0 _M DIO	-	-	-	-	IRQ 4- DS	-	
N15	M1 2	4	K11	4	4	P40 3	-	-	AG TIO 0_C / AG TIO 1_C	-	GTI OC 3A_ B	RT CIC 1	-	-	CT S7_ RT S7_ A/ SS 7_A	-	-	SSI SC K0_ A	ET1 _M DC	ET1 _M DC	-	-	-	-	-	PIX D7	-
K10	M1 3	5	L12	5	5	P40 4	-	-	-	GTI OC 3B_ B	RT CIC 2	-	-	-	-	-	-	SSI WS 0_A	ET1 _M DIO	ET1 _M DIO	-	-	-	-	-	PIX D6	-
M1 3	P15	6	L13	6	6	P40 5	-	-	-	GTI OC 1A_ B	-	-	-	-	-	-	-	SSI TX D0_ A	ET1 _TX _E N	RMI I1_ TX D_ EN	-	-	-	-	-	PIX D5	-
J9	N14	7	J10	7	7	P40 6	-	-	-	GTI OC 1B_ B	-	-	-	-	-	-	-	SSI RX D0_ A	ET1 _R X_ ER	RMI I1_ TX D1	-	-	-	-	-	PIX D4	-
M1 4	N15	8	H10	8	-	P70 0	-	-	-	GTI OC 5A_ B	-	-	-	-	-	-	-	-	ET1 _ET XD 1	RMI I1_ TX D0	-	-	-	-	-	PIX D3	-
M1 5	M1 4	9	K12	9	-	P70 1	-	-	-	GTI OC 5B_ B	-	-	-	-	-	-	-	-	ET1 _ET XD 0	RE F50 CK 1	-	-	-	-	-	PIX D2	-
K11	L12	10	K13	10	-	P70 2	-	-	-	GTI OC 6A_ B	-	-	-	-	-	-	-	-	ET1 _E RX D1	RMI I1_ RX D0	-	-	-	-	-	PIX D1	-
J8	M1 5	11	J11	11	-	P70 3	-	-	-	GTI OC 6B_ B	-	-	-	-	-	-	-	-	ET1 _E RX D0	RMI I1_ RX D1	-	-	-	-	-	PIX D0	-
J10	L13	12	H11	12	-	P70 4	-	-	-	-	-	-	-	-	-	-	-	-	ET1 _R X_ CL K	RMI I1_ RX _E R	-	-	-	-	-	HS YN C	-
L13	K12	13	G11	13	-	P70 5	-	-	-	-	-	-	-	-	-	-	-	-	ET1 _C RS	RMI I1_ CR S_ DV	-	-	-	-	-	PIX CL K	-
L14	L14	14	-	-	-	P70 6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	US BH S_ OV RC UR B	-	-	-	-	IRQ 7	-
L15	L15	15	-	-	-	P70 7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	US BH S_ OV RC UR A	-	-	-	-	IRQ 8	-

Table 1.17 Pin list (2/12)

Pin number						Power, System, Clock, Debug,	I/O port	Extbus		Timers					Communication interfaces										Analog			HMI		GLDC, PDC
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100			External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MII (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt			
H9	J12	16	-	-	-	-	PB00	-	-	-	-	-	-	SC K3_B	-	-	-	-	-	US BHS VB US EN	-	-	-	-	-	-	-			
J11	-	-	-	-	-	-	PB02	-	-	-	-	-	CT S8 RT S8 B/ SS 8_B	-	-	-	-	ET1 R X DV	-	-	-	-	-	-	-	-				
K12	-	-	-	-	-	-	PB03	-	-	-	-	-	SC K8_B	-	-	-	-	ET1 C OL	-	-	-	-	-	-	-	-				
H10	-	-	-	-	-	-	PB04	-	-	-	-	-	TX D8 B/ MO S18 B/ SD A8_B	-	-	-	-	ET1 E RX D2	-	-	-	-	-	-	IRQ 12	-				
K13	K13	17	-	-	-	-	PB01	-	-	-	-	-	CT S3 RT S3 B/ SS 3_B	-	-	-	-	-	US BHS VB US	-	-	-	-	-	-	-				
J12	-	-	-	-	-	-	PB05	-	-	-	-	-	RX D6 B/ MIS O6 B/ SC L6_B	-	-	-	-	ET1 E RX D3	-	-	-	-	-	-	IRQ 13	-				
H11	-	-	-	-	-	-	PB06	-	-	-	-	-	-	-	-	-	-	ET1 W OL	ET1 W OL	-	-	-	-	-	-	-	-			
G11	-	-	-	-	-	-	PB07	-	-	-	-	-	-	-	-	-	-	ET1 L NK STA	ET1 L NK STA	-	-	-	-	-	-	-	-			
K14	K14	18	J12	14	8	VB ATT	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
K15	K15	19	J13	15	9	VC LO	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
J15	J15	20	H13	16	10	XCI N	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
J14	J14	21	H12	17	11	XC OU T	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
J13	J13	22	F12	18	12	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
H14	H14	23	G1 2	19	13	XTA L	P21 3	-	-	-	GT ET RG C_A	-	-	TX D1 A/ MO S11 A/ SD A1_A	-	-	-	-	-	-	-	AD TR G1_A	-	-	IRQ 2	-				
H15	H15	24	G1 3	20	14	EX TAL	P21 2	-	-	AG TE E1	GT ET RG D_A	-	-	RX D1 A/ MIS O1 A/ SC L1_A	-	-	-	-	-	-	-	-	-	-	IRQ 3	-				
H12	H12	25	F13	21	15	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
H13	H13	26	-	-	-	AV CC U SB HS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			
G1 3	G1 3	27	-	-	-	US BHS RR EF	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-			



Table 1.17 Pin list (3/12)

Pin number						Power, System, Clock, Debug,	I/O port	Extbus		Timers					Communication interfaces										Analog		HMI	
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100			External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC11,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MII (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTS0	Interrupt	GLCDC, PDC
G14	G14	28	-	-	-	AVSS_USBHS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
G15	G15	29	-	-	-	PVSS_USBHS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
G12	G12	30	-	-	-	VS2_USBHS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
F15	F15	31	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	USBSDM	-	-	-	-	-	-	
F14	F14	32	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	USBSDP	-	-	-	-	-	-	
F12	F12	33	-	-	-	VS1_USBHS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
F13	F13	34	-	-	-	VC_USBHS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
E15	E15	35	-	-	-	VS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
G10	-	-	G10	22	-	-	P713	-	-	-	-	GTIOC2A_B	-	-	-	-	-	-	ET1EXOUT	ET1EXOUT	-	-	-	-	TS17	-	-	
F11	-	-	F11	23	-	-	P712	-	-	-	-	GTIOC2B_B	-	-	-	-	-	-	-	-	-	-	-	-	TS16	-	-	
E12	-	-	E13	24	-	-	P711	-	-	-	-	-	-	CTS1_RT_S1_B/SS1_B	-	-	-	ET0_TX_CLK	-	-	-	-	-	-	TS15	-	-	
F10	-	-	E12	25	-	-	P710	-	-	-	-	-	-	SCK1_B	-	-	-	ET0_TX_ER	-	-	-	-	-	-	TS14	-	-	
E13	-	-	F10	26	-	-	P709	-	-	-	-	-	-	TXD1_B/MOSI1_B/SDA1_B	-	-	-	ET0_ETXD2	-	-	-	-	-	-	TS13	IRQ10	-	
D15	-	-	D13	27	16	CA_CREF_B	P708	-	-	-	-	-	-	RXD1_B/MISO1_B/SC_L1_B	-	SSLA3_B	-	ET0_ETXD3	-	-	-	-	-	-	TS12	IRQ11	-	
E14	E14	36	E11	28	17	-	P415	-	-	-	-	-	-	-	-	SSLA2_B	-	ET0_TX_EN	RMI0_TX_D0	-	-	-	-	-	TS11	-	-	
E11	D15	37	D12	29	18	-	P414	-	-	-	-	-	-	-	-	SSLA1_B	-	ET0_RX_ER	RMI0_TX_D1	-	SDOWP	-	-	-	TS10	-	-	
D12	E13	38	E10	30	19	-	P413	-	-	GTOUTP_B	-	-	-	CTS0_RT_S0_B/SS0_B	-	SSLA0_B	-	ET0_ETXD1	RMI0_TX_D0	-	SDOCLK	-	-	-	TS09	-	-	
D13	D14	39	C13	31	20	-	P412	-	-	GTOUTO_B	-	-	-	SC_K0_B	-	RS_PCKA_B	-	ET0_ETXD0	REF50CK0	-	SDO_CMD	-	-	-	TS08	-	-	

Table 1.17 Pin list (4/12)

Pin number						Power, System, Clock, Debug, I/O port	Extbus		Timers				Communication interfaces										Analog		HMI					
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100		External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MII (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt	GLDC, PDC			
D14	C15	40	D11	32	21	-	P41 1	-	-	AG TO A1	GT OV UP _B	GTI OC 9A_ A	-	-	TX DO_ B/ MO SIO _B/ SD AO_ B	CT S3_ RT S3_ A/ SS 3_A	-	MO SIA _B	-	ET0 _E RX D1	RMI IO_ RX D0	-	SD OD AT0	-	-	TS0 7	IRQ 4	-		
C15	C14	41	C12	33	22	-	P41 0	-	-	AG TO B1	GT OV LO _B	GTI OC 9B_ A	-	-	RX DO_ B/ MIS OO _B/ SC LO_ B	SC K3_ A	-	MIS OA _B	-	ET0 _E RX D0	RMI IO_ RX D1	-	SD OD AT1	-	-	TS0 6	IRQ 5	-		
C14	B15	42	B13	34	23	-	P40 9	-	-	-	GT OW UP _B	GTI OC 10A _A	-	-	US B_ EXI CE N_ A	-	TX D3_ A/ MO SIO _A/ SD A3_ A	-	-	-	ET0 _R X_ CL K	RMI IO_ RX _E R	US BH S_ EXI CE N	-	-	-	TS0 5	IRQ 6	-	
B15	D13	43	D10	35	24	-	P40 8	-	-	-	GT OW LO _B	GTI OC 10B _A	-	-	US B_ I_ D_ A	-	RX D3_ A/ MIS O3 _A/ SC L3_ A	-	-	-	ET0 _C RS	RMI IO_ CR S_ DV	US BH S_ I_ D	-	-	-	TS0 4	IRQ 7	-	
A15	A15	44	A13	36	25	-	P40 7	-	-	-	-	-	-	RT CO UT	US B_ V B US	CT S4_ RT S4_ A/ SS 4_A	-	SD A0_ B	SS LB3 _A	-	ET0 _E XO UT	ET0 _E XO UT	-	-	AD TR GO	-	TS0 3	-	-	
B13	C13	45	B11	37	26	VS S_ US B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
B14	B14	46	A12	38	27	-	-	-	-	-	-	-	-	-	US B_ DM	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
A14	A14	47	B12	39	28	-	-	-	-	-	-	-	-	-	US B_ DP	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
A13	B13	48	A11	40	29	VC C_ US B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
C13	C12	49	C11	41	30	-	P20 7	A17	-	-	-	-	-	-	-	-	-	-	-	SS LB2 _A	-	-	-	-	-	-	TS0 2	-	-	
G9	D12	50	B10	42	31	-	P20 6	WAI T	-	-	GTI U_ A	-	-	-	US B_ V B US EN _A	RX D4_ A/ MIS O4 _A/ SC L4_ A	-	SD A1_ A	SS LB1 _A	SSI DA TA1 _A	ET0 _L I NK STA	ET0 _L I NK STA	-	SD OD AT2	-	-	TS0 1	IRQ 0- DS	-	
C12	E12	51	A10	43	32	CL KO UT _A	P20 5	A16	-	AG TO 1	GTI V_ A	GTI OC 4A_ B	-	-	US B_ O V RC UR A_ A- DS	TX D4_ A/ MO SIO _A/ SD A4_ A	CT S9_ RT S9_ A/ SS 9_A	SC L1_ A	SS LB0 _A	SSI WS 1_A	ET0 _W OL	ET0 _W OL	-	SD OD AT3	-	-	TS CA P_ A	IRQ 1- DS	-	
D11	A13	52	C10	44	-	CA CR EF_ A	P20 4	A18	-	AG TIO 1_A	GTI W_ A	GTI OC 4B_ B	-	-	US B_ O V RC UR B_ A- DS	SC K4_ A	SC K9_ A	SC L0_ B	RS PC KB _A	SSI SC K1_ A	ET0 _R X_ DV	-	-	SD OD AT4	-	-	TS0 0	-	-	
B12	D11	53	A9	45	-	-	P20 3	A19	-	-	-	GTI OC 5A_ A	-	-	CT X0_ A	CT S2_ RT S2_ A/ SS 2_A	TX D9_ A/ MO SIO _A/ SD A9_ A	-	MO SIB _A	-	ET0 _C OL	-	-	SD OD AT5	-	-	TS CA P_ B	IRQ 2- DS	-	

Table 1.17 Pin list (5/12)

Pin number						Power, System, Clock, Debug, I/O port	Extbus					Timers					Communication interfaces										Analog			HMI		GLCDC, PDC
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100		External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MI (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt						
A12	B12	54	C9	46	-	P20 2	WR 1/ BC 1	-	-	-	GTI OC 5B_ A	-	CR X0_ A	SC K2_ A	RX D9_ A/ MIS O9_ A/ SD A9_ A	-	MIS OB_ A	-	ET0 E RX D2	-	-	SD 0D AT6	-	-	-	-	IRQ 3- DS	LC D_ TC ON 3_ B				
E10	A12	55	B9	47	-	P31 3	A20	-	-	-	-	-	-	-	-	-	-	-	-	-	-	SD 0D AT7	-	-	-	-	-	LC D_ TC ON 2_ B				
F9	C11	56	-	-	-	P31 4	A21	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ TC ON 1_ B				
C11	B11	57	-	-	-	P31 5	A22	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ TC ON 0_ B				
E9	A11	58	-	-	-	P90 0	A23	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ CL K_ B				
B11	C10	59	-	-	-	P90 1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA1 5_ B				
A11	-	-	-	-	-	P90 2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA2 3_ B				
C10	D10	60	D9	48	-	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
D10	D9	61	D8	49	-	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
D9	-	-	-	-	-	P90 3	-	-	-	-	GTI OC 7A_ B	-	-	-	-	-	-	-	-	-	-	SD 0C D	-	-	-	-	-	-				
C9	-	-	-	-	-	P90 4	-	-	-	-	GTI OC 7B_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
A10	A10	62	A8	50	33	VC L1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
B10	B10	63	B8	51	34	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
A9	A9	64	A7	52	35	VL O	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
B9	B9	65	B7	53	36	VL O	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
A8	A8	66	A6	54	37	VC C, DC DC	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
H8	-	-	-	-	-	P91 3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
F8	C9	67	C7	55	38	RE S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
C8	B8	68	B6	56	39	MD	P20 1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
B8	C8	69	C8	57	40	-	P20 0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	NMI	-				
B7	-	-	-	-	-	P91 2	-	-	-	-	GTI OC 8A_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
A7	-	-	-	-	-	P91 1	-	-	-	-	GTI OC 8B_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-				
D8	-	-	-	-	-	P91 0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA2 2_ B				
E8	-	-	-	-	-	P90 9	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA2 1_ B				

Table 1.17 Pin list (6/12)

Pin number						Power, System, Clock, Debug,	I/O port	Extbus		Timers					Communication interfaces										Analog			HMI		GLCDC, PDC
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100			External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MI (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt			
E7	D8	70	-	-	-	-	P908	CS7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 4_B
F7	D7	71	-	-	-	-	P907	CS6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 3_B
F6	A7	72	-	-	-	-	P906	CS5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 2_B
A6	B7	73	-	-	-	-	P905	CS4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 1_B
B6	C7	74	C6	58	-	-	P312	CS3	CA S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
C7	D6	75	B5	59	-	-	P311	CS2	RA S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA2 3_A
A4	-	-	-	-	-	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
B4	-	-	-	-	-	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
C6	A6	76	D7	60	-	-	P310	A15	A15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA2 2_A
C5	B6	77	A5	61	-	-	P309	A14	A14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA2 1_A
D7	A5	78	C5	62	-	-	P308	A13	A13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA2 0_A
D6	C6	79	A4	63	41	-	P307	A12	A12	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 9_A
D5	A4	80	B4	64	42	-	P306	A11	A11	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 8_A
D4	B5	81	D6	65	43	-	P305	A10	A10	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 7_A
C4	B4	82	C4	66	44	-	P304	A09	A09	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 6_A
A5	C5	83	A3	67	45	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
B5	D5	84	B3	68	46	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
E6	-	-	-	-	-	-	P915	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA2 0_B
E5	-	-	-	-	-	-	P914	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC_D_DA TA1 9_B

Table 1.17 Pin list (7/12)

Pin number						Power, System, Clock, Debug, I/O port	Extbus		Timers			Communication interfaces										Analog		HMI		GLCDC, PDC			
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100		External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MI (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU		Interrupt		
A3	A3	85	D5	69	47	-	P30 3	A08	A08	-	-	GTI OC 7B_ A	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA1 5_A
A2	B3	86	A2	70	48	-	P30 2	A07	A07	-	-	GT OU UP _A	GTI OC 4A_ A	-	-	-	-	-	-	-	-	-	-	-	-	-	IRQ 5	LC D_ DA TA1 4_A	
B3	A2	87	C3	71	49	-	P30 1	A06	A06	-	-	GT OU LO _A	GTI OC 4B_ A	-	-	-	-	-	-	-	-	-	-	-	-	-	IRQ 6	LC D_ DA TA1 3_A	
F5	C4	88	B2	72	50	TC K/S W/LK	P30 0	-	-	-	-	GTI OC 0A_ A	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
B2	C3	89	A1	73	51	TM S/S WD IO	P10 8	-	-	-	-	GTI OC 0B_ A	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
B1	A1	90	D4	74	52	CL K/UT _B/ TD O/S WO	P10 9	-	-	-	-	GT OU UP _A	GTI OC 1A_ A	-	-	CT X1_ A	-	-	-	-	-	-	-	-	-	-	-	-	-
C2	D3	91	B1	75	53	TDI	P11 0	-	-	-	-	GT OU LO _A	GTI OC 1B_ A	-	-	CR X1_ A	CT S2_ RT S2_ B/ SS 2_B	RX D9_ B/ MIS O9 _B/ SD A9 B	-	-	-	-	-	-	-	-	VC OU T	IRQ 3	-
C1	D4	92	C2	76	54	-	P11 1	A05	A05	-	-	GTI OC 3A_ A	-	-	-	SC K2_ B	SC K9 B	-	-	-	-	-	-	-	-	-	-	IRQ 4	LC D_ DA TA1 2_A
C3	B2	93	D3	77	55	-	P11 2	A04	A04	-	-	GTI OC 3B_ A	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA1 1_A
D3	B1	94	C1	78	56	-	P11 3	A03	A03	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA1 0_A
E4	C2	95	E4	79	57	-	P11 4	A02	A02	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 9_A
E3	C1	96	E3	80	58	-	P11 5	A01	A01	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 8_A
D1	E3	97	D2	81	-	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
D2	E4	98	D1	82	-	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
F4	D2	99	F4	83	59	-	P60 8	A00 /BC 0	A00 /DQ M1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 7_A

Table 1.17 Pin list (8/12)

Pin number						Power, System, Clock, Debug,	I/O port	Extbus		Timers				Communication interfaces										Analog		HMI		GLCDC, PDC		
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100			External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MII (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt			
G4	D1	100	E2	84	60	-	P60 9	CS 1	CK M	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 6_A	
E1	F3	101	F3	85	61	-	P61 0	CS 0	WE	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 5_A	
E2	E2	102	E1	86	-	-	P61 1	-	SD CS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
F2	E1	103	F2	87	-	-	P61 2	D08	DQ 08	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
F3	F4	104	F1	88	-	-	P61 3	D09	DQ 09	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
F1	F2	105	G3	89	-	-	P61 4	D10	DQ 10	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
G8	F1	106	-	-	-	-	P61 5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA1 0_B	
G7	G1	107	-	-	-	-	PA0 8	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 9_B	
G6	-	-	-	-	-	-	PA1 1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA1 8_B	
G5	-	-	-	-	-	TC LK	PA1 2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
H4	G4	108	-	-	-	-	PA0 9	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 8_B	
H7	-	-	-	-	-	TD ATA 0	PA1 3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
G3	-	-	-	-	-	TD ATA 1	PA1 4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
H5	G2	109	-	-	-	-	PA1 0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 7_B	
G2	-	-	-	-	-	TD ATA 2	PA1 5	-	-	-	-	GTI OC 9A_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
G1	-	-	-	-	-	TD ATA 3	P81 3	-	-	-	-	GTI OC 9B_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
H3	G3	110	G1	90	62	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
H2	H3	111	G2	91	63	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
H1	H1	112	H1	92	64	VC L_F	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
J1	-	-	-	-	-	-	PA0 7	-	-	-	-	GTI OC 10A_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
J2	-	-	-	-	-	-	PA0 6	-	-	-	-	GTI OC 10B_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
J3	-	-	-	-	-	-	PA0 5	-	-	-	-	GTI OC 11A_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	CT S7_ RT S7_ B/ SS 7_B
J4	-	-	-	-	-	-	PA0 4	-	-	-	-	GTI OC 11B_ B	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	SC K7_ B

Table 1.17 Pin list (9/12)

Pin number						Power, System, Clock, Debug, I/O port	Extbus		Timers				Communication interfaces								Analog		HMI		GLCDC, PDC		
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100		External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MI (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS		CTSU	Interrupt
J5	-	-	-	-	-	PA0 3	-	-	-	-	-	-	-	RX D7_ B/ MIS O7 _B/ SC L7_ B	-	-	-	-	-	-	-	-	-	-	-	IRQ 9	-
H6	-	-	-	-	-	PA0 2	-	-	-	-	-	-	-	TX D7_ B/ MO S17 B/ SD A7_ B	-	-	-	-	-	-	-	-	-	-	-	IRQ 10	-
J6	H2	113	-	-	-	PA0 1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 6_B
J7	H4	114	-	-	-	PA0 0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 5_B
K5	J4	115	-	-	-	P60 7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 4_B
K6	J1	116	-	-	-	P60 6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 3_B
K1	J2	117	H2	93	-	P60 5	D11	DQ 11	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
K2	J3	118	G4	94	-	P60 4	D12	DQ 12	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
K3	K3	119	H3	95	-	P60 3	D13	DQ 13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
L1	K1	120	J1	96	65	P60 2	EB CL K	SD CL K	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 4_A
L2	K2	121	J2	97	66	P60 1	WR /W RO	DQ MO	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 3_A
L3	L1	122	H4	98	67	P60 0	RD	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA0 2_A
M2	K4	123	K2	99	-	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
M1	L4	124	K1	100	-	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
K4	L2	125	J3	101	68	P10 7	D07	DQ 07	-	-	GTI OC 8A_ A	-	-	CT S8_ RT S8_ A/ SS 8_A	-	-	-	-	-	-	-	-	-	-	-	KR 07	LC D_ DA TA0 1_A
L4	M1	126	K3	102	69	P10 6	D06	DQ 06	-	-	GTI OC 8B_ A	-	-	SC K8_ A	-	-	SS LA3 _A	-	-	-	-	-	-	-	-	KR 06	LC D_ DA TA0 0_A
M3	L3	127	J4	103	70	P10 5	D05	DQ 05	-	GT ET RG A_ C	-	-	TX D8_ A/ MO S18 A/ SD A8_ A	-	-	SS LA2 _A	-	-	-	-	-	-	-	-	IRQ 0/K R05	LC D_ TC ON 3_A	
N3	M2	128	L3	104	71	P10 4	D04	DQ 04	-	GT ET RG B_ B	-	-	RX D8_ A/ MIS O8 A/ SC L8_ A	-	-	SS LA1 _A	-	-	-	-	-	-	-	-	IRQ 1/K R04	LC D_ TC ON 2_A	

Table 1.17 Pin list (10/12)

Pin number						Power, System, Clock, Debug, I/O port	Extbus					Timers					Communication interfaces										Analog			HMI		GLCDC, PDC
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100		External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MI (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt						
N2	N1	129	L1	105	72	-	P103	D03	DQ03	-	GTOWUP_A	GTI OC2A_A	-	-	CT S0_RT S0_A/SS0_A	-	SS LA0_A	-	-	-	-	-	-	-	-	KR03	LC D_TC ON1_A					
N1	M3	130	M1	106	73	-	P102	D02	DQ02	AGT0	GTOWLO_A	GTI OC2B_A	-	-	SC K0_A	-	RS PC KA_A	-	-	-	-	-	AD TR GO_A	-	-	KR02	LC D_TC ON0_A					
P1	N2	131	M2	107	74	-	P101	D01	DQ01	AGTE0	GTETRG_B_A	-	-	-	TX DO_A/ MO SI_A/ SD A0_A	CT S1_RT S1_A/SS1_A	SD A1_B	MO SIA_A	-	-	-	-	-	-	-	IRQ1/KR01	LC D_CL K_A					
R1	P1	132	N1	108	75	-	P100	D00	DQ00	AGTIO0_A	GTETRG_A_A	-	-	-	RX DO_A/ MIS O0_A/ SL CO_A	SC K1_A	SC L1_B	MIS OA_A	-	-	-	-	-	-	-	IRQ2/KR00	LC D_EX TC LK_A					
P2	N3	133	L2	109	-	-	P800	D14	DQ14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-					
R2	R1	134	N2	110	-	-	P801	D15	DQ15	-	-	-	-	-	-	-	-	-	-	-	-	SD1D AT4	-	-	-	-	-					
K7	-	-	-	-	-	-	P808	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-					
K8	-	-	-	-	-	-	P809	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-					
P3	-	-	-	-	-	-	P810	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-					
R3	P2	135	-	-	-	-	P802	-	-	-	-	-	-	-	-	-	-	-	-	-	-	SD1D AT5	-	-	-	-	LC D_DA TA02_B					
P4	R2	136	-	-	-	-	P803	-	-	-	-	-	-	-	-	-	-	-	-	-	-	SD1D AT6	-	-	-	-	LC D_DA TA01_B					
M4	P3	137	-	-	-	-	P804	-	-	-	-	-	-	-	-	-	-	-	-	-	-	SD1D AT7	-	-	-	-	LC D_DA TA00_B					
L5	-	-	-	-	-	-	P811	-	-	-	-	-	-	-	CT X0_C	-	-	-	-	-	-	-	-	-	-	-	-	-				
L6	-	-	-	-	-	-	P812	-	-	-	-	-	-	-	CR X0_C	-	-	-	-	-	-	-	-	-	-	-	-	-				
L7	N4	138	N3	111	-	VC	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-					
L8	M4	139	M3	112	-	VS	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-					
R4	R3	140	K4	113	76	-	P500	-	-	AGT A0	GTI U_B	GTI OC11A_A	-	-	US B_VB US EN_B	-	QS PC LK	-	-	-	-	SD1C LK	AN016	IVR EF0	-	-	-					
N4	P4	141	M4	114	77	-	P501	-	-	AGT B0	GTI V_B	GTI OC11B_A	-	-	US B_OV RC UR_A_B	-	QS SL	-	-	-	-	SD1C MD	AN116	IVR EF1	IRQ11	-						
N5	R4	142	L4	115	78	-	P502	-	-	-	GTI W_B	GTI OC12A	-	-	US B_OV RC UR_B_B	-	QIO0	-	-	-	-	SD1D AT0	AN017	IVC MP0	IRQ12	-						



Table 1.17 Pin list (11/12)

Pin number						Power, System, Clock, Debug,	I/O port	Extbus		Timers				Communication interfaces										Analog		HMI		GLCDC, PDC	
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100			External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SC0,2,4,6,8 (30 MHz)	SC1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MI (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt		
P5	N5	143	K5	116	79	-	P503	-	-	-	GTETRG_B/ C/ D/ E/ F/ G/ H/ I/ J/ K/ L/ M/ N/ O/ P/ Q/ R/ S/ T/ U/ V/ W/ X/ Y/ Z	GTIOC12B	-	US B_/ EXI CE N_/ B	CT S6_/ RT S6_/ B/ SS 6_B	SC K5_/ A	-	QIO1	-	-	-	-	-	SD 1D AT1	AN 117	-	-	-	-
R5	P5	144	L5	117	80	-	P504	-	-	-	GTETRG_D/ B	GTIOC13A	-	US B_/ D_/ B	SC K6_/ B	CT S5_/ RT S5_/ A/ SS 5_A	-	QIO2	-	-	-	-	-	SD 1D AT2	AN 018	-	-	-	-
M5	P6	145	K6	118	-	-	P505	-	-	-	GTIOC13B	-	-	RX D6_/ B/ MIS O6_/ B/ SC L6_/ B	-	QIO3	-	-	-	-	-	-	SD 1D AT3	AN 118	-	-	IRQ 14	-	
M6	R5	146	L6	119	-	-	P506	-	-	-	-	-	-	TX D6_/ B/ MO SI6_/ B/ SD A6_/ B	-	-	-	-	-	-	-	SD 1C D	AN 019	-	-	IRQ 15	-		
N6	N6	147	-	-	-	-	P507	-	-	-	-	-	-	CT S5_/ RT S5_/ B/ SS 5_B	-	-	-	-	-	-	-	SD 1W P	AN 119	-	-	-	-		
M7	-	-	-	-	-	-	P508	-	-	-	-	-	-	SC K5_/ B	-	-	-	-	-	-	-	-	AN 020	-	-	-	-		
P6	-	-	-	-	-	-	P509	-	-	-	-	-	-	TX D5_/ B/ MO SI5_/ B/ SD A5_/ B	-	-	-	-	-	-	-	-	AN 120	-	-	-	-		
N7	-	-	-	-	-	-	P510	-	-	-	-	-	-	RX D5_/ B/ MIS O5_/ B/ SC L5_/ B	-	-	-	-	-	-	-	-	AN 021	-	-	-	-		
R6	R6	148	N4	120	81	VC L2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
P7	M7	149	N5	121	82	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
R7	N7	150	M5	122	83	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
M8	P7	151	M6	123	84	-	P015	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 006 /AN 106	DA 1/IV CM P1	-	IRQ 13	-		
M9	R7	152	N6	124	85	-	P014	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 005 /AN 105	DA 0/IV RE F3	-	-	-		
N8	P8	153	M7	125	86	VR EFL	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
R8	R8	154	N7	126	87	VR EFH	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
P8	N8	155	L7	127	88	AV CC0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
N9	N9	156	L8	128	89	AV SS0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
P9	P9	157	M8	129	90	VR EFL0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
R9	R9	158	N8	130	91	VR EFH0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		

Table 1.17 Pin list (12/12)

Pin number						Power, System, Clock, Debug, I/O port	Extbus		Timers			Communication interfaces										Analog		HMI				
BGA224	BGA176	LQFP176	LGA145	LQFP144	LQFP100		External bus	SDRAM	AGT	GPT	GPT	RTC	USBFS, CAN	SCI0,2,4,6,8 (30 MHz)	SCI1,3,5,7,9 (30 MHz)	IIC	SPI, QSPI	SSI	MI (25 MHz)	RMI (50 MHz)	USBHS	SDHI	ADC12	DAC12, ACMPHS	CTSU	Interrupt	GLCDC, PDC	
N10	-	-	-	-	-	P01 1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 104	-	-	IRQ 15- DS	-	
M10	M8	159	-	-	-	P01 0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 103	-	-	IRQ 14- DS	-	
R10	M9	160	M9	131	-	P00 9	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 004	-	-	IRQ 13- DS	-	
N11	P10	161	N9	132	92	P00 8	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 003	-	-	IRQ 12- DS	-	
L9	M6	162	K7	133	93	P00 7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	PG AV SS 100	-	-	-	-	
P10	N10	163	L9	134	94	P00 6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 102	IVC MP 2	-	IRQ 11- DS	-	
R11	R10	164	K8	135	95	P00 5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 101	IVC MP 2	-	IRQ 10- DS	-	
M11	P11	165	K9	136	96	P00 4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 100	IVC MP 2	-	IRQ 9- DS	-	
L10	M5	166	K10	137	97	P00 3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	PG AV SS 000	-	-	-	-	
N12	R11	167	M10	138	98	P00 2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 002	IVC MP 2	-	IRQ 8- DS	-	
P11	N11	168	N10	139	99	P00 1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 001	IVC MP 2	-	IRQ 7- DS	-	
R12	R12	169	L10	140	100	P00 0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	AN 000	IVC MP 2	-	IRQ 6- DS	-	
L11	M10	170	N11	141	-	VS S	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
L12	M11	171	N12	142	-	VC C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
M12	P12	172	-	-	-	P80 6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ EX TC LK_ B	
R13	R13	173	-	-	-	P80 5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LC D_ DA TA1 7_B	
P12	-	-	-	-	-	P80 7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
P13	N12	174	-	-	-	P51 3	-	-	-	-	-	-	-	-	-	-	-	-	ET1 ET XD 3	-	-	-	-	-	-	-	LC D_ DA TA1 6_B	
K9	-	-	-	-	-	P51 5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
R14	R14	175	M11	143	-	P51 2	-	-	-	-	GT I OC 0A_ B	-	CT X1_ B	TX D4_ B/ MO S14_ B/ SD A4_ B	-	SC L2	-	-	ET1 ET XD 2	-	-	-	-	-	-	-	IRQ 14	VS YN C
P14	-	-	-	-	-	P51 4	-	-	-	GT ET RG B_ C	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
R15	P13	176	M12	144	-	P51 1	-	-	-	-	GT I OC 0B_ B	-	CR X1_ B	RX D4_ B/ MIS O4_ B/ SC L4_ B	-	SD A2	-	-	ET1 TX E R	-	-	-	-	-	-	IRQ 15	PC KO	

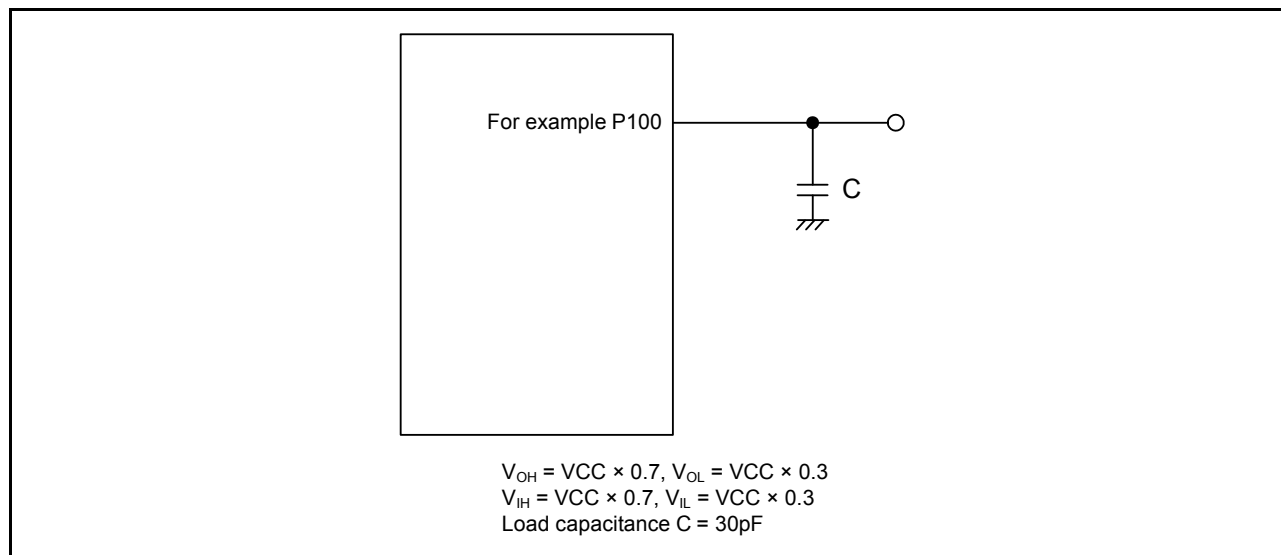
Note: Some pin names have the added suffix of \_A, \_B, and \_C. When assigning the IIC, SPI, and SSI functionality, select the functional pins with the same suffix. The other pins can be selected regardless of the suffix.

## 2. Electrical Characteristics

Unless otherwise specified, the electrical characteristics of the MCU are defined under the following conditions:

$VCC = AVCC0 = VCC\_USB = VBATT = 2.7$  to  $3.6$  V,  $2.7 \leq VREFH0/VREFH \leq AVCC0$ ,  $VCC\_USBHS = AVCC\_USBHS = 3.0$  to  $3.6$  V,  $VSS = AVSS0 = VREFL0/VREFL = VSS\_USB = VSS1\_USBHS = VSS2\_USBHS = PVSS\_USBHS = AVSS\_USBHS = 0$  V,  $T_a = T_{opr}$

Figure 2.1 shows the timing conditions.



**Figure 2.1** Input or output timing measurement conditions

The measurement conditions of timing specification in each peripherals are recommended for the best peripheral operation, however make sure to adjust driving abilities of each pins to meet your conditions.

### 2.1 Absolute Maximum Ratings

**Table 2.1** Absolute maximum ratings

Item	Symbol	Value	Unit
Power supply voltage	$VCC, VCC\_USB$ *2	-0.3 to +4.6	V
VBATT power supply voltage	VBATT	-0.3 to +4.6	V
Input voltage (except for 5V-tolerant ports*1)	$V_{in}$	-0.3 to $VCC + 0.3$	V
Input voltage (5V-tolerant ports*1)	$V_{in}$	-0.3 to +5.8	V
Reference power supply voltage	VREFH/VREFH0	-0.3 to $VCC + 0.3$	V
Analog power supply voltage	AVCC0 *2	-0.3 to +4.6	V
USBHS power supply voltage	VCC_USBHS	-0.3 to +4.6	V
USBHS analog power supply voltage	AVCC_USBHS	-0.3 to +4.6	V
Switching regulator power supply voltage	VCC_DCDC	-0.3 to +4.6	V
Analog input voltage	$V_{AN}$	-0.3 to AVCC0 + 0.3	V
Operating temperature*3 *4	$T_{opr}$	-40 to +105	°C
Storage temperature	$T_{stg}$	-55 to +125	°C

**Caution:** Permanent damage to the MCU might result if absolute maximum ratings are exceeded.

Note 1. Ports P205, P206, P400, P401, P407 to P415, P511, P512, P708 to P713, and PB01 are 5V-tolerant.

Note 2. Connect AVCC0 and VCC\_USB to VCC.

Note 3. See [section 2.2.1, Tj/Ta Definition](#).

Note 4. Contact a Renesas Electronics sales office for information on derating operation when  $T_a = +85^\circ\text{C}$  to  $+105^\circ\text{C}$ .

Derating is the systematic reduction of load for improved reliability.

**Table 2.2 Recommended operating conditions**

Item	Symbol	Value	Min	Typ	Max	Unit
Power supply voltages	VCC	When USB/SDRAM is not used	2.7	-	3.6	V
		When USB/SDRAM is used	3.0	-	3.6	V
	VSS		-	0	-	V
USB power supply voltages	VCC_USB, VCC_USBHS		-	VCC	-	V
	VSS_USB, AVSS_USBHS, PVSS_USBHS, VSS1_USBHS, VSS2_USBHS		-	0	-	V
Switching regulator power supply voltage	VCC_DCDC	When switching regulator is used	-	VCC	-	V
		When switching regulator is not used	-	0	-	V
VBATT power supply voltage	VBATT		2.0		3.6	V
Analog power supply voltages	AVCC0		-	VCC	-	V
	AVSS0		-	0	-	V

## 2.2 DC Characteristics

### 2.2.1 T<sub>j</sub>/T<sub>a</sub> Definition

**Table 2.3 DC characteristics**

Conditions: Products with operating temperature (T<sub>a</sub>) -40 to +105°C

Item	Symbol	Typ	Max	Unit	Test conditions
Permissible junction temperature	T <sub>j</sub>	-	125	°C	High-speed mode Low-speed mode Subosc-speed mode

Note: Make sure that  $T_j = T_a + \theta_{ja} \times \text{total power consumption (W)}$ , where total power consumption =  $(V_{CC} - V_{OH}) \times \Sigma I_{OH} + V_{OL} \times \Sigma I_{OL} + I_{CCmax} \times V_{CC}$ .

### 2.2.2 I/O V<sub>IH</sub>, V<sub>IL</sub>

**Table 2.4 I/O V<sub>IH</sub>, V<sub>IL</sub> (1/2)**

Item	Symbol	Min	Typ	Max	Unit		
Input voltage (except for Schmitt trigger input pins)	Peripheral function pin	EXTAL(external clock input), WAIT, SPI	V <sub>IH</sub>	VCC × 0.8	-	VCC + 0.3	V
			V <sub>IL</sub>	-0.3	-	VCC × 0.2	
	D00 to D15, DQ00 to DQ15	V <sub>IH</sub>	VCC × 0.7	-	VCC + 0.3		
		V <sub>IL</sub>	-0.3	-	VCC × 0.3		
	ETHERC	V <sub>IH</sub>	2.3	-	VCC + 0.3		
		V <sub>IL</sub>	-0.3	-	VCC × 0.2		
	IIC (SMBus)*1	V <sub>IH</sub>	2.1	-	VCC + 0.3		
		V <sub>IL</sub>	-0.3	-	0.8		
	IIC (SMBus)*2	V <sub>IH</sub>	2.1	-	5.8		
		V <sub>IL</sub>	-0.3	-	0.8		

**Table 2.4 I/O  $V_{IH}$ ,  $V_{IL}$  (2/2)**

Item			Symbol	Min	Typ	Max	Unit
Schmitt trigger input voltage	Peripheral function pin	IIC (except for SMBus)* <sup>1</sup>	$V_{IH}$	$VCC \times 0.7$	-	$VCC + 0.3$	V
			$V_{IL}$	-0.3	-	$VCC \times 0.3$	
			$\Delta V_T$	$VCC \times 0.05$	-	-	
		IIC (except for SMBus)* <sup>2</sup>	$V_{IH}$	$VCC \times 0.7$	-	5.8	
			$V_{IL}$	-0.3	-	$VCC \times 0.3$	
			$\Delta V_T$	$VCC \times 0.05$	-	-	
		5V-tolerant ports* <sup>3</sup>	$V_{IH}$	$VCC \times 0.8$	-	5.8	
			$V_{IL}$	-0.3	-	$VCC \times 0.2$	
			$\Delta V_T$	$VCC \times 0.05$	-	-	
		RTCIC0, RTCIC1, RTCIC2 (When $V_{BATT}$ power supply is selected)	$V_{IH}$	$V_{BATT} \times 0.8$	-	$V_{BATT} + 0.3$	
			$V_{IL}$	-0.3	-	$V_{BATT} \times 0.2$	
			$\Delta V_T$	$V_{BATT} \times 0.05$	-	-	
		Other input pins* <sup>4</sup>	$V_{IH}$	$VCC \times 0.8$	-	$VCC + 0.3$	
			$V_{IL}$	-0.3	-	$VCC \times 0.2$	
			$\Delta V_T$	$VCC \times 0.05$	-	-	
	Ports	5V-tolerant ports* <sup>5</sup>	$V_{IH}$	$VCC \times 0.8$	-	5.8	
			$V_{IL}$	-0.3	-	$VCC \times 0.2$	
		Other input pins* <sup>6</sup>	$V_{IH}$	$VCC \times 0.8$	-	$VCC + 0.3$	
$V_{IL}$			-0.3	-	$VCC \times 0.2$		

Note 1. SCL0\_B, SCL1\_B, SDA1\_B (total 3 pins).

Note 2. SCL0\_A, SDA0\_A, SDA0\_B, SCL1\_A, SDA1\_A, SCL2, SDA2 (total 7 pins).

Note 3. RES and peripheral function pins associated with P205, P206, P400, P401, P407 to P415, P511, P512, P708 to P713, PB01 (total 23 pins).

Note 4. All input pins except for the peripheral function pins already described in the table.

Note 5. P205, P206, P400, P401, P407 to P415, P511, P512, P708 to P713, PB01 (total 22pins).

Note 6. All input pins except for the ports already described in the table.

2.2.3 I/O  $I_{OH}$ ,  $I_{OL}$ Table 2.5 I/O  $I_{OH}$ ,  $I_{OL}$ 

Item		Symbol	Min	Typ	Max	Unit	
Permissible output current (average value per pin)	Ports P008 to P011, P201,P212	$I_{OH}$	-	--	-2.0	mA	
		$I_{OL}$	-	-	2.0	mA	
	Ports P014, P015, P213, P400, P401, P511, P512	$I_{OH}$	-	-	-4.0	mA	
		$I_{OL}$	-	-	4.0	mA	
	Ports P402 to P404	Low drive*1	$I_{OH}$	-	-	-2.0	mA
			$I_{OL}$	-	-	2.0	mA
		Middle drive*2	$I_{OH}$	-	-	-4.0	mA
			$I_{OL}$	-	-	4.0	mA
	Ports P205, P206, P407 to P415, P602, P708 to P713, P813, PA12 to PA15, PB01 (total 24 pins)	Low drive*1	$I_{OH}$	-	-	-2.0	mA
			$I_{OL}$	-	-	2.0	mA
		Middle drive*2	$I_{OH}$	-	-	-4.0	mA
			$I_{OL}$	-	-	4.0	mA
		High drive*3	$I_{OH}$	-	-	-20	mA
			$I_{OL}$	-	-	20	mA
	Other output pins*4	Low drive*1	$I_{OH}$	-	-	-2.0	mA
			$I_{OL}$	-	-	2.0	mA
		Middle drive*2	$I_{OH}$	-	-	-4.0	mA
			$I_{OL}$	-	-	4.0	mA
		High drive*3	$I_{OH}$	-	-	-16	mA
			$I_{OL}$	-	-	16	mA
	Permissible output current (max value per pin)	Ports P008 to P011, P201,P212	$I_{OH}$	-	-	-4.0	mA
			$I_{OL}$	-	-	4.0	mA
		Ports P014, P015, P213, P400, P401, P511, P512	$I_{OH}$	-	-	-8.0	mA
			$I_{OL}$	-	-	8.0	mA
Ports P402 to P404		Low drive*1	$I_{OH}$	-	-	-4.0	mA
			$I_{OL}$	-	-	4.0	mA
		Middle drive*2	$I_{OH}$	-	-	-8.0	mA
			$I_{OL}$	-	-	8.0	mA
Ports P205, P206, P407 to P415, P602, P708 to P713, P813, PA12 to PA15, PB01 (total 24 pins)		Low drive*1	$I_{OH}$	-	-	-4.0	mA
			$I_{OL}$	-	-	4.0	mA
		Middle drive*2	$I_{OH}$	-	-	-8.0	mA
			$I_{OL}$	-	-	8.0	mA
		High drive*3	$I_{OH}$	-	-	-40	mA
			$I_{OL}$	-	-	40	mA
Other output pins*4		Low drive*1	$I_{OH}$	-	-	-4.0	mA
			$I_{OL}$	-	-	4.0	mA
		Middle drive*2	$I_{OH}$	-	-	-8.0	mA
			$I_{OL}$	-	-	8.0	mA
		High drive*3	$I_{OH}$	-	-	-32	mA
			$I_{OL}$	-	-	32	mA
Permissible output current (max value total pins)		Maximum of all output pins	$\Sigma I_{OH}(\text{max})$	-	-	-80	mA
			$\Sigma I_{OL}(\text{max})$	-	-	80	mA

**Caution:** To protect the reliability of the MCU, the output current values should not exceed the values in this table. The average output current indicates the average value of current measured during 100  $\mu\text{s}$ .

- Note 1. This is the value when low driving ability is selected in the port drive capability bit in the PmnPFS register. The selected driving ability is retained in Deep Software Standby mode.
- Note 2. This is the value when middle driving ability is selected in the port drive capability bit in the PmnPFS register. The selected driving ability is retained in Deep Software Standby mode.
- Note 3. This is the value when high driving ability is selected in the port drive capability bit in the PmnPFS register. When the following ports are configured for high driving ability, they shift to middle driving ability during Deep Software Standby mode: P203 to P207, P407 to P415, P602, P708 to P713, P813, PA12 to PA15, PB01.
- Note 4. Except for P000 to P007, P200, which are input ports.

## 2.2.4 I/O $V_{OH}$ , $V_{OL}$ , and Other Characteristics

**Table 2.6 I/O  $V_{OH}$ ,  $V_{OL}$ , and other characteristics**

Item		Symbol	Min	Typ	Max	Unit	Test conditions
Output voltage	IIC*1	$V_{OL}$	-	-	0.4	V	$I_{OL} = 3.0 \text{ mA}$
		$V_{OL}$	-	-	0.6		$I_{OL} = 6.0 \text{ mA}$
	IIC*2	$V_{OL}$	-	-	0.4		$I_{OL} = 15.0 \text{ mA}$ (ICFER.FMPE = 1)
		$V_{OL}$	-	0.4	-		$I_{OL} = 20.0 \text{ mA}$ (ICFER.FMPE = 1)
	ETHERC	$V_{OH}$	$VCC - 0.5$	-	-		$I_{OH} = -1.0 \text{ mA}$
		$V_{OL}$	-	-	0.4		$I_{OL} = 1.0 \text{ mA}$
	Ports P205, P206, P407 to P415, P602, P708 to P713, P813, PA12 to PA15, PB01 (total 24 pins)*3	$V_{OH}$	$VCC - 1.0$	-	-		$I_{OH} = -20 \text{ mA}$ $VCC = 3.3 \text{ V}$
		$V_{OL}$	-	-	1.0		$I_{OL} = 20 \text{ mA}$ $VCC = 3.3 \text{ V}$
	Other output pins	$V_{OH}$	$VCC - 0.5$	-	-		$I_{OH} = -1.0 \text{ mA}$
		$V_{OL}$	-	-	0.5		$I_{OL} = 1.0 \text{ mA}$
Input leakage current	RES	$ I_{in} $	-	-	5.0	$\mu\text{A}$	$V_{in} = 0 \text{ V}$ $V_{in} = 5.5 \text{ V}$
	Ports P000 to P007, P200		-	-	1.0		$V_{in} = 0 \text{ V}$ $V_{in} = VCC$
Three-state leakage current (off state)	5V-tolerant ports	$ I_{TSil} $	-	-	5.0	$\mu\text{A}$	$V_{in} = 0 \text{ V}$ $V_{in} = 5.5 \text{ V}$
	Other ports (except for ports P000 to P007, P200)		-	-	1.0		$V_{in} = 0 \text{ V}$ $V_{in} = VCC$
Input pull-up MOS current	Ports P0 to PB (except for ports P000 to P007)	$I_p$	-300	-	-10	$\mu\text{A}$	$VCC = 2.7 \text{ to } 3.6 \text{ V}$ $V_{in} = 0 \text{ V}$
Input capacitance	USB_DP, USB_DM, and ports P003, P007, P014, P015, P400, P415, P401, P511, P512	$C_{in}$	-	-	16	$\text{pF}$	$V_{bias} = 0 \text{ V}$ $V_{amp} = 20 \text{ mV}$ $f = 1 \text{ MHz}$ $T_a = 25^\circ\text{C}$
	Other input pins		-	-	8		

Note 1. SCL0\_B, SDA0\_B, SCL1\_A, SDA1\_A, SCL1\_B, SDA1\_B, SCL2, SDA2 (total 8 pins).

Note 2. SCL0\_A, SDA0\_A (total 2 pins).

Note 3. This is the value when high driving ability is selected in the port drive capability bit in the PmnPFS register. Even when high driving ability is selected,  $I_{OH}$  and  $I_{OL}$  shift to middle driving ability during Deep Software Standby mode.

## 2.2.5 Operating and Standby Current

Table 2.7 Operating and standby current (1/2)

Item	Symbol	LDO mode			DCDC mode			Unit	Test conditions			
		Min	Typ	Max	Min	Typ	Max					
Supply current*1	High-speed mode	Maximum*2		-	-	330	-	-	140	mA	ICLK = 240 MHz PCLKA = 120 MHz*6 PCLKB = 60 MHz PCLKC = 60 MHz PCLKD = 120 MHz FCLK = 60 MHz BCLK = 120 MHz	
		CoreMark®*4		-	45	-	-	24	-			
		Normal mode*3	All peripheral clocks enabled, code executing from flash		-	75	-	-	38			-
			All peripheral clocks disabled, code executing from flash		-	32	-	-	18			-
		Sleep mode*4		-	25	150	-	15	75			
		Increase during BGO operation	Data flash P/E		-	7	-	-	7			-
			Code flash P/E		-	10	-	-	10			-
		Low-speed mode*4		-	4.4	-	-	3	-			ICLK = 1 MHz
		Subosc-speed mode*4		-	3	-	-	2	-			ICLK = 32.768 kHz
		Software Standby mode		-	2.4	110	-	1.2	55			-
	Deep Software Standby mode	Power supplied to Standby SRAM and USB resume detecting unit		-	37	255	-	37	255	μA	VBAT ≠ VCC*7	
				-	37	285	-	37	285	μA	VBAT = VCC	
		Power not supplied to SRAM or USB resume detecting unit	Power-on reset circuit low-power function disabled		-	25	50	-	25	50	μA	VBAT ≠ VCC*7
			Power-on reset circuit low-power function enabled		-	25	80	-	25	80	μA	VBAT = VCC
		Increase when the RTC and AGT are operating	When the low-speed on-chip oscillator (LOCO) is in use		-	16	35	-	16	35	μA	VBAT ≠ VCC*7
			When a crystal oscillator for low clock loads is in use		-	16	65	-	16	65	μA	VBAT = VCC
			When a crystal oscillator for standard clock loads is in use		-	9	-	-	9	-	μA	-
RTC operating while VCC is off (with the battery backup function, only the RTC and sub-clock oscillator operate)		When a crystal oscillator for low clock loads is in use		-	1.0	-	-	1.0	-	μA	-	
		When a crystal oscillator for standard clock loads is in use		-	3.0	-	-	3.0	-	μA	-	
				-	0.9	-	-	0.9	-	μA	V <sub>BATT</sub> = 2.0 V, V <sub>C</sub> = 0 V	
Analog power supply current	During 12-bit A/D conversion		-	0.8	1.1	-	0.8	1.1	mA	-		
	During 12-bit A/D conversion with S/H amp		-	2.3	3.3	-	2.3	3.3	mA	-		
	PGA (1ch)		-	1	3	-	1	3	mA	-		
	ACMPHS (1unit)		-	100	150	-	100	150	μA	AVCC ≥ 2.7 V		
	Temperature sensor		-	0.1	0.2	-	0.1	0.2	mA	-		
	During D/A conversion (per unit)	Without AMP output		-	0.1	0.2	-	0.1	0.2	mA	-	
		With AMP output		-	0.5	0.8	-	0.5	0.8	mA	-	
	Waiting for A/D, D/A conversion (all units)		-	0.9	1.6	-	0.9	1.6	mA	-		
	ADC12, DAC12 in standby modes (all units)		-	2	6	-	2	6	μA	-		
	Reference power supply current (VREFH0)	During 12-bit A/D conversion (unit 0)		-	70	120	-	70	120	μA	-	
Waiting for 12-bit A/D conversion (unit 0)		-	0.07	0.4	-	0.07	0.4	μA	-			
ADC12 in standby modes (unit 0)		-	0.07	0.2	-	0.07	0.2	μA	-			



**Table 2.7 Operating and standby current (2/2)**

Item	Symbol		LDO mode			DCDC mode			Unit	Test conditions			
			Min	Typ	Max	Min	Typ	Max					
Reference power supply current (VREFH)	During 12-bit A/D conversion (unit 1)		A <sub>IREFH</sub>	-	70	120	-	70	120	μA	-		
	During D/A conversion (per unit)	Without AMP output		-	0.24	0.4	-	0.24	0.4	mA	-		
		With AMP output		-	0.1	0.2	-	0.1	0.2	mA	-		
	Waiting for 12-bit A/D (unit 1), D/A (all units) conversion			-	0.07	0.4	-	0.07	0.4	μA	-		
	ADC12 unit 1 in standby modes			-	0.07	0.2	-	0.07	0.2	μA	-		
USB operating current	Low speed	USB	I <sub>CCUSBLS</sub>	-	3.5	6.5	-	3.5	6.5	mA	VCC_USB		
		USBHS		-	10.5	13.5	-	10.5	13.5	mA	VCC_USBHS = AVCC_USBHS (PHYSET.HSEB = 0)		
		USBHS		-	2.8	3.6	-	2.8	3.6	mA	VCC_USBHS = AVCC_USBHS (PHYSET.HSEB = 1)		
	Full speed	USB		I <sub>CCUSBFS</sub>	-	4.0	10.0	-	4.0	10.0	mA	VCC_USB	
		USBHS			-	14	22	-	14	22	mA	VCC_USBHS = AVCC_USBHS (PHYSET.HSEB = 0)	
		USBHS			-	6.5	13.0	-	6.5	13.0	mA	VCC_USBHS = AVCC_USBHS (PHYSET.HSEB = 1)	
	High speed	USBHS			I <sub>CCUSBHS</sub>	-	50	65	-	50	65	mA	VCC_USBHS = AVCC_USBHS
	Standby mode (direct power down)	USBHS			I <sub>CCUSBSTBY</sub>	-	0.5	3.0	-	0.5	3.0	μA	VCC_USBHS = AVCC_USBHS

Note 1. Supply current values are with all output pins unloaded and all input pull-up MOS transistors in the off state.

Note 2. Measured with clocks supplied to the peripheral functions. This does not include the BGO operation.

Note 3. This does not include the BGO operation.

Note 4. Supply of the clock signal to peripherals is stopped in this state. This does not include the BGO operation.

Note 5. When V<sub>BATT</sub> is used.

Note 6. When using ETHERC, PCLKA frequency is:

$$12.5\text{MHz} \leq \text{PCLKA} \leq 120\text{MHz}$$

Note 7. When VCC is < VDET<sub>BATT</sub> and > (V<sub>BATT</sub> + 0.6 V), the injected current connects from the VCC to the V<sub>BATT</sub> pin through an internal diode.

## 2.2.6 VCC Rise and Fall Gradient and Ripple Frequency

**Table 2.8 Rise and fall gradient characteristics**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
VCC rising gradient	SrVCC	0.0084	-	20	ms/V	-
VCC falling gradient*1	SfVCC	0.0084	-	-	ms/V	-

Note 1. This applies when V<sub>BATT</sub> is used.

**Table 2.9 Rise and fall gradient and ripple frequency characteristics**

The ripple voltage must meet the allowable ripple frequency  $f_{r(VCC)}$  within the range between the VCC upper limit (3.6 V) and lower limit (2.7 V). When the VCC change exceeds VCC ±10%, the allowable voltage change rising and falling gradient dt/dVCC must be met.

Item	Symbol	Min	Typ	Max	Unit	Test conditions
Allowable ripple frequency	$f_{r(VCC)}$	-	-	10	kHz	Figure 2.2 $V_{r(VCC)} \leq VCC \times 0.2$
		-	-	1	MHz	Figure 2.2 $V_{r(VCC)} \leq VCC \times 0.08$
		-	-	10	MHz	Figure 2.2 $V_{r(VCC)} \leq VCC \times 0.06$
Allowable voltage change rising and falling gradient	dt/dVCC	1.0	-	-	ms/V	When VCC change exceeds VCC ±10%

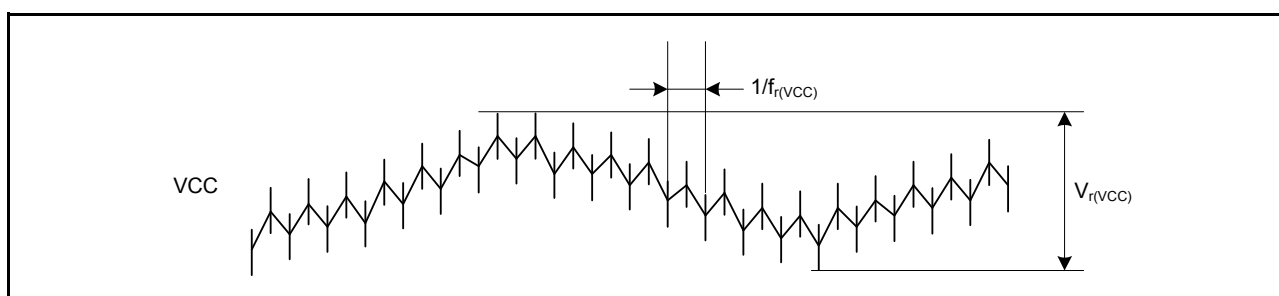


Figure 2.2 Ripple waveform

## 2.3 AC Characteristics

### 2.3.1 Frequency

Table 2.10 Operation frequency value in high-speed mode

Item	Symbol	Min	Typ	Max	Unit
Operation frequency	System clock (ICLK)*2	-	-	240	MHz
	Peripheral module clock (PCLKA)*2	-	-	120	
	Peripheral module clock (PCLKB)*2	-	-	60	
	Peripheral module clock (PCLKC)*2	_*3	-	60	
	Peripheral module clock (PCLKD)*2	-	-	120	
	Flash interface clock (FCLK)*2	_*1	-	60	
	External bus clock (BCLK)*2	-	-	120	
	EBCLK pin output	-	-	60	
	SDCLK pin output	-	-	120	

Note 1. FCLK must run at a frequency of at least 4 MHz when programming or erasing the flash memory.

Note 2. See section 9, Clock Generation Circuit in User's Manual for the relationship between the ICLK, PCLKA, PCLKB, PCLKC, PCLKD, FCLK, and BCLK frequencies.

Note 3. When the ADC12 is used, the PCLKC frequency must be at least 1 MHz.

Table 2.11 Operation frequency value in low-speed mode

Item	Symbol	Min	Typ	Max	Unit
Operation frequency	System clock (ICLK)*2	-	-	1	MHz
	Peripheral module clock (PCLKA)*2	-	-	1	
	Peripheral module clock (PCLKB)*2	-	-	1	
	Peripheral module clock (PCLKC)*2,*3	_*3	-	1	
	Peripheral module clock (PCLKD)*2	-	-	1	
	Flash interface clock (FCLK)*1,*2	-	-	1	
	External bus clock (BCLK)	-	-	1	
	EBCLK pin output	-	-	1	

Note 1. Programming or erasing the flash memory is disabled in low-speed mode.

Note 2. See section 9, Clock Generation Circuit in User's Manual for the relationship between the ICLK, PCLKA, PCLKB, PCLKC, PCLKD, FCLK, and BCLK frequencies.

Note 3. When the ADC12 is used, the PCLKC frequency must be set to at least 1 MHz.

**Table 2.12 Operation frequency value in Subosc-speed mode**

Item	Symbol	Min	Typ	Max	Unit	
Operation frequency	System clock (ICLK)*2	f	29.4	-	36.1	kHz
	Peripheral module clock (PCLKA)*2		-	-	36.1	
	Peripheral module clock (PCLKB)*2		-	-	36.1	
	Peripheral module clock (PCLKC)*2,*3		-	-	36.1	
	Peripheral module clock (PCLKD)*2		-	-	36.1	
	Flash interface clock (FCLK)*1, *2		29.4	-	36.1	
	External bus clock (BCLK)*2		-	-	36.1	
	EBCLK pin output		-	-	36.1	

Note 1. Programming or erasing the flash memory is disable in Subosc-speed mode.

Note 2. See section 9, Clock Generation Circuit in User's Manual for the relationship between the ICLK, PCLKA, PCLKB, PCLKC, PCLKD, FCLK, and BCLK frequencies.

Note 3. The ADC12 cannot be used.

### 2.3.2 Clock Timing

**Table 2.13 Clock timing except for sub-clock oscillator (1/2)**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
EBCLK pin output cycle time	$t_{Bcyc}$	16.6	-	-	ns	Figure 2.3
EBCLK pin output high pulse width	$t_{CH}$	3.3	-	-	ns	
EBCLK pin output low pulse width	$t_{CL}$	3.3	-	-	ns	
EBCLK pin output rise time	$t_{Cr}$	-	-	5.0	ns	
EBCLK pin output fall time	$t_{Cf}$	-	-	5.0	ns	
SDCLK pin output cycle time	$t_{SDcyc}$	8.33	-	-	ns	
SDCLK pin output high pulse width	$t_{CH}$	1.0	-	-	ns	
SDCLK pin output low pulse width	$t_{CL}$	1.0	-	-	ns	
SDCLK pin output rise time	$t_{Cr}$	-	-	3.0	ns	
SDCLK pin output fall time	$t_{Cf}$	-	-	3.0	ns	
EXTAL external clock input cycle time	$t_{EXcyc}$	41.66	-	-	ns	Figure 2.4
EXTAL external clock input high pulse width	$t_{EXH}$	15.83	-	-	ns	
EXTAL external clock input low pulse width	$t_{EXL}$	15.83	-	-	ns	
EXTAL external clock rise time	$t_{EXr}$	-	-	5.0	ns	
EXTAL external clock fall time	$t_{EXf}$	-	-	5.0	ns	
Main clock oscillator frequency	$f_{MAIN}$	8	-	24	MHz	-
Main clock oscillation stabilization wait time (crystal) *1	$t_{MAINOSCWT}$	-	-	-*1	ms	Figure 2.5
LOCO clock oscillation frequency	$f_{LOCO}$	29.4912	32.768	36.0448	kHz	-
LOCO clock oscillation stabilization wait time	$t_{LOCOWT}$	-	-	60.4	$\mu$ s	Figure 2.6
ILOCO clock oscillation frequency	$f_{ILOCO}$	13.5	15	16.5	kHz	-
MOCO clock oscillation frequency	$F_{MOCO}$	7.2	8	8.8	MHz	-
MOCO clock oscillation stabilization wait time	$t_{MOCOWT}$	-	-	15.0	$\mu$ s	-

**Table 2.13 Clock timing except for sub-clock oscillator (2/2)**

Item		Symbol	Min	Typ	Max	Unit	Test conditions
HOCO clock oscillator oscillation frequency	Without FLL	$f_{\text{HOCO16}}$	15.61	16	16.39	MHz	$-20 \leq T_a \leq 105^\circ\text{C}$
		$f_{\text{HOCO18}}$	17.56	18	18.44		
		$f_{\text{HOCO20}}$	19.52	20	20.48		
		$f_{\text{HOCO16}}$	15.52	16	16.48		
		$f_{\text{HOCO18}}$	17.46	18	18.54		
		$f_{\text{HOCO20}}$	19.40	20	20.60		
	With FLL	$f_{\text{HOCO16}}$	15.91	16	16.09		$-40 \leq T_a \leq -20^\circ\text{C}$
		$f_{\text{HOCO18}}$	17.90	18	18.10		
		$f_{\text{HOCO20}}$	19.89	20	20.11		
HOCO clock oscillation stabilization wait time *2		$t_{\text{HOCOWT}}$	-	-	64.7	$\mu\text{s}$	-
FLL stabilization wait time		$t_{\text{FLLWT}}$	-	-	3	ms	-
PLL clock frequency		$f_{\text{PLL}}$	120	-	240	MHz	-
PLL clock oscillation stabilization wait time		$t_{\text{PLLWT}}$	-	-	174.9	$\mu\text{s}$	Figure 2.7

Note 1. When setting up the main clock oscillator, ask the oscillator manufacturer for an oscillation evaluation and use the results as the recommended oscillation stabilization time. Set the MOSCWTCR register to a value equal to or greater than the recommended value.

After changing the setting in the MOSCCR.MOSTP bit to start main clock operation, read the OSCSF.MOSCSF flag to confirm that it is 1, and then start using the main clock oscillator.

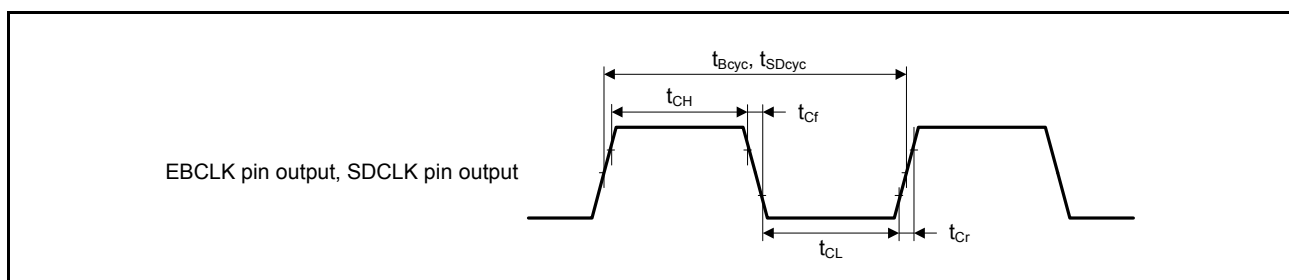
Note 2. This is the time from release from reset state until the HOCO oscillation frequency ( $f_{\text{HOCO}}$ ) reaches the range for guaranteed operation.

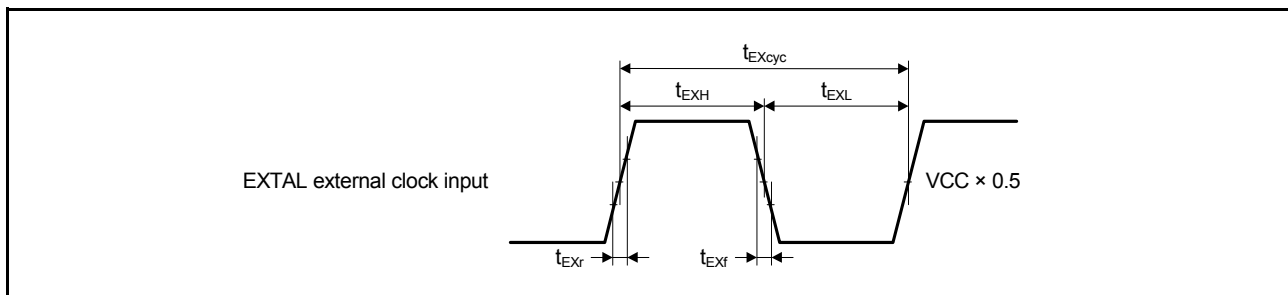
**Table 2.14 Clock timing for the sub-clock oscillator**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
Sub-clock frequency	$f_{\text{SUB}}$	-	32.768	-	kHz	-
Sub-clock oscillation stabilization wait time	$t_{\text{SUBOSCWT}}$	-	-	-*1	s	-

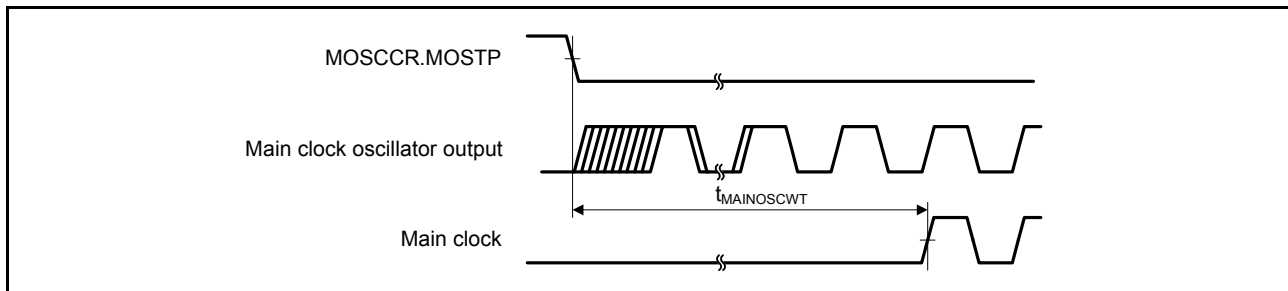
Note 1. When setting up the sub-clock oscillator, ask the oscillator manufacturer for an oscillation evaluation and use the results as the recommended oscillation stabilization time.

After changing the setting in the SOSCCR.SOSTP bit to start sub-clock operation, only start using the sub-clock oscillator after the sub-clock oscillation stabilization time elapses with an adequate margin. Two times the value shown is recommended.

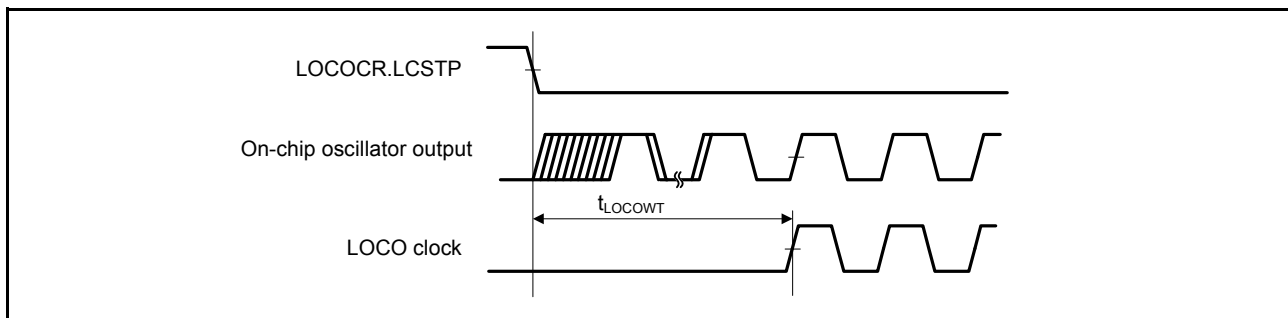
**Figure 2.3 EBCLK and SDCLK output timing**



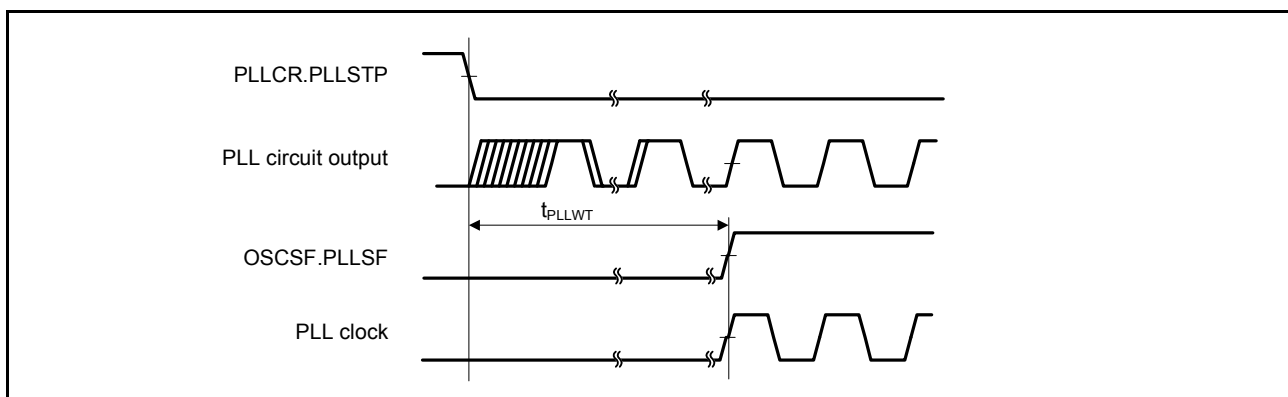
**Figure 2.4** EXTAL external clock input timing



**Figure 2.5** Main clock oscillation start timing



**Figure 2.6** LOCO clock oscillation start timing



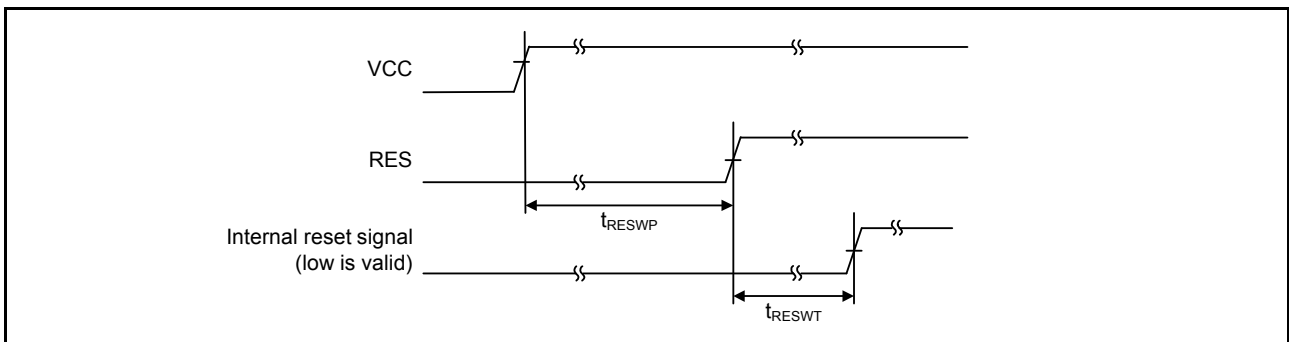
**Figure 2.7** PLL clock oscillation start timing

Note: Only operate the PLL is operated after main clock oscillation has stabilized.

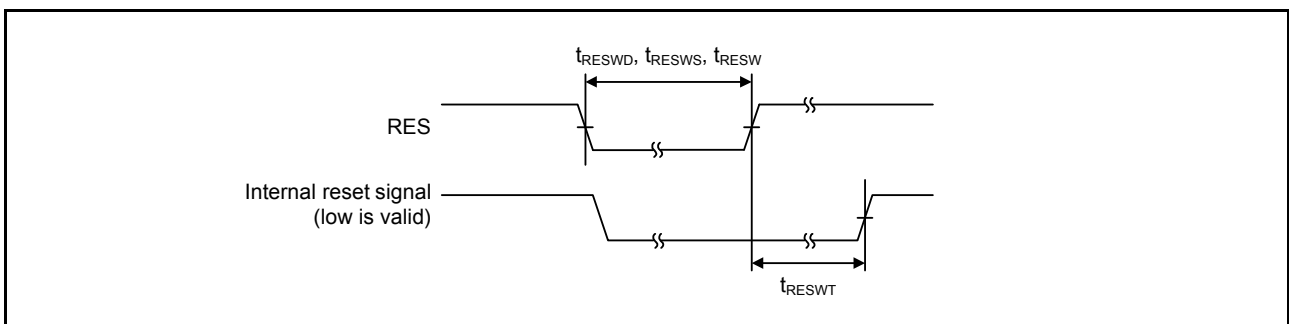
### 2.3.3 Reset Timing

**Table 2.15 Reset timing**

Item			Symbol	Min	Typ	Max	Unit	Test conditions
RES pulse width	Power-on	LDO mode	$t_{RESWP}$	1	-	-	ms	Figure 2.8
		DCDC mode		1.5	-	-	ms	
	Deep Software Standby mode		$t_{RESWD}$	0.6	-	-	ms	Figure 2.9
	Software Standby mode, Subosc-speed mode		$t_{RESWS}$	0.3	-	-	ms	
	All other		$t_{RESW}$	200	-	-	$\mu$ s	
Wait time after RES cancellation			$t_{RESWT}$	-	-	33.4	$\mu$ s	Figure 2.8
Wait time after internal reset cancellation (IWDT reset, WDT reset, software reset, SRAM parity error reset, SRAM ECC error reset, bus master MPU error reset, bus slave MPU error reset, stack pointer error reset)			$t_{RESW2}$	-	-	390	$\mu$ s	-



**Figure 2.8 Power-on reset timing**



**Figure 2.9 Reset input timing**

## 2.3.4 Wakeup Timing and Duration

Table 2.16 Timing of recovery from low-power modes and duration

Item			Symbol	Min	Typ	Max	Unit	Test conditions
Recovery time from Software Standby mode*1	Crystal resonator connected to main clock oscillator	System clock source is main clock oscillator*2	t <sub>SBYMC</sub>	-	-	2.8	ms	Figure 2.10 The division ratio of all oscillators is 1.
		System clock source is PLL with main clock oscillator*3	t <sub>SBYPC</sub>	-	-	3.2	ms	
	External clock input to main clock oscillator	System clock source is main clock oscillator*4	t <sub>SBYEX</sub>	-	-	280	μs	
		System clock source is PLL with main clock oscillator*5	t <sub>SBYPE</sub>	-	-	700	μs	
	System clock source is sub-clock oscillator*8		t <sub>SBYSC</sub>	-	-	1.3	ms	
	System clock source is LOCO*8		t <sub>SBYLO</sub>	-	-	1.4	ms	
	System clock source is HOCO clock oscillator*6		t <sub>SBYHO</sub>	-	-	300	μs	
	System clock source is MOCO clock oscillator*7		t <sub>SBYMO</sub>	-	-	300	μs	
Recovery time from Deep Software Standby mode			t <sub>DSBY</sub>	-	-	1.0	ms	Figure 2.11
Wait time after cancellation of Deep Software Standby mode			t <sub>DSBYWT</sub>	31	-	32	t <sub>cyc</sub>	
Recovery time from Software Standby mode to Snooze	High-speed mode when system clock source is HOCO (20 MHz)		t <sub>SNZ</sub>	-	-	68	μs	-
	High-speed mode when system clock source is MOCO (8 MHz)		t <sub>SNZ</sub>	-	-	14*9	μs	
Normal mode duration*10	System clock source is main clock oscillator		t <sub>NML</sub>	-*11	-	-	t <sub>cycmosc</sub>	Figure 2.10
	System clock source is PLL with main clock oscillator							

Note 1. The recovery time is determined by the system clock source. When multiple oscillators are active, the recovery time can be determined with the following equation:

Total recovery time = recovery time for an oscillator as the system clock source + the longest oscillation stabilization time of any oscillators requiring longer stabilization times than the system clock source + 2 LOCO cycles (when LOCO is operating) + 3 SOSC cycles (when Subosc is oscillating and MSTPC0 = 0 (CAC module stop)).

Note 2. When the frequency of the crystal is 24 MHz (Main Clock Oscillator Wait Control Register (MOSCWTCR) is set to 05h). For other settings (MOSCWTCR is set to Xh), the recovery time can be determined with the following equation:

$$t_{SBYMC} (\text{MOSCWTCR} = \text{Xh}) = t_{SBYMC} (\text{MOSCWTCR} = 05\text{h}) + (t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = \text{Xh}) - t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = 05\text{h}))$$

Note 3. When the frequency of PLL is 240 MHz (Main Clock Oscillator Wait Control Register (MOSCWTCR) is set to 05h). For other settings (MOSCWTCR is set to Xh), the recovery time can be determined with the following equation:

$$t_{SBYMC} (\text{MOSCWTCR} = \text{Xh}) = t_{SBYMC} (\text{MOSCWTCR} = 05\text{h}) + (t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = \text{Xh}) - t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = 05\text{h}))$$

Note 4. When the frequency of the external clock is 24 MHz (Main Clock Oscillator Wait Control Register (MOSCWTCR) is set to 00h). For other settings (MOSCWTCR is set to Xh), the recovery time can be determined with the following equation:

$$t_{SBYMC} (\text{MOSCWTCR} = \text{Xh}) = t_{SBYMC} (\text{MOSCWTCR} = 00\text{h}) + (t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = \text{Xh}) - t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = 00\text{h}))$$

Note 5. When the frequency of PLL is 240 MHz (Main Clock Oscillator Wait Control Register (MOSCWTCR) is set to 00h). For other settings (MOSCWTCR is set to Xh), the recovery time can be determined with the following

equation:

$$t_{\text{SBYMC}} (\text{MOSCWTCR} = \text{Xh}) = t_{\text{SBYMC}} (\text{MOSCWTCR} = \text{00h}) + (t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = \text{Xh}) - t_{\text{MAINOSCWT}} (\text{MOSCWTCR} = \text{00h}))$$

Note 6. The HOCO frequency is 20 MHz.

Note 7. The MOCO frequency is 8 MHz.

Note 8. In Subosc-speed mode, the sub-clock oscillator or LOCO continues oscillating in Software Standby mode.

Note 9. When the SNZCR.RXDREQEN bit is set to 0, 86  $\mu\text{s}$  is added as the power supply recovery time.

Note 10. This defines the duration of Normal mode after a transition from Snooze to Normal mode.

The following cases are valid uses of the main clock oscillator:

- The crystal resonator is connected to main clock oscillator
- The external clock is input to main clock oscillator.

The following cases are excluded:

- The main clock resonator is not connected to the system clock source
- Transition is made from Software Standby to Normal mode.

Note 11. The same value as set in MOSCWTCR.MSTS[3:0]. Duration of Normal mode must be longer than the main clock oscillator wait time.

MOSCWTCR: Main Clock Oscillator Wait Control Register

$t_{\text{cycmosc}}$ : Main clock oscillator frequency cycle.



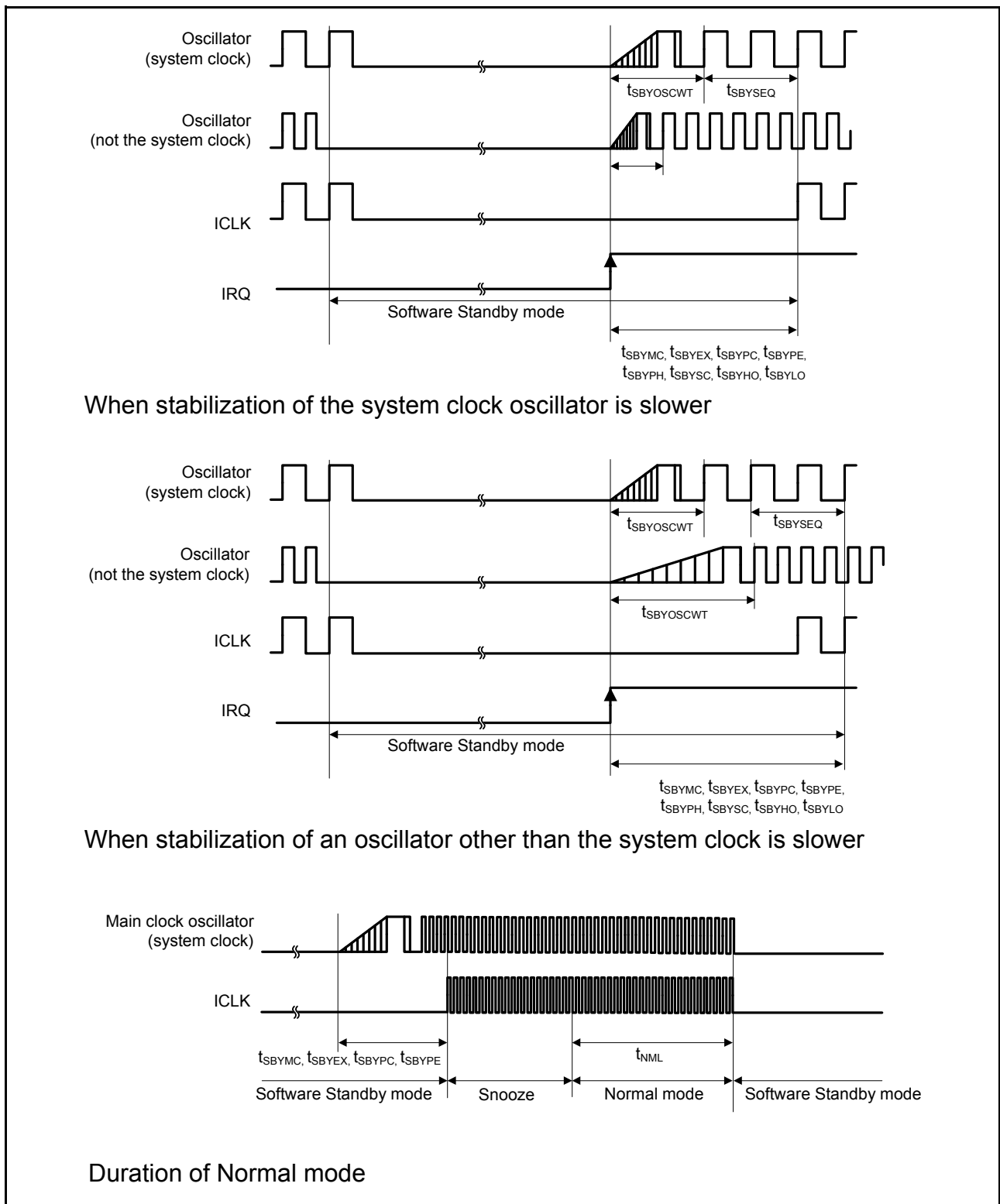


Figure 2.10 Software Standby mode cancellation timing and duration

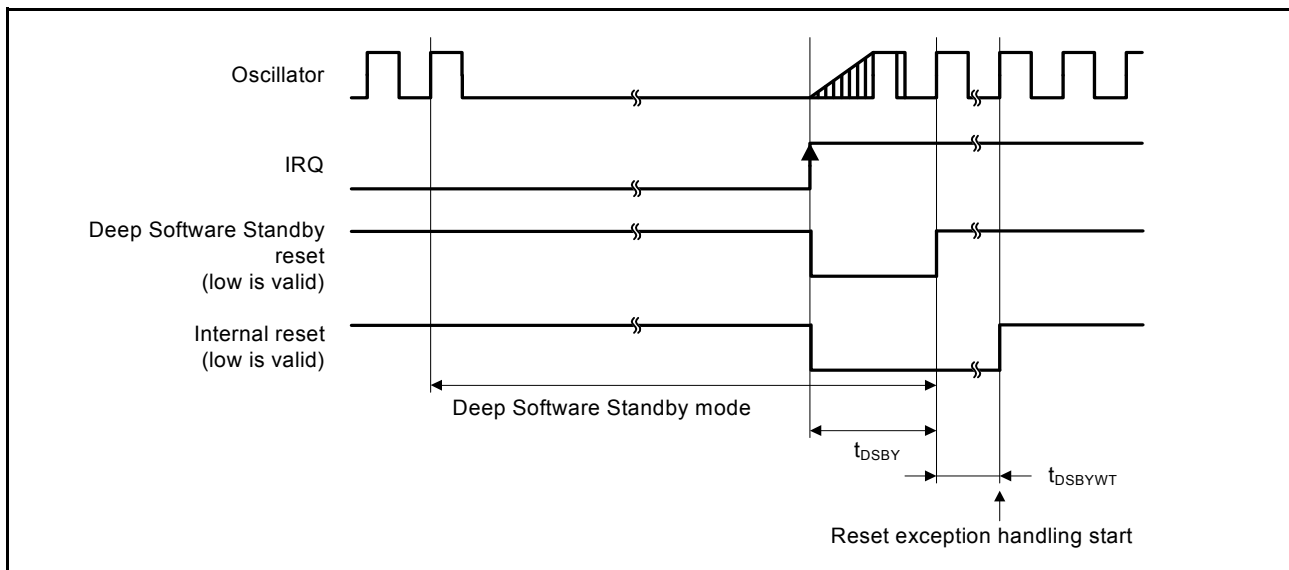


Figure 2.11 Deep Software Standby mode cancellation timing

### 2.3.5 NMI and IRQ Noise Filter

Table 2.17 NMI and IRQ noise filter

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
NMI pulse width	$t_{\text{NMIW}}$	200	-	-	ns	NMI digital filter disabled	
		$t_{\text{Pcyc}} \times 2^{*1}$	-	-			$t_{\text{Pcyc}} \times 2 \leq 200$ ns
		200	-	-		NMI digital filter enabled	$t_{\text{NMICK}} \times 3 \leq 200$ ns
		$t_{\text{NMICK}} \times 3.5^{*2}$	-	-			$t_{\text{NMICK}} \times 3 > 200$ ns
IRQ pulse width	$t_{\text{IRQW}}$	200	-	-	ns	IRQ digital filter disabled	
		$t_{\text{Pcyc}} \times 2^{*1}$	-	-			$t_{\text{Pcyc}} \times 2 \leq 200$ ns
		200	-	-		IRQ digital filter enabled	$t_{\text{IRQCK}} \times 3 \leq 200$ ns
		$t_{\text{IRQCK}} \times 3.5^{*3}$	-	-			$t_{\text{IRQCK}} \times 3 > 200$ ns

Note: 200 ns minimum in Software Standby mode.

Note 1.  $t_{\text{Pcyc}}$  indicates the PCLKB cycle.

Note 2.  $t_{\text{NMICK}}$  indicates the cycle of the NMI digital filter sampling clock.

Note 3.  $t_{\text{IRQCK}}$  indicates the cycle of the IRQi digital filter sampling clock.

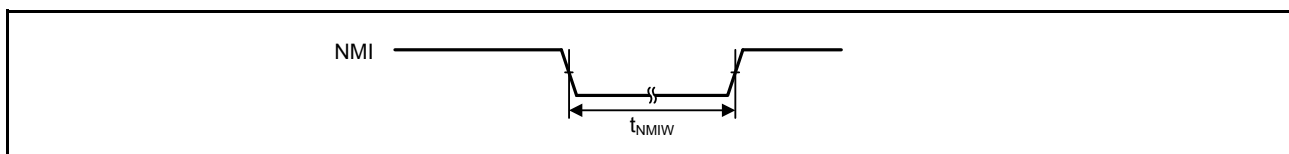


Figure 2.12 NMI interrupt input timing

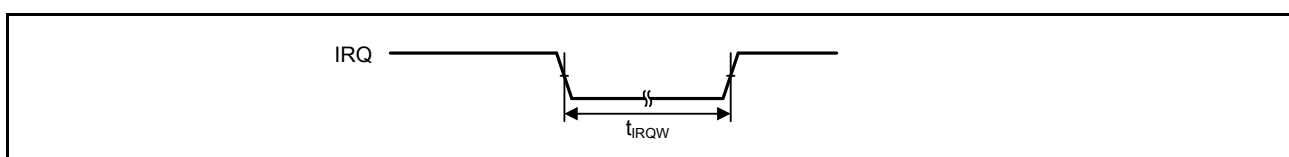


Figure 2.13 IRQ interrupt input timing

### 2.3.6 Bus Timing

**Table 2.18 Bus timing**

Condition 1: When using the CS area controller (CSC).

BCLK = 8 to 60 MHz

VCC = AVCC0 = VCC\_USB = VBATT = 2.7 to 3.6 V, VREFH/VREFH0 = 2.7 V to AVCC0,

VCC\_USBHS = AVCC\_USBHS = 3.0 to 3.6 V

Output load conditions: VOH = VCC × 0.5, VOL = VCC × 0.5, C = 30 pF

EBCLK: High drive output is selected in the port drive capability bit in the PmnPFS register.

Others: Middle drive output is selected in the port drive capability bit in the PmnPFS register.

Condition 2: When using the SDRAM area controller (SDRAMC).

BCLK = SDCLK = 8 to 120 MHz

VCC = AVCC0 = VCC\_USB = VBATT = 3.0 to 3.6 V, VREFH/VREFH0 = 3.0 V to AVCC0,

VCC\_USBHS = AVCC\_USBHS = 3.0 to 3.6 V

Output load conditions: VOH = VCC × 0.5, VOL = VCC × 0.5, C = 15 pF

High drive output is selected in the port drive capability bit in the PmnPFS register.

Condition 3: When using the SDRAM area controller (SDRAMC) and CS area controller (CSC) simultaneously.

BCLK = SDCLK = 8 to 60 MHz

VCC = AVCC0 = VCC\_USB = VBATT = 3.0 to 3.6 V, VREFH/VREFH0 = 3.0 V to AVCC0,

VCC\_USBHS = AVCC\_USBHS = 3.0 to 3.6 V

Output load conditions: VOH = VCC × 0.5, VOL = VCC × 0.5, C = 15 pF

High drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Max	Unit	Test conditions
Address delay	$t_{AD}$	-	12.5	ns	Figure 2.14 to Figure 2.17
Byte control delay	$t_{BCD}$	-	12.5	ns	
CS delay	$t_{CSD}$	-	12.5	ns	
RD delay	$t_{RSD}$	-	12.5	ns	
Read data setup time	$t_{RDS}$	12.5	-	ns	
Read data hold time	$t_{RDH}$	0	-	ns	
WR/WRn delay	$t_{WRD}$	-	12.5	ns	
Write data delay	$t_{WDD}$	-	12.5	ns	
Write data hold time	$t_{WDH}$	0	-	ns	
WAIT setup time	$t_{WTS}$	12.5	-	ns	
WAIT hold time	$t_{WTH}$	0	-	ns	
Address delay 2 (SDRAM)	$t_{AD2}$	0.8	6.8	ns	Figure 2.19 to Figure 2.25
CS delay 2 (SDRAM)	$t_{CSD2}$	0.8	6.8	ns	
DQM delay (SDRAM)	$t_{DQMD}$	0.8	6.8	ns	
CKE delay (SDRAM)	$t_{CKED}$	0.8	6.8	ns	
Read data setup time 2 (SDRAM)	$t_{RDS2}$	2.9	-	ns	
Read data hold time 2 (SDRAM)	$t_{RDH2}$	1.5	-	ns	
Write data delay 2 (SDRAM)	$t_{WDD2}$	-	6.8	ns	
Write data hold time 2 (SDRAM)	$t_{WDH2}$	0.8	-	ns	
WE delay (SDRAM)	$t_{WED}$	0.8	6.8	ns	
RAS delay (SDRAM)	$t_{RASD}$	0.8	6.8	ns	
CAS delay (SDRAM)	$t_{CASD}$	0.8	6.8	ns	

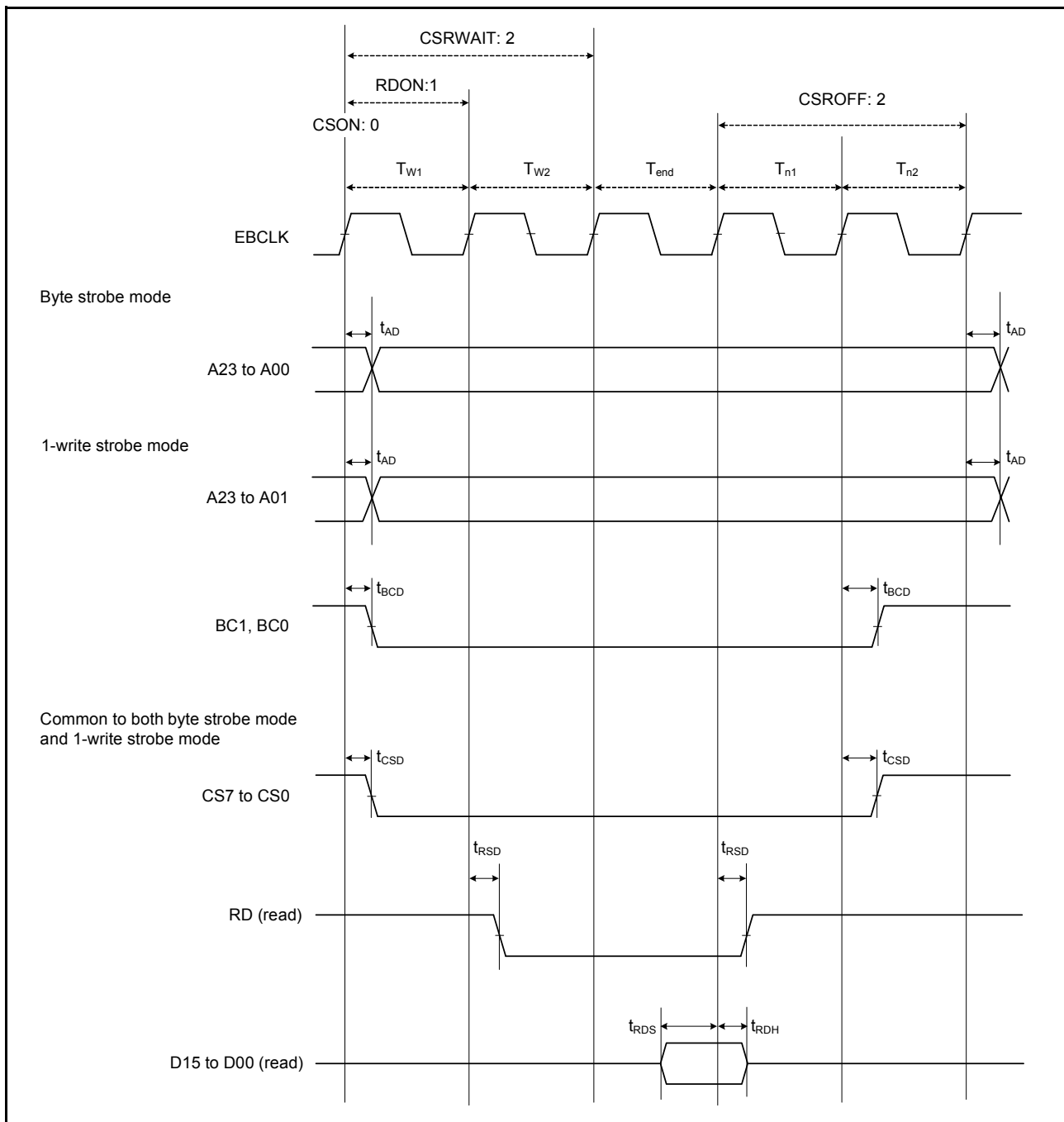


Figure 2.14 External bus timing for normal read cycle with bus clock synchronized

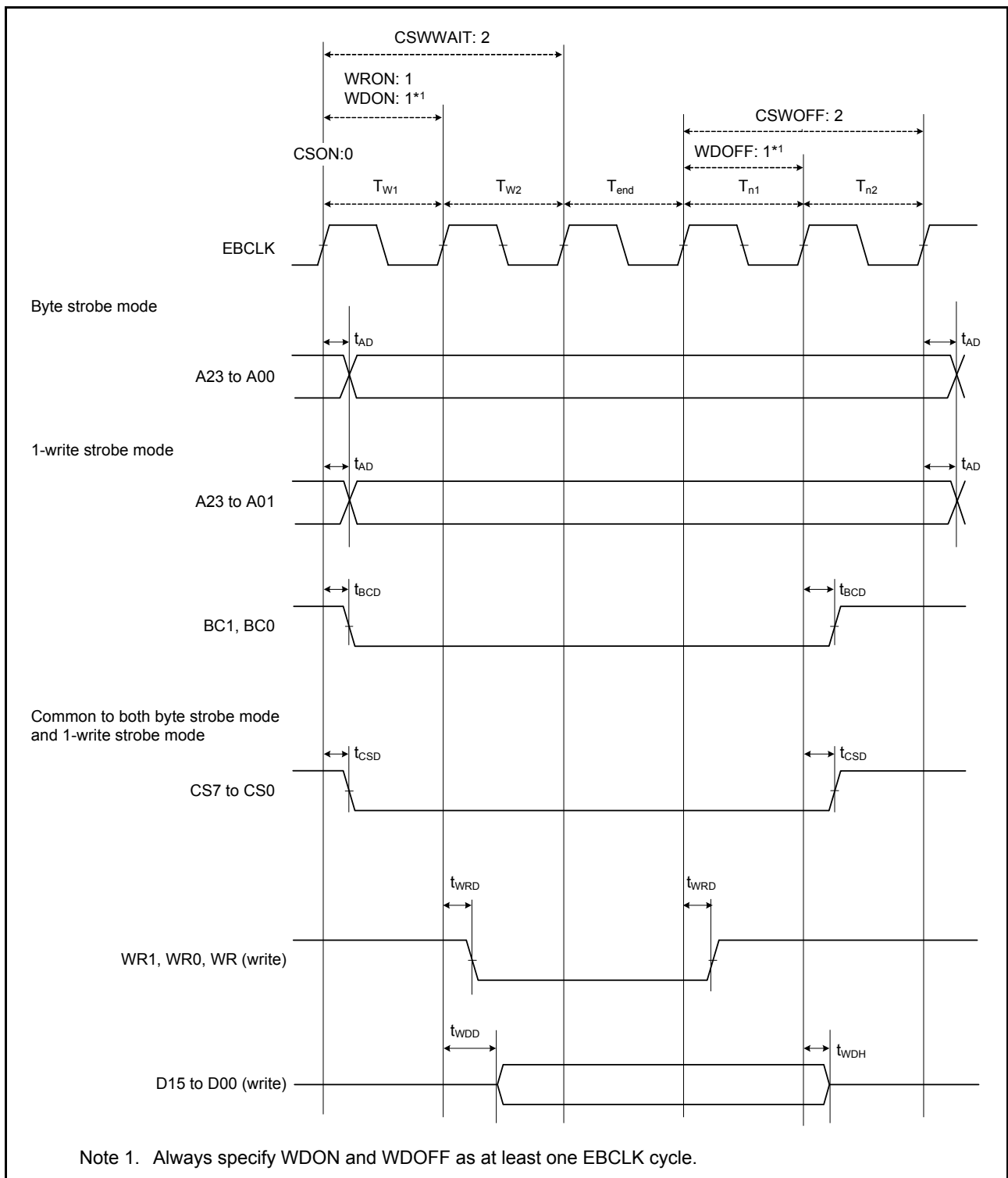


Figure 2.15 External bus timing for normal write cycle with bus clock synchronized

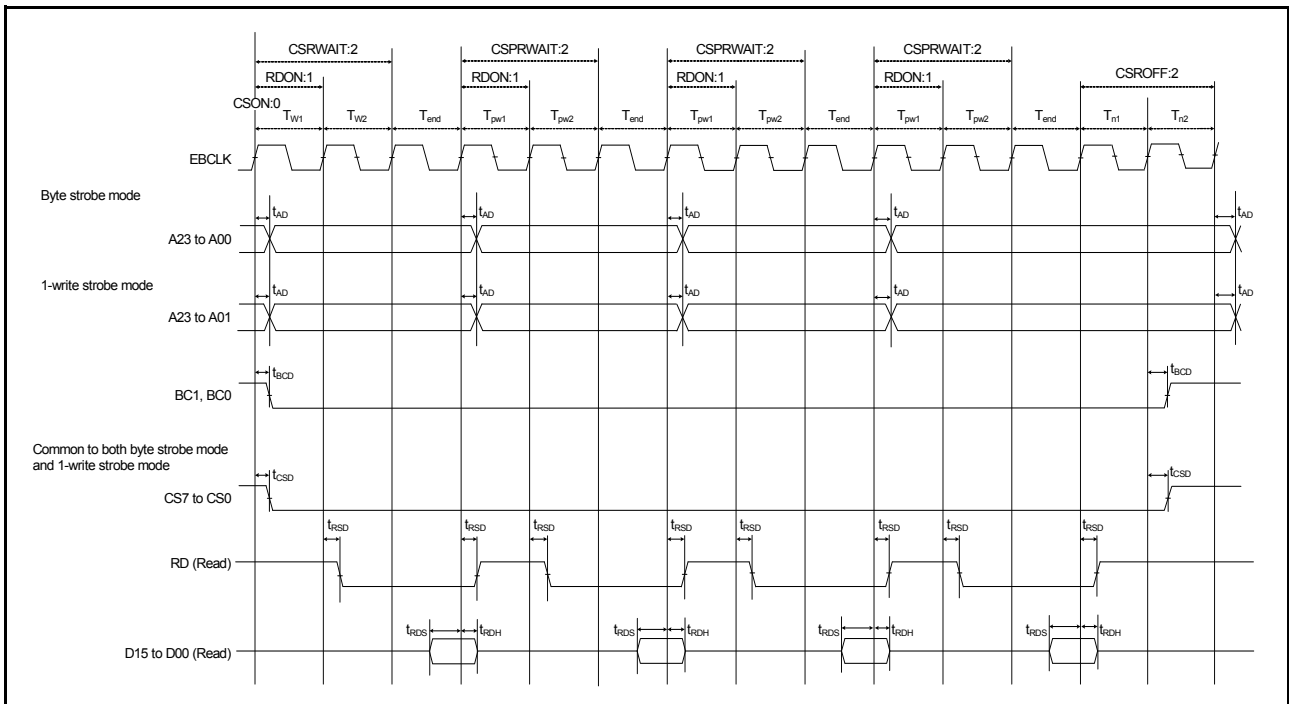


Figure 2.16 External bus timing for page read cycle with bus clock synchronized

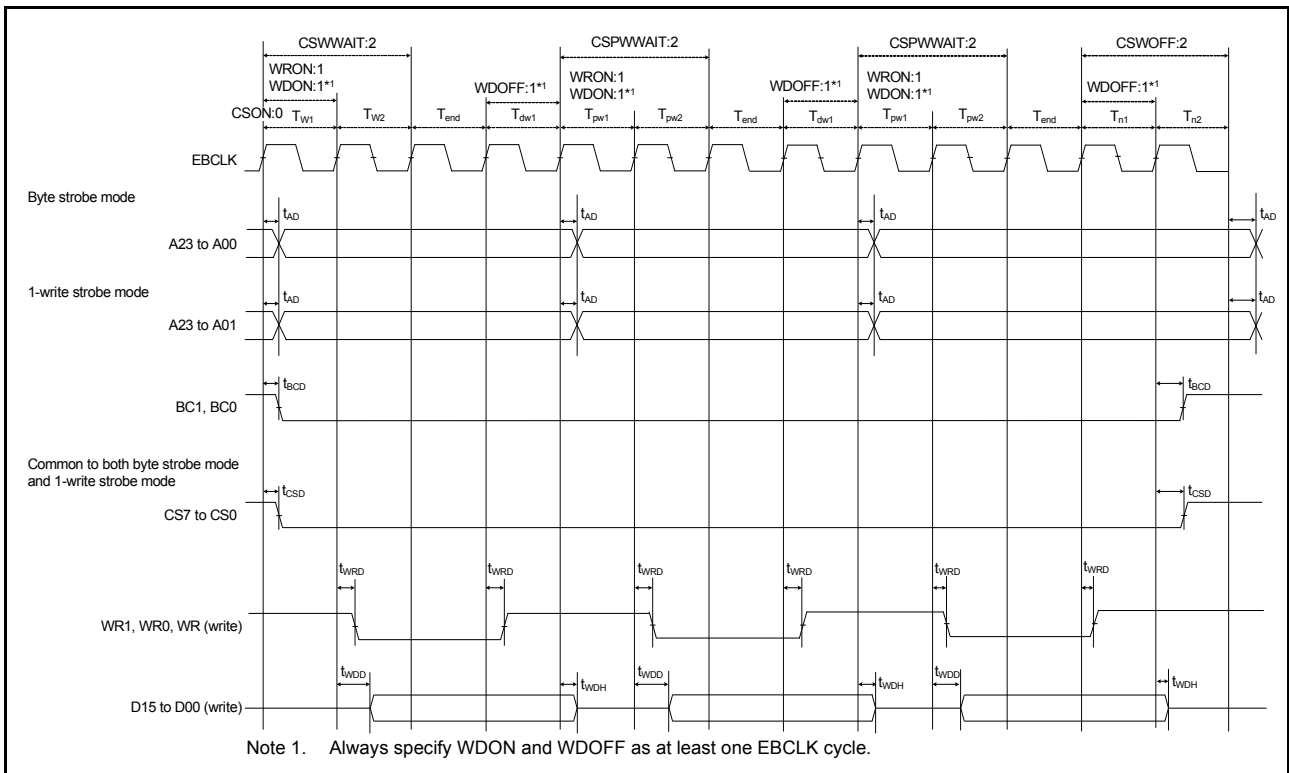


Figure 2.17 External bus timing for page write cycle with bus clock synchronized

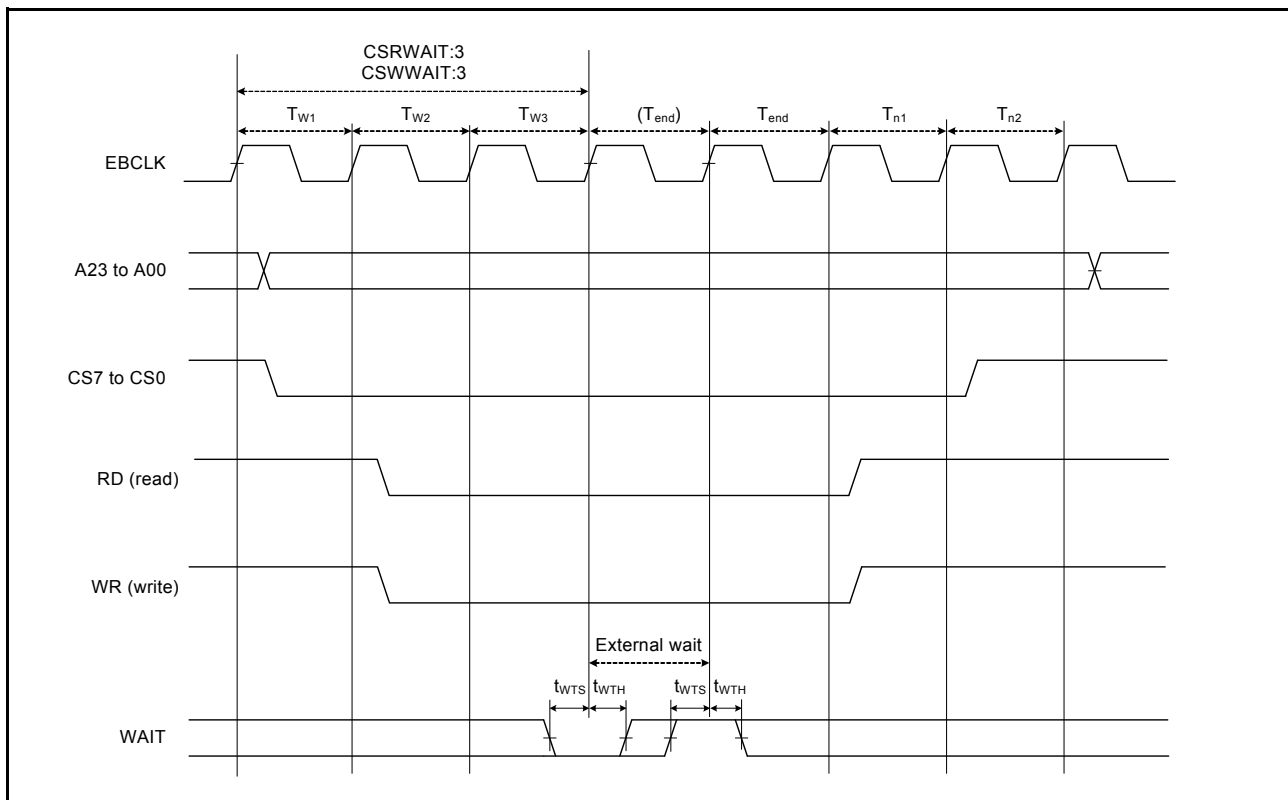


Figure 2.18 External bus timing for external wait control

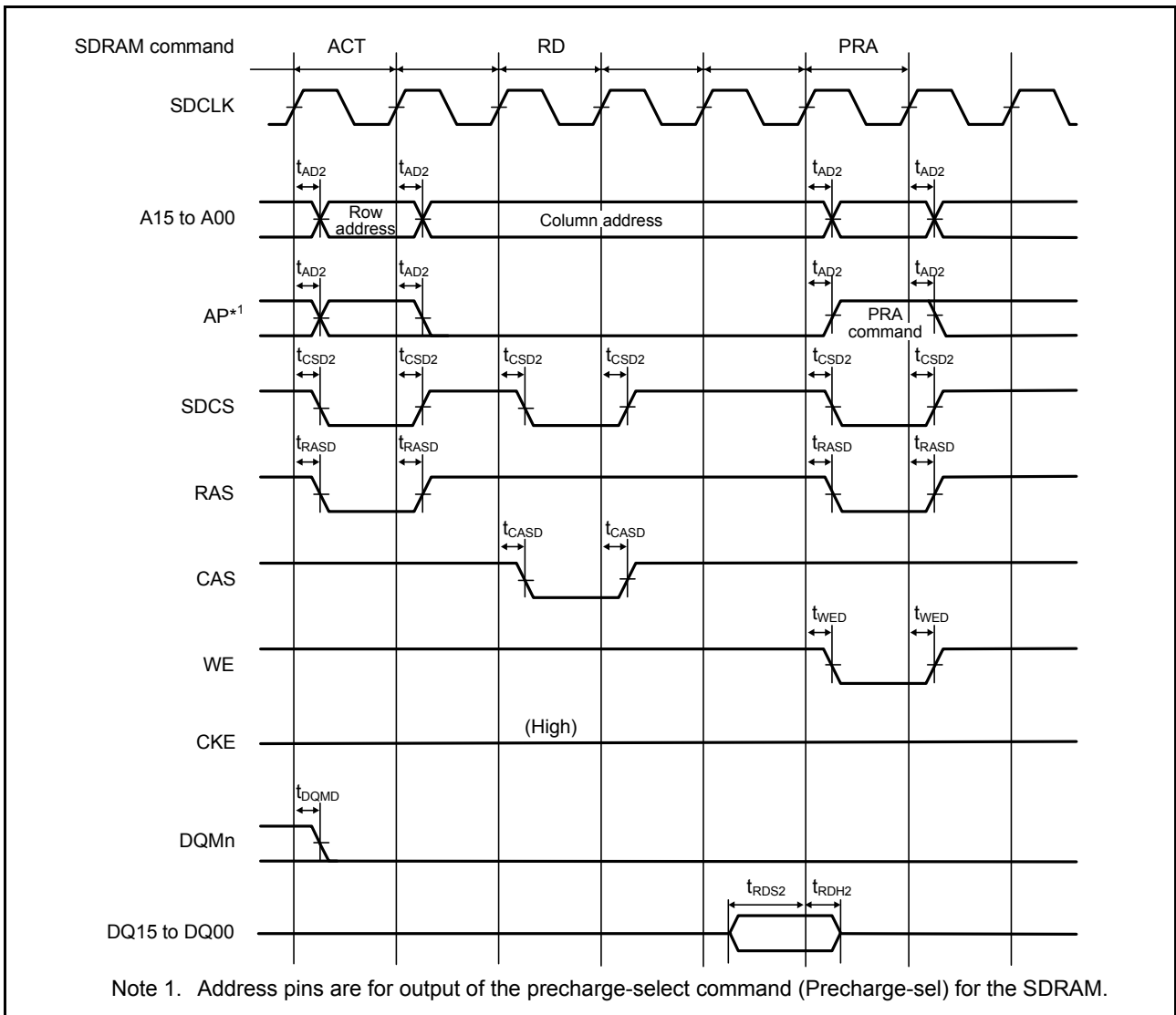


Figure 2.19 SDRAM single read timing



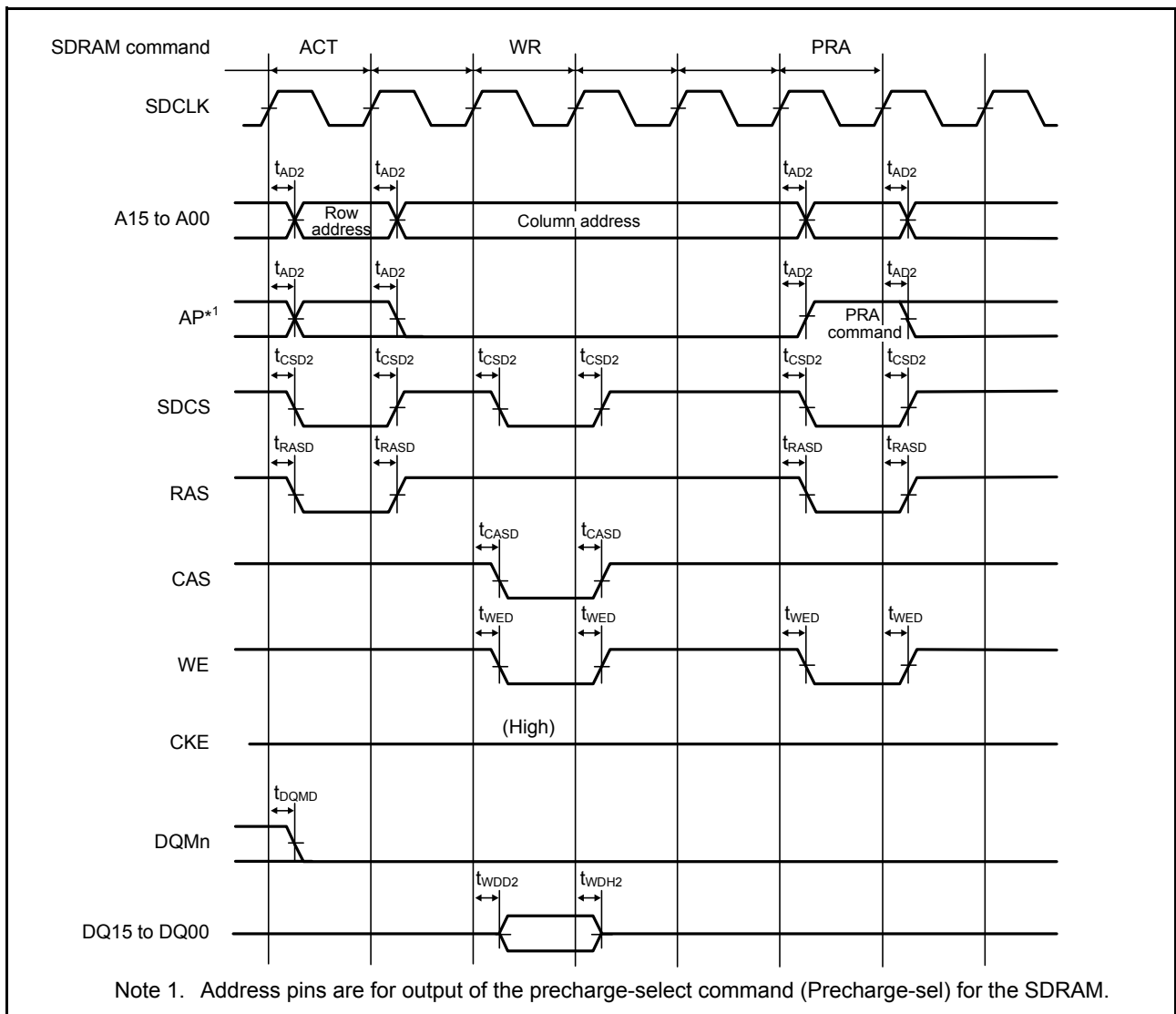


Figure 2.20 SDRAM single write timing

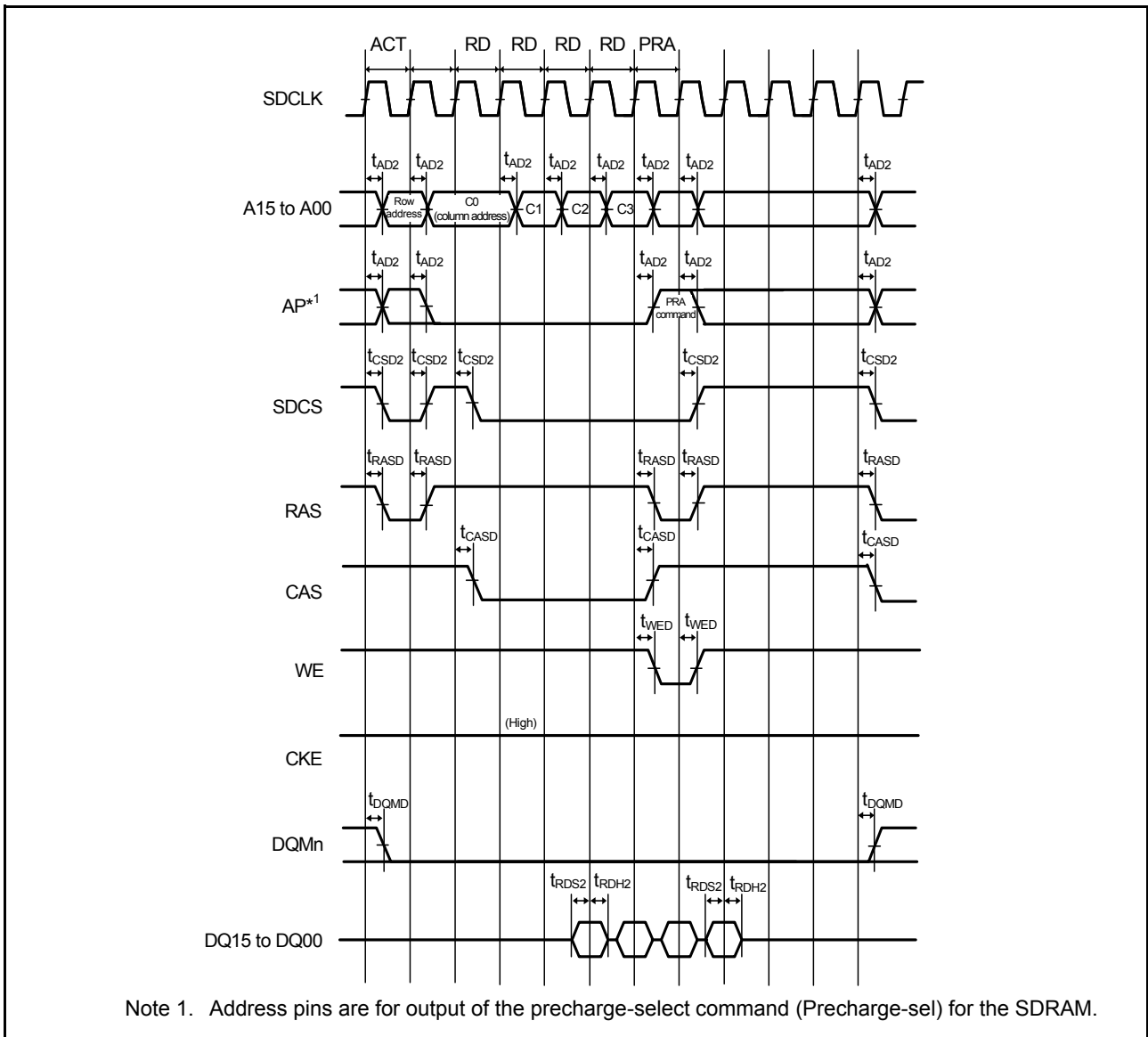


Figure 2.21 SDRAM multiple read timing

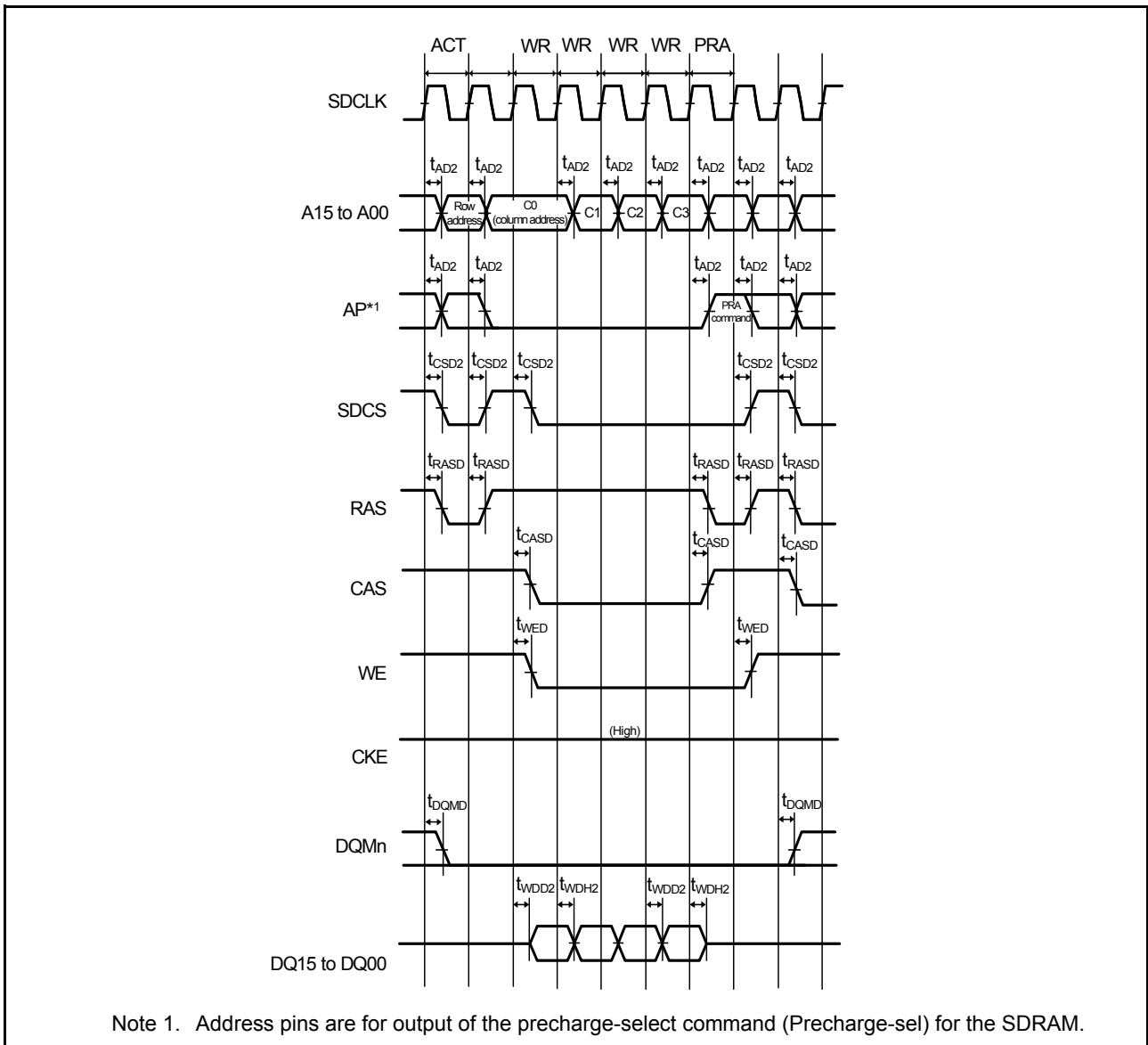


Figure 2.22 SDRAM multiple write timing

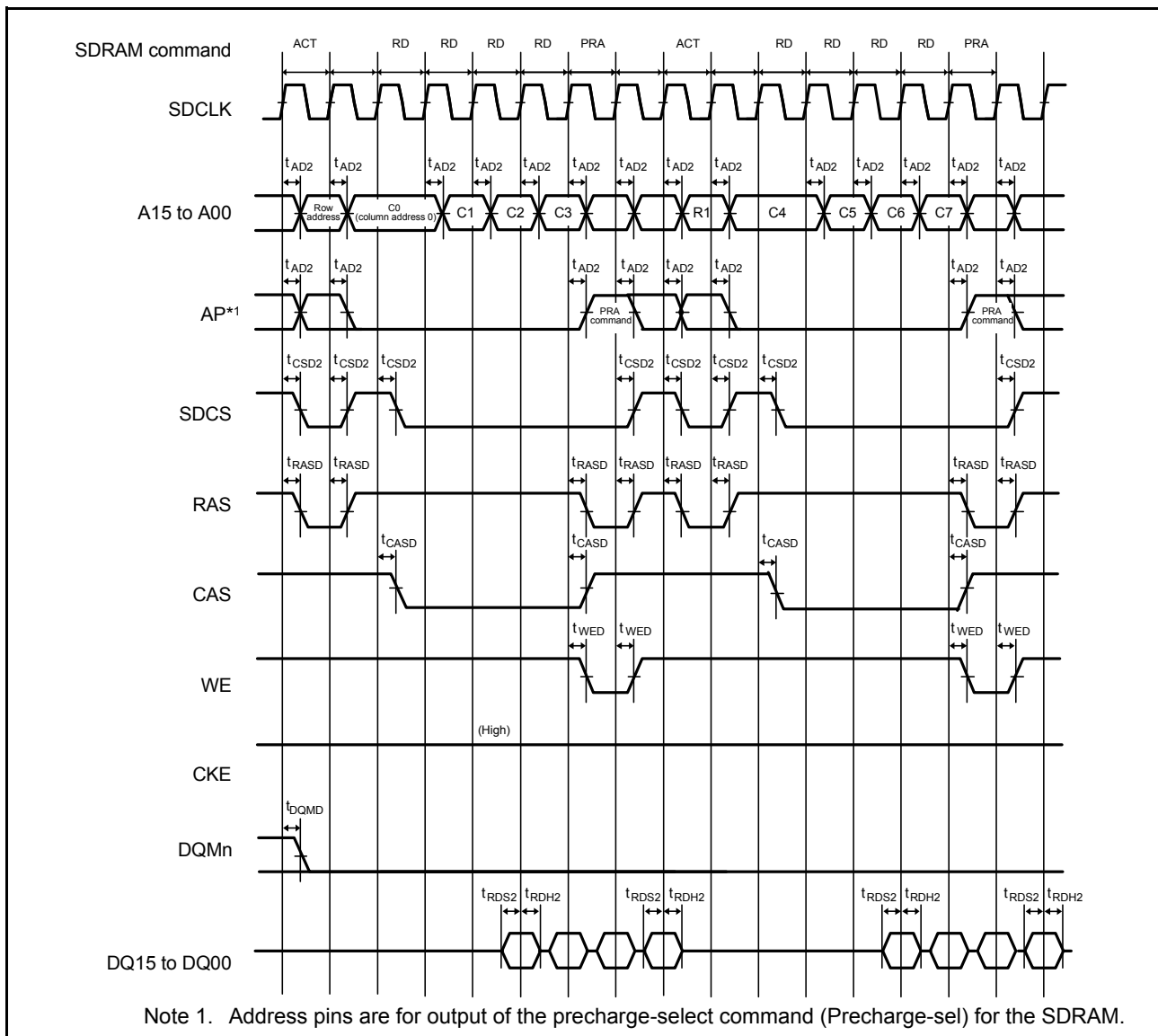


Figure 2.23 SDRAM multiple read line stride timing

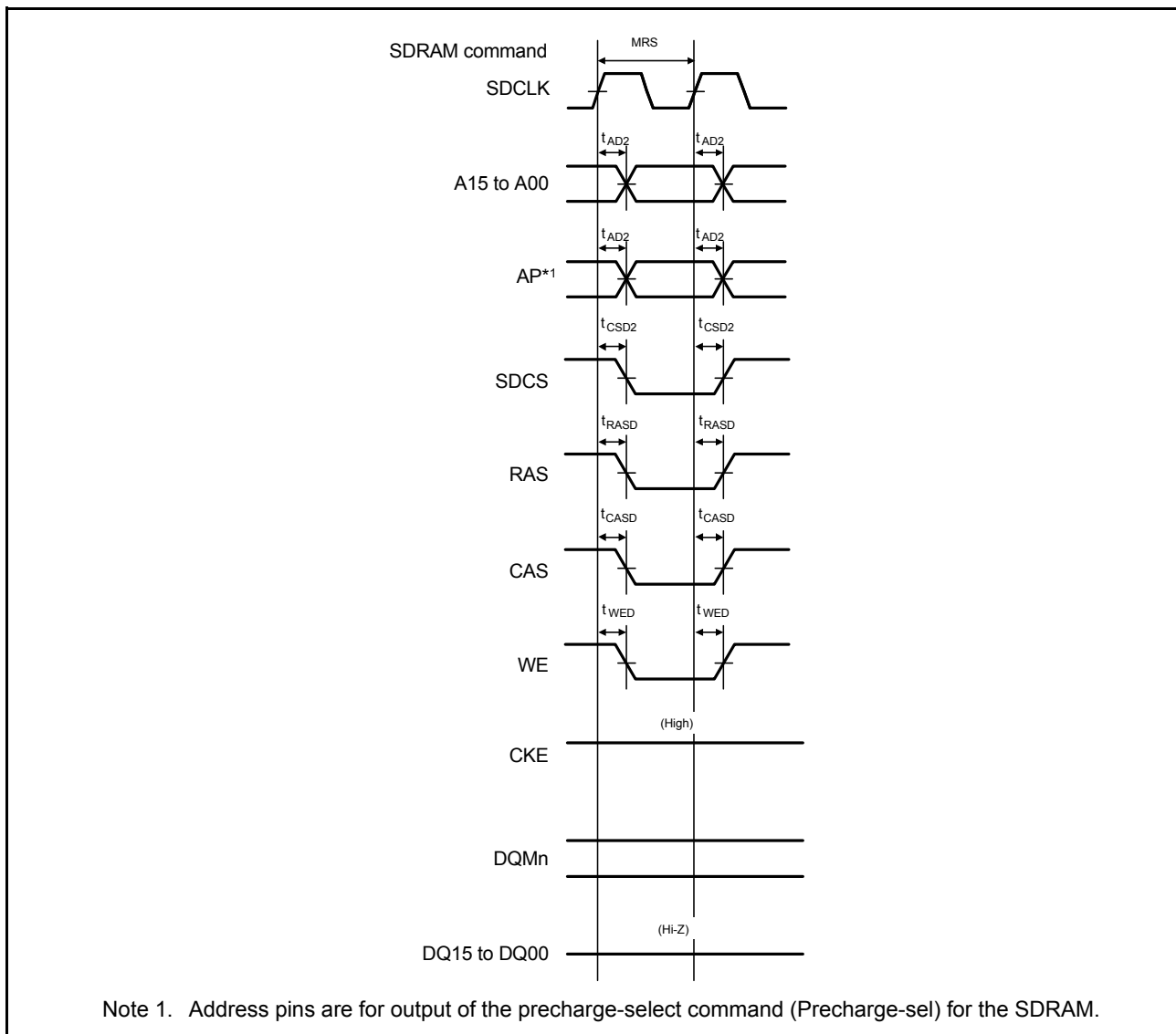


Figure 2.24 SDRAM mode register set timing

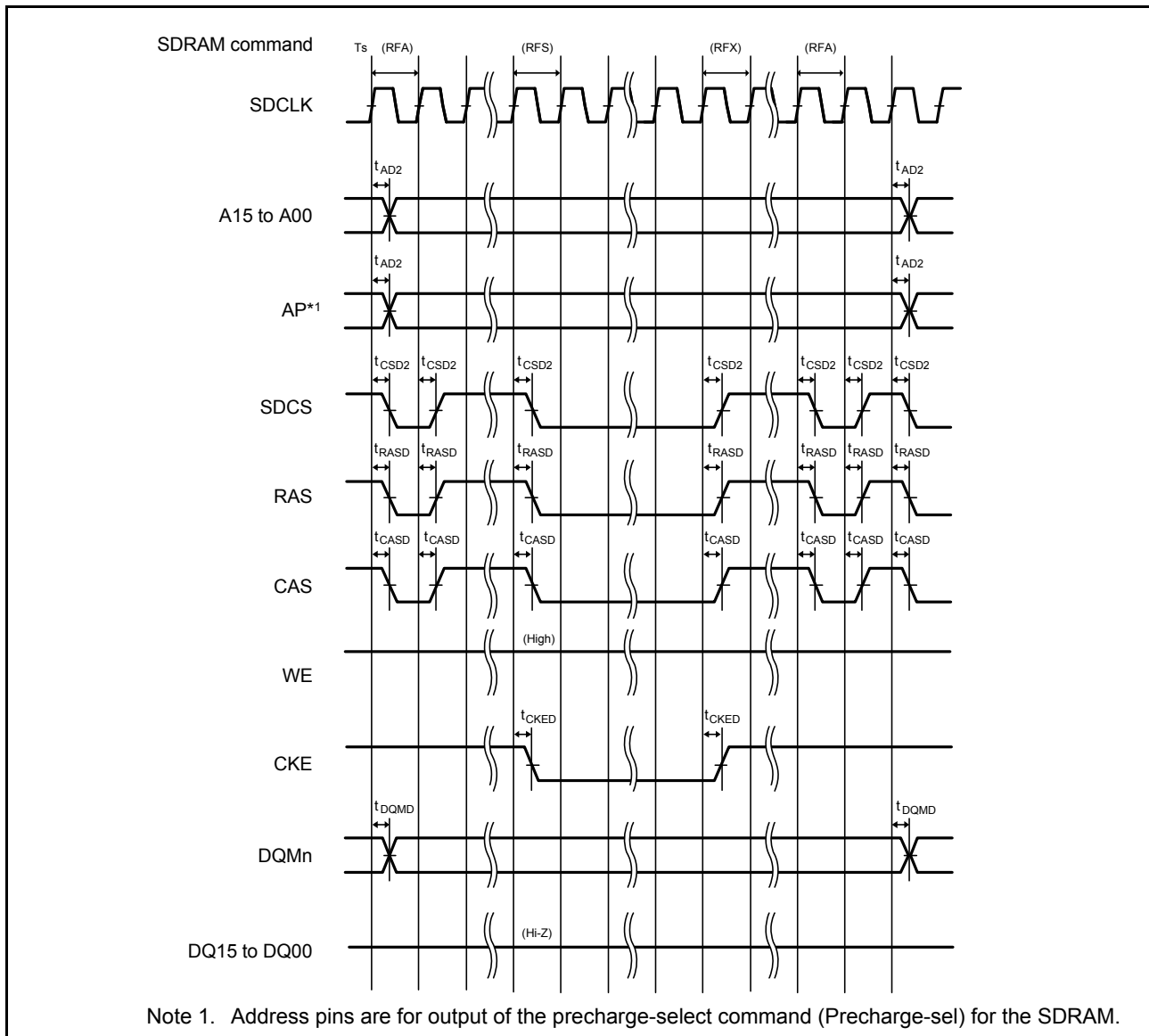


Figure 2.25 SDRAM self-refresh timing

2.3.7 I/O Ports, POEG, GPT32, AGT, KINT, and ADC12 Trigger Timing

Table 2.19 I/O ports, POEG, GPT32, AGT, KINT, and ADC12 trigger timing (1/2)

GPT32 Conditions:

Middle drive output is selected in the port drive capability bit in the PmnPFS register for the following pins: GTIOC6A\_A, GTIOC6B\_A, GTIOC3A\_B, GTIOC3B\_B, GTIOC0A\_B, GTIOC0B\_B, GTIOC9A\_B, GTIOC9B\_B.

High drive output is selected in the port drive capability bit in the PmnPFS register for all other pins.

AGT Conditions:

Middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Max	Unit	Test conditions
I/O ports	Input data pulse width	$t_{PRW}$	1.5	-	$t_{Pcyc}$ <a href="#">Figure 2.26</a>
POEG	POEG input trigger pulse width	$t_{POEW}$	3	-	$t_{Pcyc}$ <a href="#">Figure 2.27</a>

**Table 2.19 I/O ports, POEG, GPT32, AGT, KINT, and ADC12 trigger timing (2/2)**

GPT32 Conditions:

Middle drive output is selected in the port drive capability bit in the PmnPFS register for the following pins: GTIOC6A\_A, GTIOC6B\_A, GTIOC3A\_B, GTIOC3B\_B, GTIOC0A\_B, GTIOC0B\_B, GTIOC9A\_B, GTIOC9B\_B.

High drive output is selected in the port drive capability bit in the PmnPFS register for all other pins.

AGT Conditions:

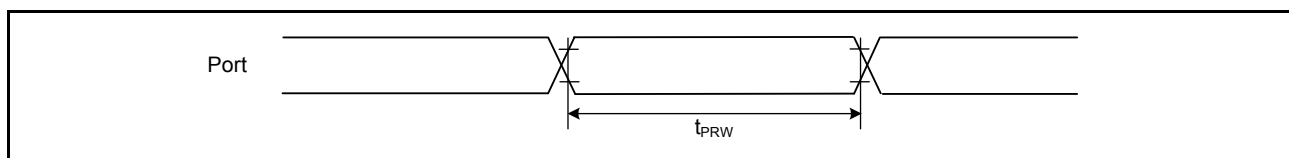
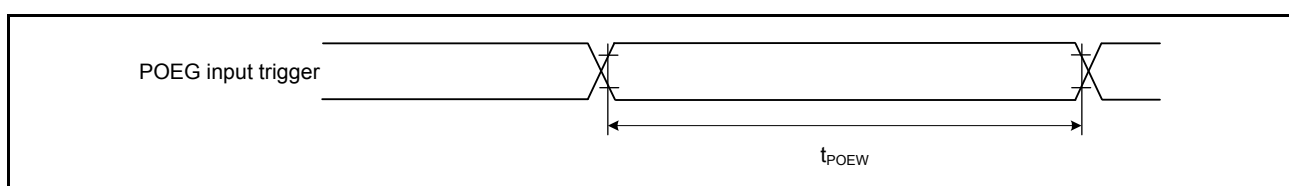
Middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item		Symbol	Min	Max	Unit	Test conditions	
GPT32	Input capture pulse width	Single edge	$t_{GTICW}$	1.5	-	$t_{PDcyc}$	Figure 2.28
		Dual edge		2.5	-		
GPT32	GTIOCxY_Z output skew (x = 0 to 7, Y = A or B, Z = A or B)	Middle drive buffer	$t_{GTISK}^{*2}$	-	4	ns	Figure 2.29
		High drive buffer		-	4		
	GTIOCxY_Z output skew (x = 8 to 13, Y = A or B, Z = A or B)	Middle drive buffer		-	4		
		High drive buffer		-	4		
	GTIOCxY_Z output skew (x = 0 to 13, Y = A or B, Z = A or B)	Middle drive buffer		-	6		
		High drive buffer		-	6		
OPS output skew GTOUUP_x, GTOULO_x, GTOVUP_x, GTOVLO_x, GTOWUP_x, GTOWLO_x (x = A or B)		$t_{GTOSK}^{*2}$	-	5	ns	Figure 2.30	
GPT(PWM Delay Generation Circuit)	GTIOCxY_Z output skew (x = 0 to 3, Y = A or B, Z = A)	$t_{HRSK}^{*3}$	-	2.0	ns	Figure 2.31	
AGT	AGTIO, AGTEE input cycle	$t_{ACYC}^{*1}$	100	-	ns	Figure 2.32	
	AGTIO, AGTEE input high width, low width	$t_{ACKWH}$ , $t_{ACKWL}$	40	-	ns		
	AGTIO, AGTO, AGTOA, AGTOB output cycle	$t_{ACYC2}$	62.5	-	ns		
ADC12	ADC12 trigger input pulse width	$t_{TRGW}$	1.5	-	$t_{Pcyc}$	Figure 2.33	
KINT	Key interrupt input low width	$t_{KR}$	250	-	ns	Figure 2.34	

Note 1.  $t_{Pcyc}$ : PCLKB cycle,  $t_{PDcyc}$ : PCLKD cycle.

Note 2. This skew applies when the same driver I/O is used. If the I/O of the middle and high drivers is mixed, operation is not guaranteed.

Note 3. The load is 30 pF.

Note 4. Constraints on AGTIO input:  $t_{Pcyc} \times 2$  ( $t_{Pcyc}$ : PCLKB cycle) <  $t_{ACYC}$ .**Figure 2.26 I/O ports input timing****Figure 2.27 POEG input trigger timing**

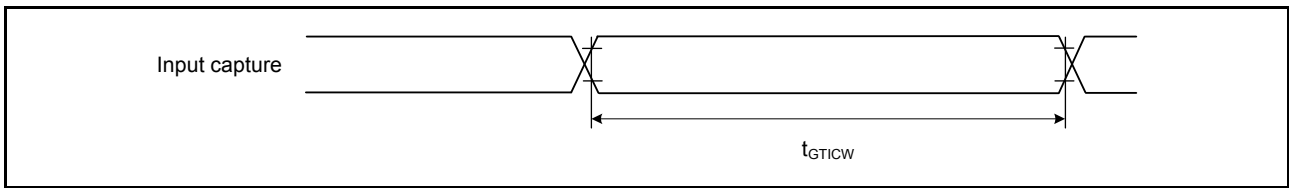


Figure 2.28 GPT32 input capture timing

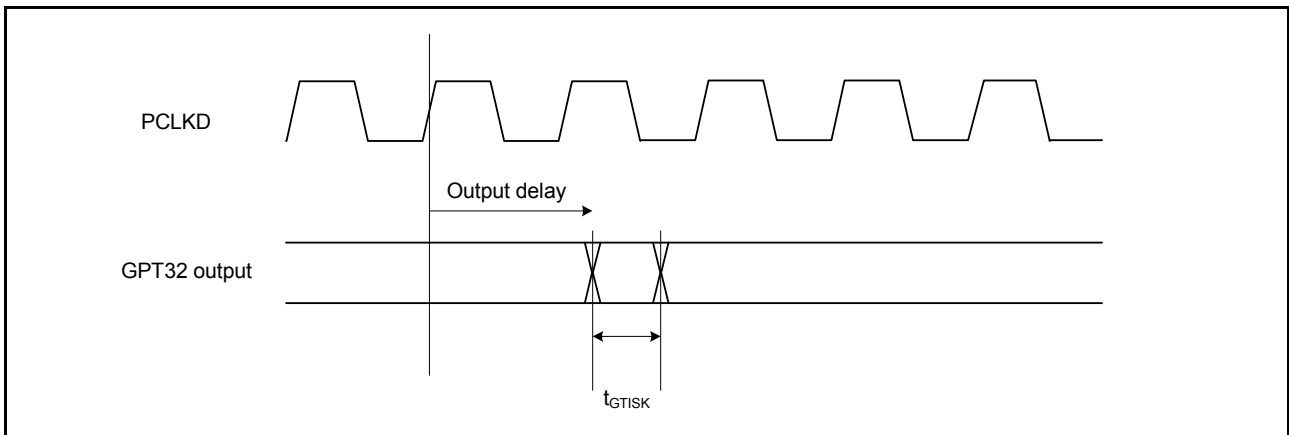


Figure 2.29 GPT32 output delay skew

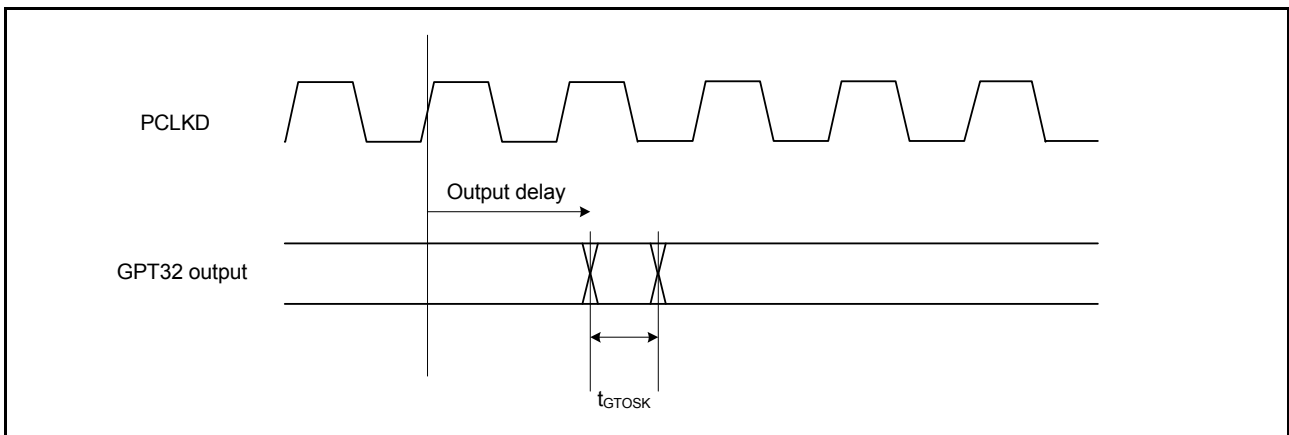


Figure 2.30 GPT32 output delay skew for OPS

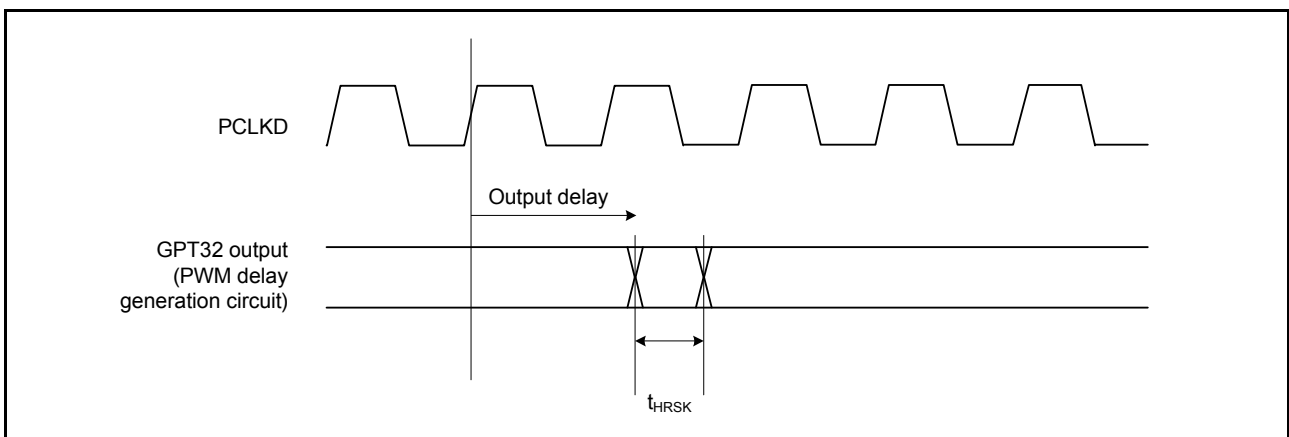


Figure 2.31 GPT32 (PWM Delay Generation Circuit) output delay skew



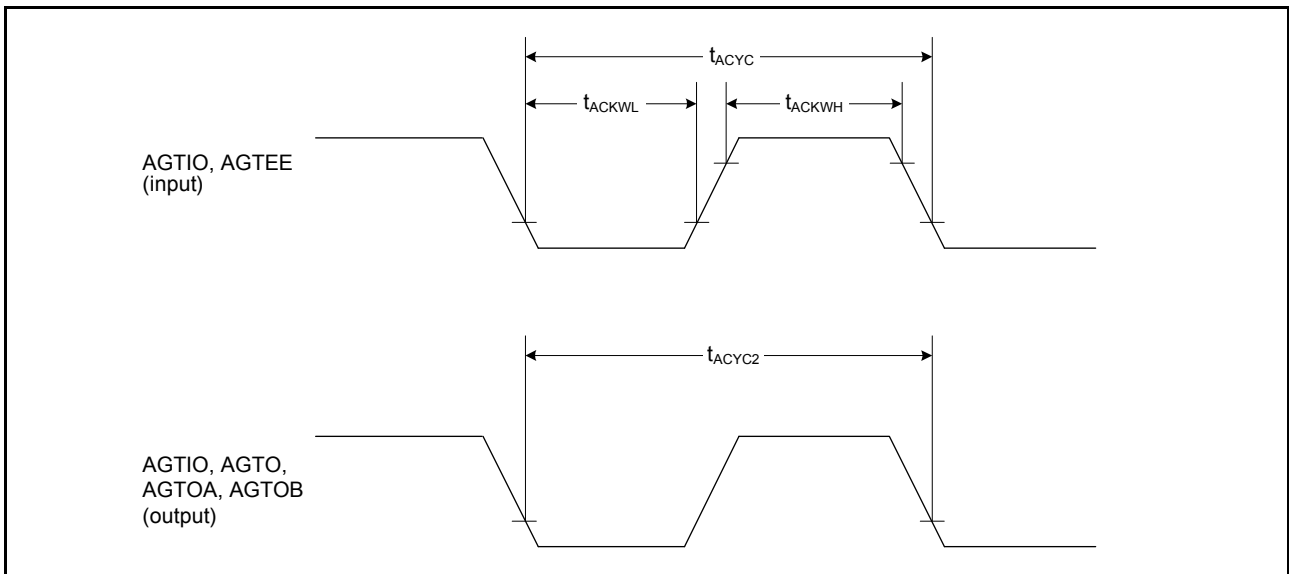


Figure 2.32 AGT input/output timing

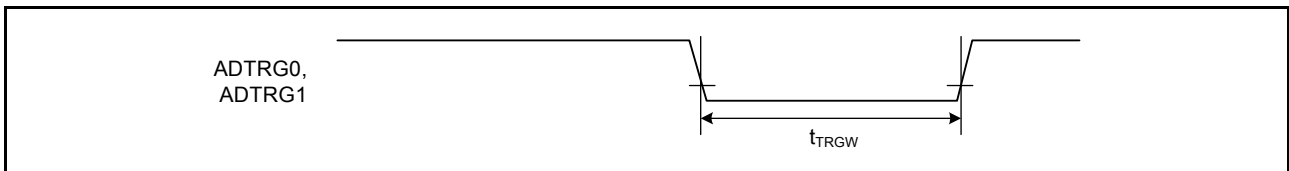


Figure 2.33 ADC12 trigger input timing

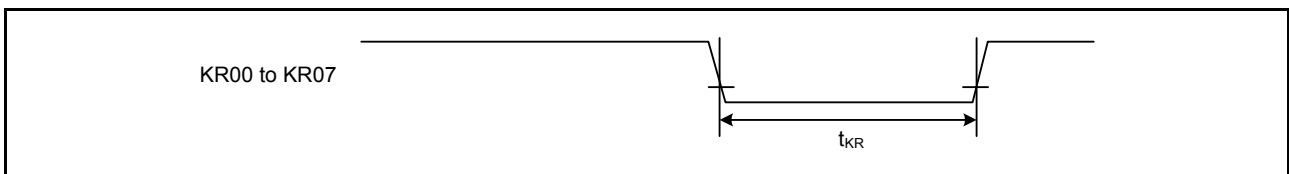


Figure 2.34 Key interrupt input timing

### 2.3.8 PWM Delay Generation Circuit Timing

Table 2.20 PWM Delay Generation Circuit timing

Item	Min	Typ	Max	Unit	Test conditions
Resolution	-	260	-	ps	PCLKD = 120 MHz
DNL*1	-	±2.0	-	LSB	-

Note 1. This value normalizes the differences between lines in 1-LSB resolution.

### 2.3.9 CAC Timing

Table 2.21 CAC timing

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
CAC	CACREF input pulse width	$t_{PBcyc} \leq t_{cac} \times 2$	$t_{CACREF}$	$4.5 \times t_{cac} + 3 \times t_{PBcyc}$	-	ns	-
		$t_{PBcyc} > t_{cac} \times 2$		$5 \times t_{cac} + 6.5 \times t_{PBcyc}$	-	ns	

Note 1.  $t_{pBcyc}$ : PCLKB cycle.

Note 2.  $t_{cac}$ : CAC count clock source cycle.

### 2.3.10 SCI Timing

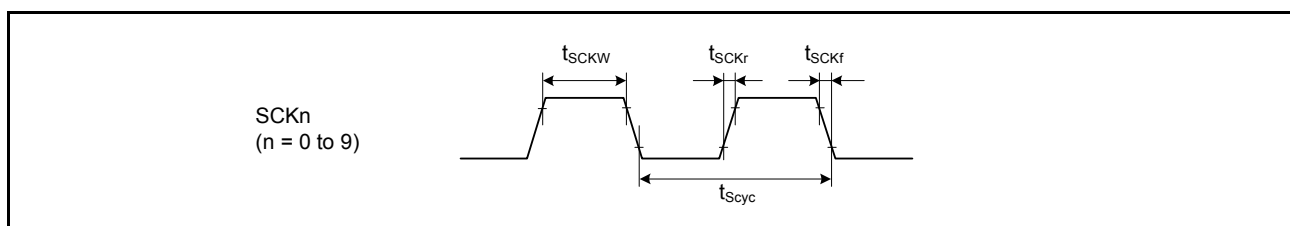
**Table 2.22 SCI timing (1)**

Conditions: High drive output is selected in the port drive capability bit in the PmnPFS register for the following pins: SCK0 to SCK9 (except for SCK4\_B, SCK7\_A), SCK4\_B, SCK7\_A.

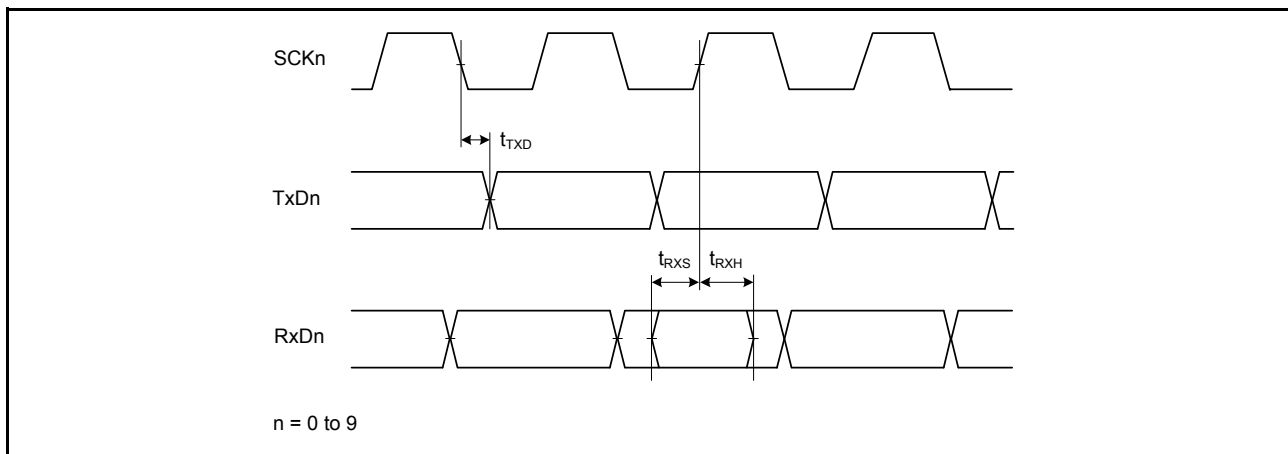
For other pins, middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item		Symbol	Min	Max	Unit*1	Test conditions	
SCI	Input clock cycle	Asynchronous	$t_{Scyc}$	4	-	$t_{Pcyc}$	Figure 2.35
		Clock synchronous		6	-		
	Input clock pulse width	$t_{SCKW}$	0.4	0.6	$t_{Scyc}$		
	Input clock rise time	$t_{SCKr}$	-	5	ns		
	Input clock fall time	$t_{SCKf}$	-	5	ns		
	Output clock cycle	Asynchronous	$t_{Scyc}$	6	-	$t_{Pcyc}$	
		Clock synchronous		4	-		
	Output clock pulse width	$t_{SCKW}$	0.4	0.6	$t_{Scyc}$		
	Output clock rise time	$t_{SCKr}$	-	5	ns		
	Output clock fall time	$t_{SCKf}$	-	5	ns		
	Transmit data delay	Clock synchronous $t_{TXD}$	-	25	ns	Figure 2.36	
	Receive data setup time	Clock synchronous $t_{RXS}$	15	-	ns		
	Receive data hold time	Clock synchronous $t_{RXH}$	5	-	ns		

Note 1.  $t_{Pcyc}$ : PCLKA cycle.



**Figure 2.35 SCK clock input/output timing**



**Figure 2.36** SCI input/output timing in clock synchronous mode

**Table 2.23** SCI timing (2)

Conditions: High drive output is selected in the port drive capability bit in the PmnPFS register for the following pins: SCK0 to SCK9 (except for SCK4\_B, SCK7\_A).

For the SCK4\_B and SCK7\_A pins, middle drive output is selected in the port drive capability bit in the PmnPFS register.

For the MISO1\_A pins, low drive output is selected in the port drive capability bit in the PmnPFS register.

For other pins, middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Max	Unit	Test conditions	
Simple SPI	SCK clock cycle output (master)	$t_{SPcyc}$	4 (PCLKA ≤ 60 MHz) 8 (PCLKA > 60 MHz)	65536	$t_{Pcyc}$	Figure 2.37
	SCK clock cycle input (slave)	-	6 (PCLKA ≤ 60 MHz) 12 (PCLKA > 60 MHz)	65536		
	SCK clock high pulse width	$t_{SPCKWH}$	0.4	0.6	$t_{SPcyc}$	
	SCK clock low pulse width	$t_{SPCKWL}$	0.4	0.6	$t_{SPcyc}$	
	SCK clock rise and fall time	$t_{SPCKr}, t_{SPCKf}$	-	20	ns	
	Data input setup time	$t_{SU}$	33.3	-	ns	Figure 2.38 to Figure 2.41
	Data input hold time	$t_H$	33.3	-	ns	
	SS input setup time	$t_{LEAD}$	1	-	$t_{SPcyc}$	
	SS input hold time	$t_{LAG}$	1	-	$t_{SPcyc}$	
	Data output delay	$t_{OD}$	-	33.3	ns	
	Data output hold time	$t_{OH}$	-10	-	ns	
	Data rise and fall time	$t_{Dr}, t_{Df}$	-	16.6	ns	
	SS input rise and fall time	$t_{SSLr}, t_{SSLf}$	-	16.6	ns	
	Slave access time	$t_{SA}$	-	4 (PCLKA ≤ 60 MHz) 8 (PCLKA > 60 MHz)	$t_{Pcyc}$	Figure 2.41
	Slave output release time	$t_{REL}$	-	5 (PCLKA ≤ 60 MHz) 10 (PCLKA > 60 MHz)	$t_{Pcyc}$	

Note: MISO1\_A is not supported in these specifications.

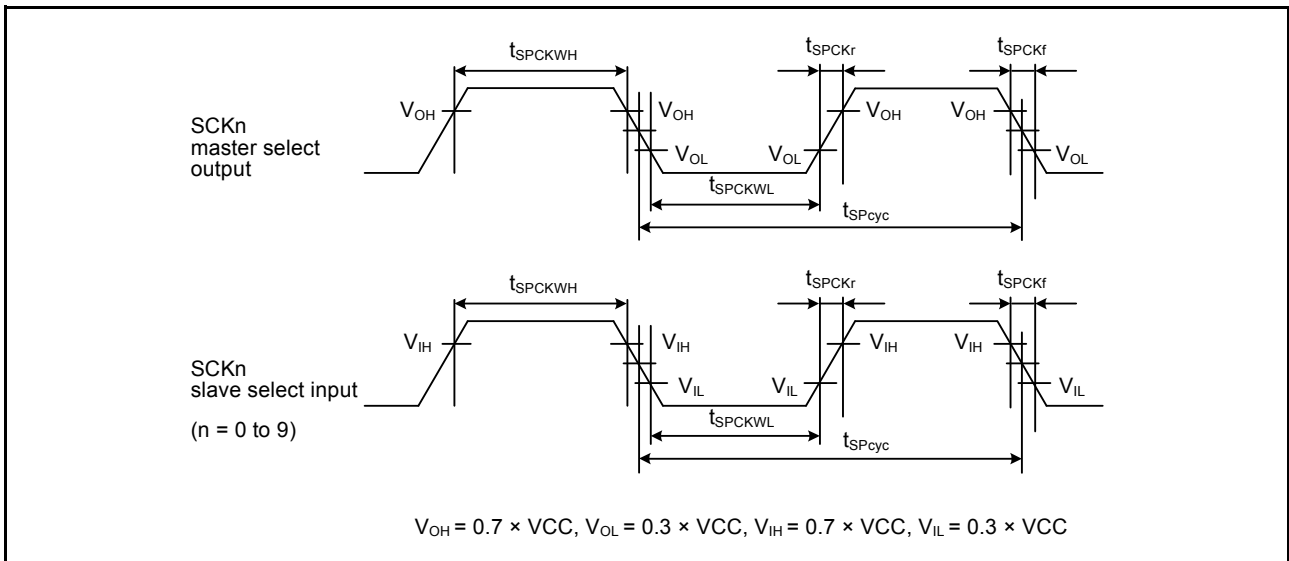


Figure 2.37 SCI simple SPI mode clock timing

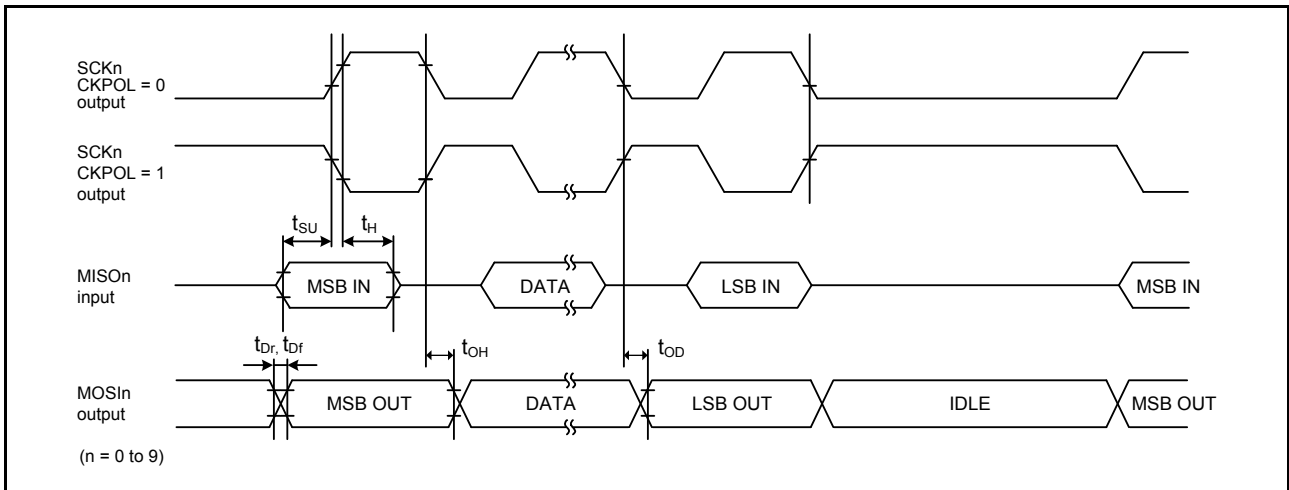


Figure 2.38 SCI simple SPI mode timing for master when CKPH = 1

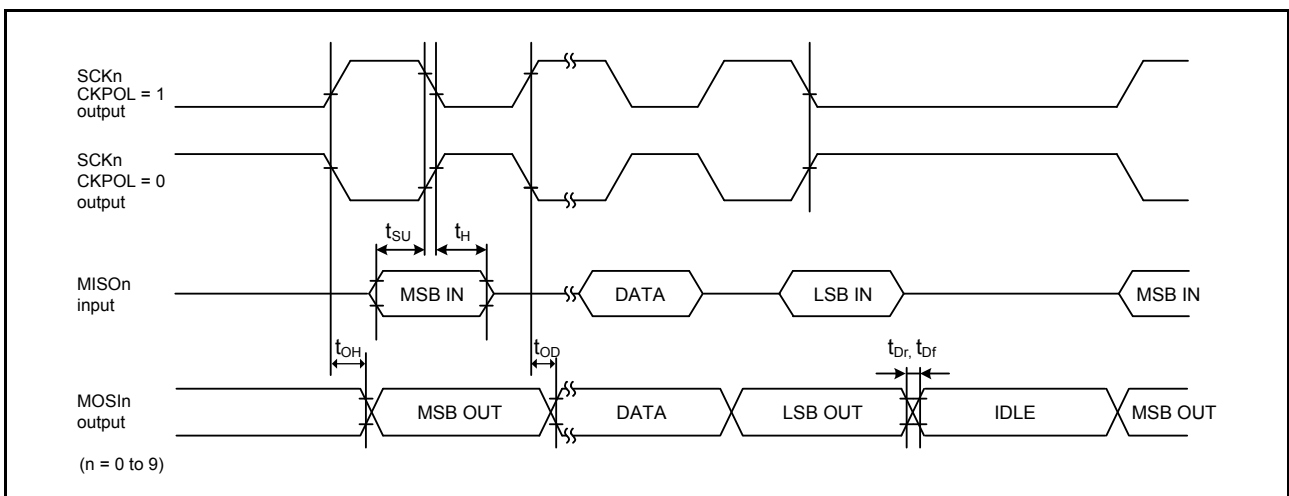


Figure 2.39 SCI simple SPI mode timing for master when CKPH = 0

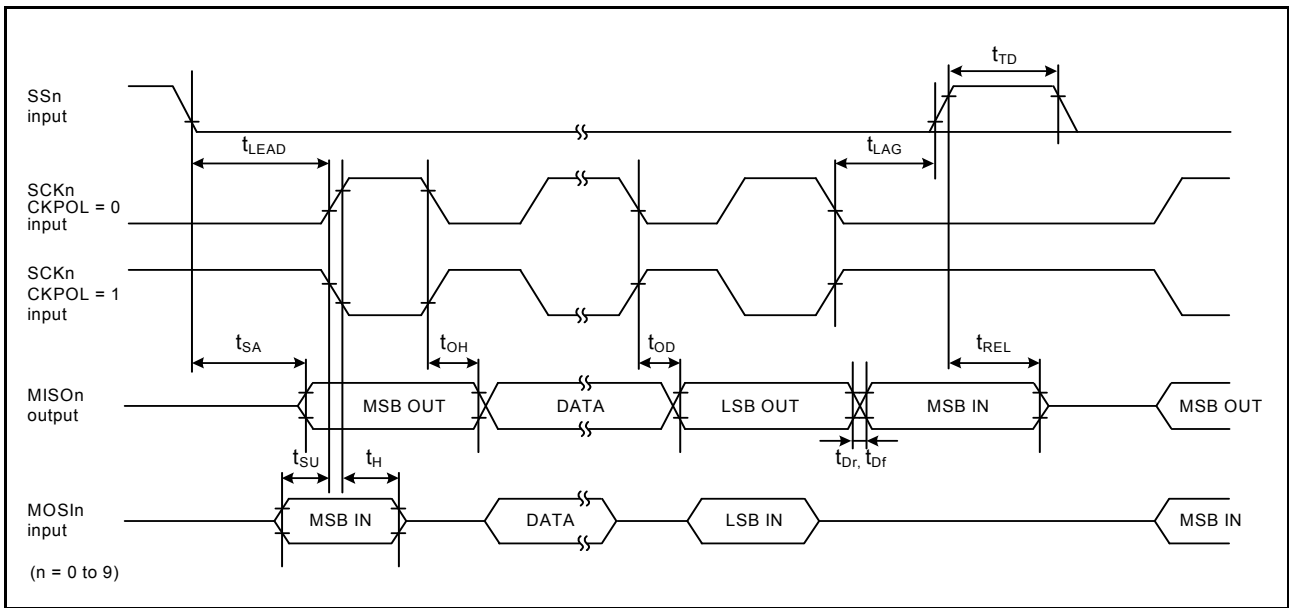


Figure 2.40 SCI simple SPI mode timing for slave when CKPH = 1

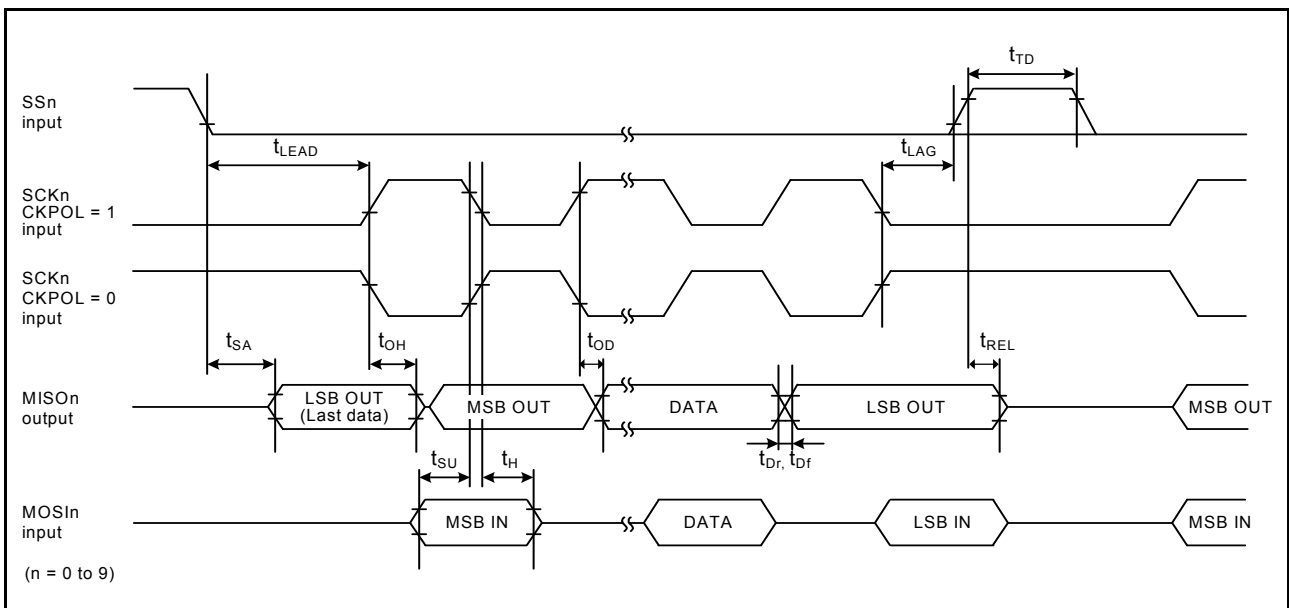


Figure 2.41 SCI simple SPI mode timing for slave when CKPH = 0

Table 2.24 SCI timing (3) (1/2)

Conditions: For the SCL1\_A pins, low drive output is selected in the port drive capability bit in the PmnPFS register. For other pins, middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Max	Unit	Test conditions	
Simple IIC (Standard mode)	SDA input rise time	$t_{Sr}$	-	1000	ns	Figure 2.42
	SDA input fall time	$t_{Sf}$	-	300	ns	
	SDA input spike pulse removal time	$t_{SP}$	0	$4 \times t_{IICyc}$	ns	
	Data input setup time	$t_{SDAS}$	250	-	ns	
	Data input hold time	$t_{SDAH}$	0	-	ns	
	SCL, SDA capacitive load	$C_b^{*1}$	-	400	pF	

**Table 2.24 SCI timing (3) (2/2)**

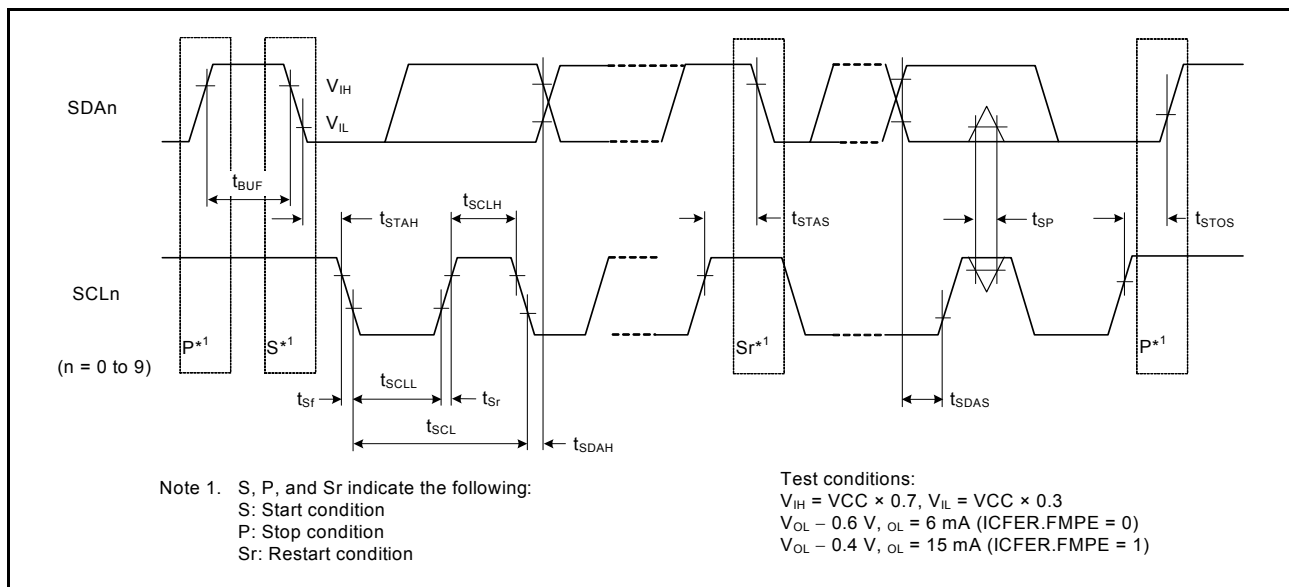
Conditions: For the SCL1\_A pins, low drive output is selected in the port drive capability bit in the PmnPFS register.  
For other pins, middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Max	Unit	Test conditions	
Simple IIC (Fast mode)	SCL, SDA input rise time	$t_{Sr}$	-	300	ns	Figure 2.42
	SCL, SDA input fall time	$t_{Sf}$	-	300	ns	
	SCL, SDA input spike pulse removal time	$t_{SP}$	0	$4 \times t_{IICcyc}$	ns	
	Data input setup time	$t_{SDAS}$	100	-	ns	
	Data input hold time	$t_{SDAH}$	0	-	ns	
	SCL, SDA capacitive load	$C_b^{*1}$	-	400	pF	

Note: SCL1\_A output is not supported in these specifications.

$t_{IICcyc}$ : IIC internal reference clock (IIC $\phi$ ) cycle,  $t_{Pcyc}$ : PCLKA cycle.

Note 1.  $C_b$  indicates the total capacity of the bus line.

**Figure 2.42 SCI simple IIC mode timing**

## 2.3.11 SPI Timing

**Table 2.25 SPI timing**

Conditions:

(1) Middle drive output is selected with the port drive capability bit in the PmnPFS register.

(2) Use pins that have a letter appended to their names, for instance "\_A" or "\_B", to indicate group membership. For the SPI interface, the AC portion of the electrical characteristics is measured for each group.

Item	Symbol	Min	Max	Unit*1	Test conditions		
SPI	RSPCK clock cycle	Master	$t_{SPCyc}$	2 (PCLKA ≤ 60 MHz) 4 (PCLKA > 60 MHz)	4096	$t_{Pcyc}$	Figure 2.43 C = 30 pF
		Slave		6	4096		
RSPCK clock high pulse width	Master	$t_{SPCKWH}$	$(t_{SPCyc} - t_{SPCKR} - t_{SPCKF}) / 2 - 3$	-	ns		
	Slave		$3 \times t_{Pcyc}$	-			
RSPCK clock low pulse width	Master	$t_{SPCKWL}$	$(t_{SPCyc} - t_{SPCKR} - t_{SPCKF}) / 2 - 3$	-	ns		
	Slave		$3 \times t_{Pcyc}$	-			
RSPCK clock rise and fall time	Master	$t_{SPCKr}$	-	5	ns		
	Slave	$t_{SPCKf}$	-	1	μs		
Data input setup time	Master	$t_{SU}$	4	-	ns	Figure 2.44 to Figure 2.49 C = 30 pF	
	Slave		5	-			
Data input hold time	Master	$t_{HF}^{*4}$	0	-	ns		
	Master	$t_H$	$t_{Pcyc}$	-			
	Slave	$t_H$	20	-			
SSL setup time	Master	$t_{LEAD}$	$N \times t_{SPCyc} - 10^{*2}$	$N \times t_{SPCyc} + 100^{*2}$	ns		
	Slave		$6 \times t_{Pcyc}$	-	ns		
SSL hold time	Master	$t_{LAG}$	$N \times t_{SPCyc} - 10^{*3}$	$N \times t_{SPCyc} + 100^{*3}$	ns		
	Slave		$6 \times t_{Pcyc}$	-	ns		
Data output delay	Master	$t_{OD}$	-	6.3	ns	Figure 2.44 to Figure 2.49 C = 30 pF	
	Slave		-	20			
Data output hold time	Master	$t_{OH}$	0	-	ns		
	Slave		0	-			
Successive transmission delay	Master	$t_{TD}$	$t_{SPCyc} + 2 \times t_{Pcyc}$	$8 \times t_{SPCyc} + 2 \times t_{Pcyc}$	ns		
	Slave		$6 \times t_{Pcyc}$				
MOSI and MISO rise and fall time	Output	$t_{Dr}, t_{Df}$	-	5	ns		
	Input		-	1	μs		
SSL rise and fall time	Output	$t_{SSLr}$	-	5	ns		
	Input	$t_{SSLf}$	-	1	μs		
Slave access time		$t_{SA}$	-	$2 \times t_{Pcyc} + 28$	ns	Figure 2.48 and Figure 2.49 C = 30 pF	
Slave output release time		$t_{REL}$	-	$2 \times t_{Pcyc} + 28$			

Note 1.  $t_{Pcyc}$ : PCLKA cycle.

Note 2. N is set to an integer from 1 to 8 by the SPCKD register.

Note 3. N is set to an integer from 1 to 8 by the SSLND register.

Note 4. PCLKA division ratio set to 1/2.

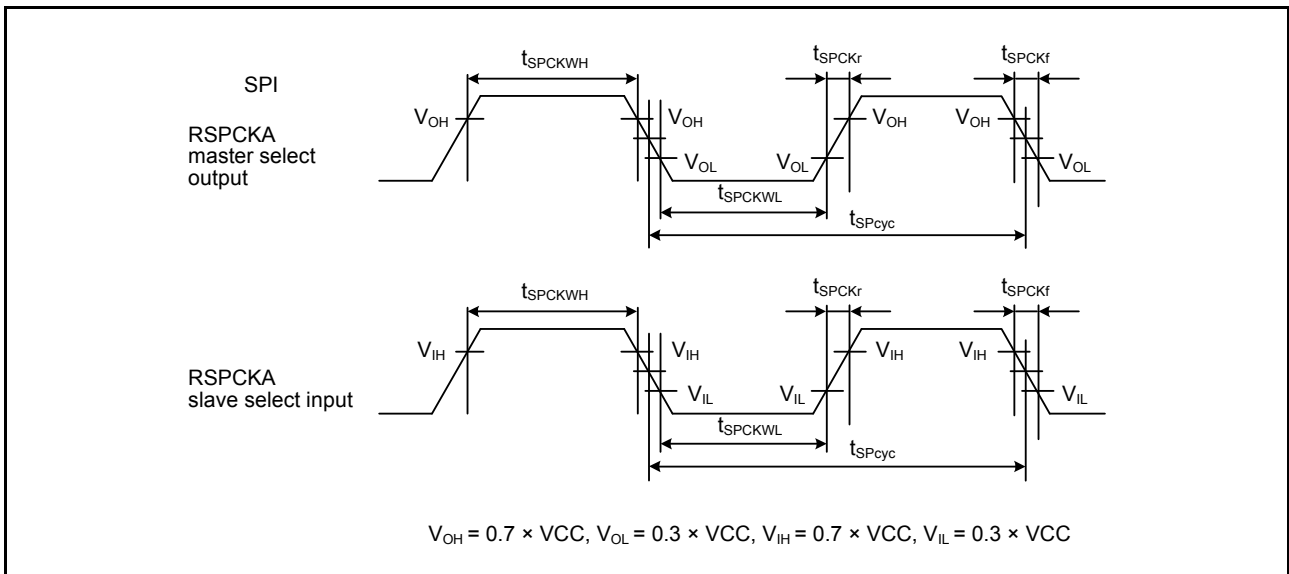


Figure 2.43 SPI clock timing

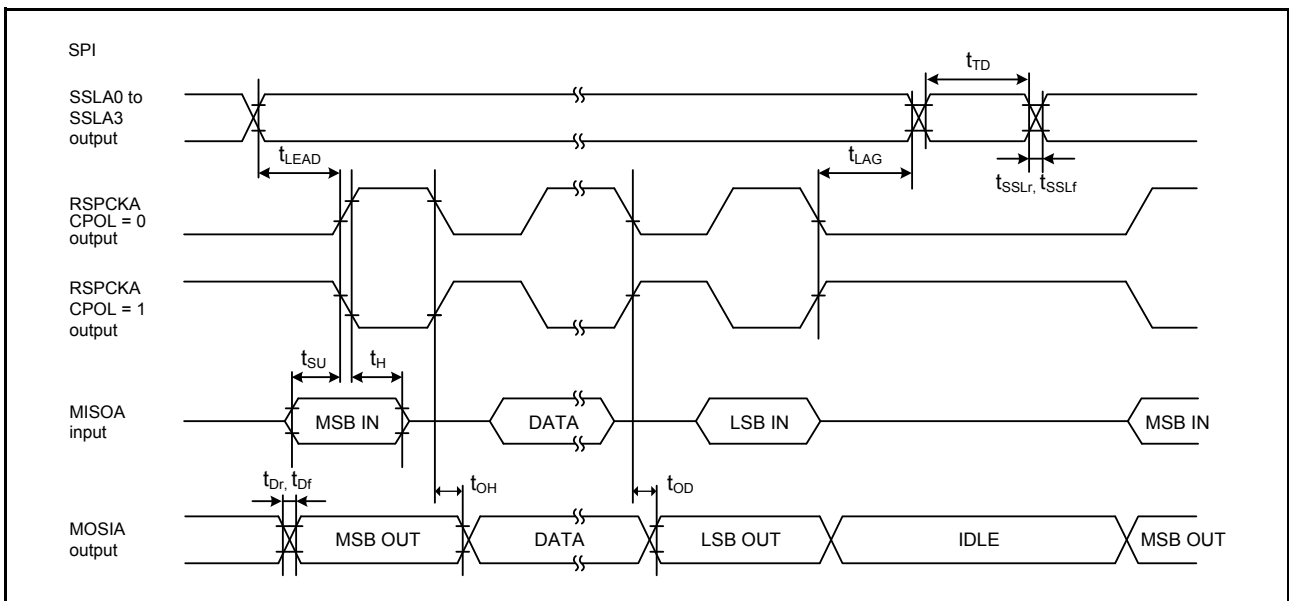


Figure 2.44 SPI timing for master when CPHA = 0



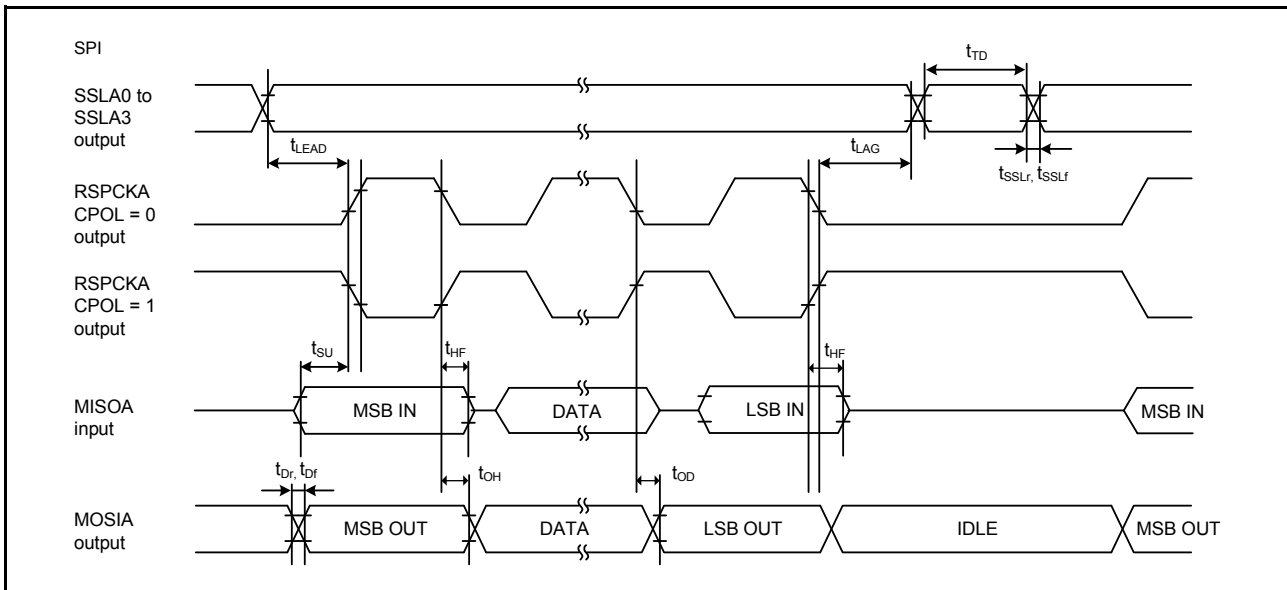


Figure 2.45 SPI timing for master when CPHA = 0 and the bit rate is set to PCLKA/2

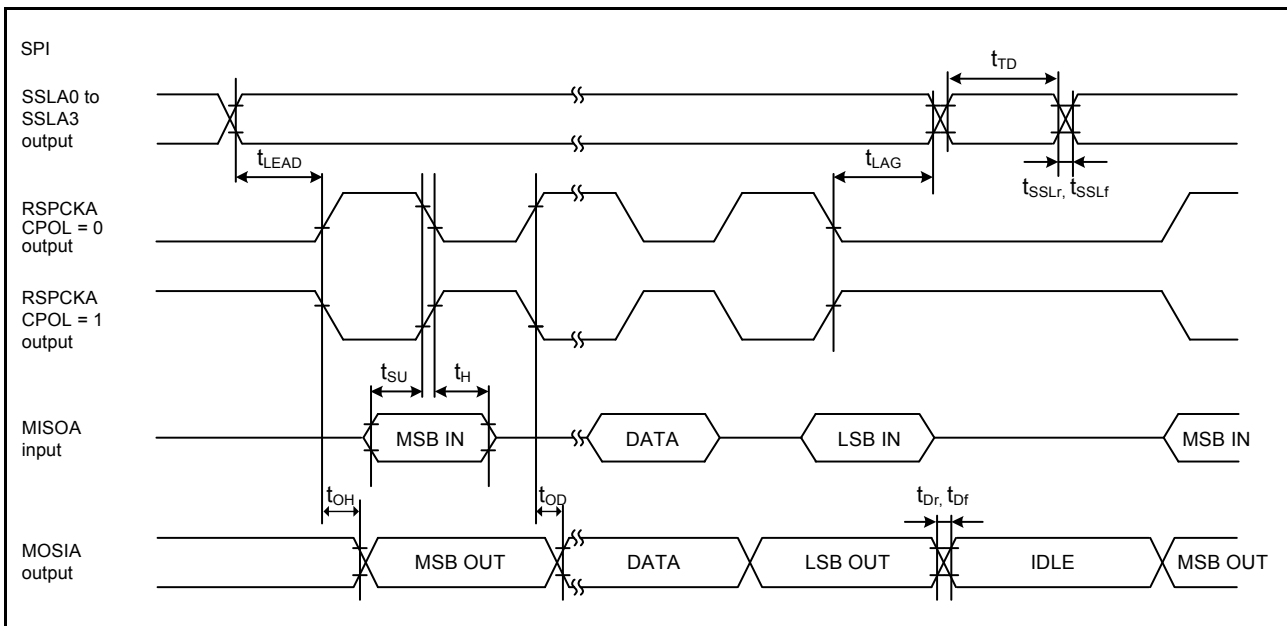


Figure 2.46 SPI timing for master when CPHA = 1 and the bit rate is set to PCLKA/2

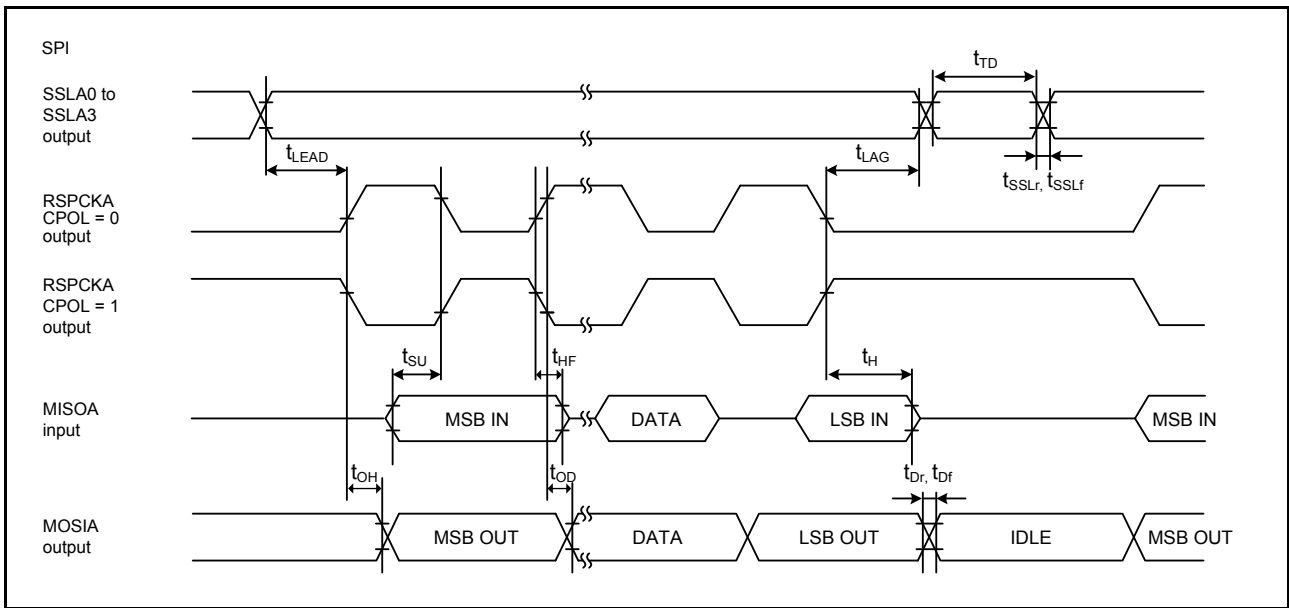


Figure 2.47 SPI timing for master when CPHA = 1 and the bit rate is set to PCLKA/2

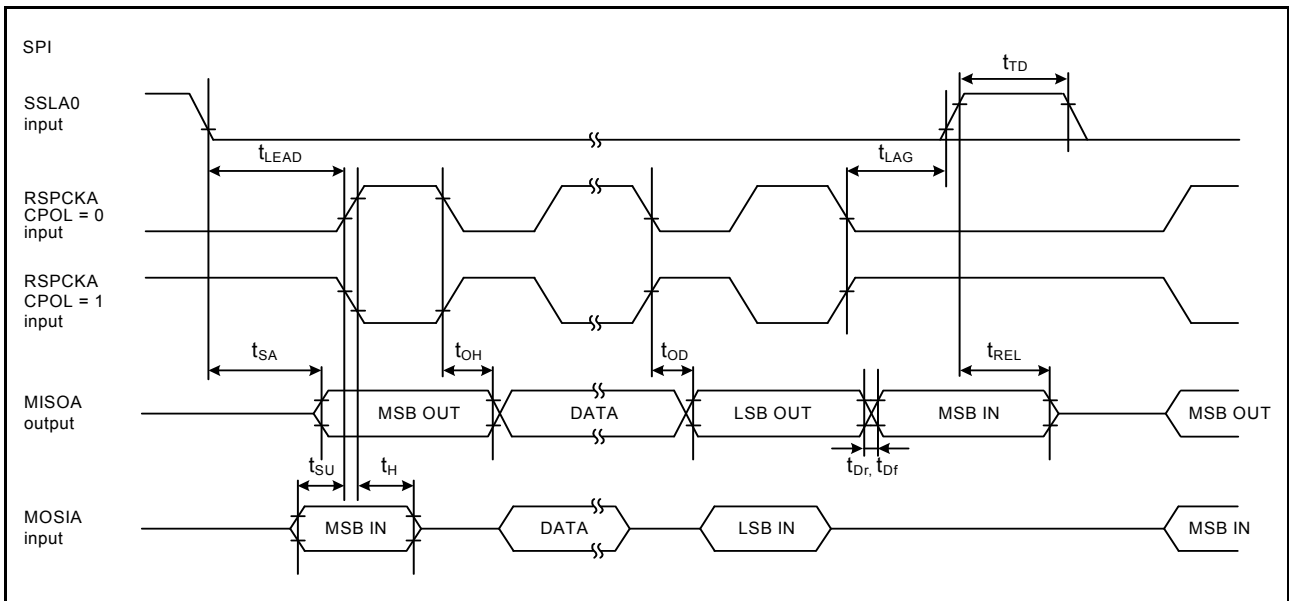


Figure 2.48 SPI timing for slave when CPHA = 0

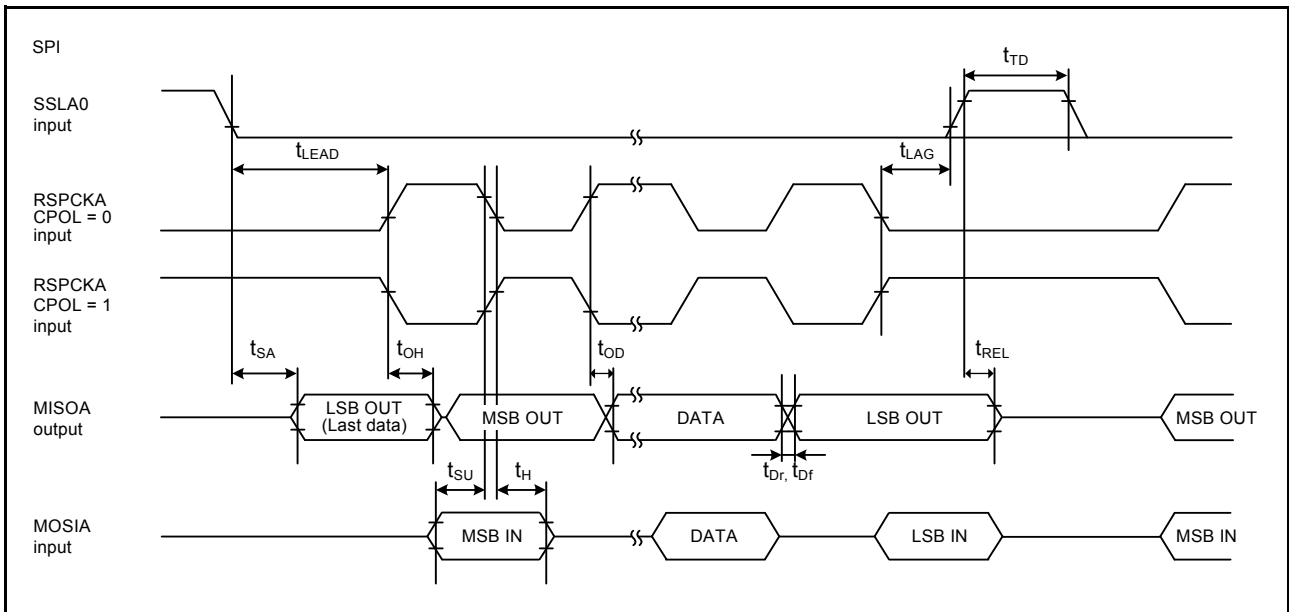


Figure 2.49 SPI timing for slave when CPHA = 1

### 2.3.12 QSPI Timing

Table 2.26 QSPI timing

Conditions: High drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Max	Unit*1	Test conditions	
QSPI	QSPCK clock cycle	$t_{QScyc}$	2	48	$t_{Pcyc}$	Figure 2.50
	QSPCK clock high pulse width	$t_{QSWH}$	$t_{QScyc} \times 0.4$	-	ns	
	QSPCK clock low pulse width	$t_{QSWL}$	$t_{QScyc} \times 0.4$	-	ns	
QSPI	Data input setup time	$t_{Su}$	11	-	ns	Figure 2.51
	Data input hold time	$t_{IH}$	0	-	ns	
	QSSL setup time	$t_{LEAD}$	$(N+0.5) \times t_{QScyc} - 5 *2$	$(N+0.5) \times t_{QScyc} + 100 *2$	ns	
	QSSL hold time	$t_{LAG}$	$(N+0.5) \times t_{QScyc} - 5 *3$	$(N+0.5) \times t_{QScyc} + 100 *3$	ns	
	Data output delay	$t_{OD}$	-	4	ns	
	Data output hold time	$t_{OH}$	-3.3	-	ns	
	Successive transmission delay	$t_{TD}$	1	16	$t_{QScyc}$	

Note 1.  $t_{Pcyc}$ : PCLKA cycle.

Note 2. N is set to 0 or 1 in SFMSLD.

Note 3. N is set to 0 or 1 in SFMSHD.

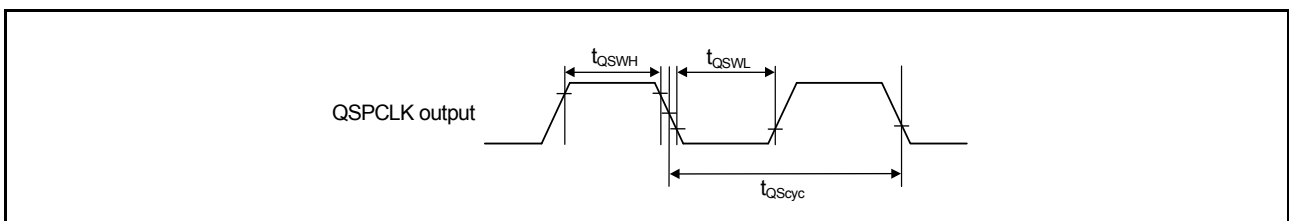
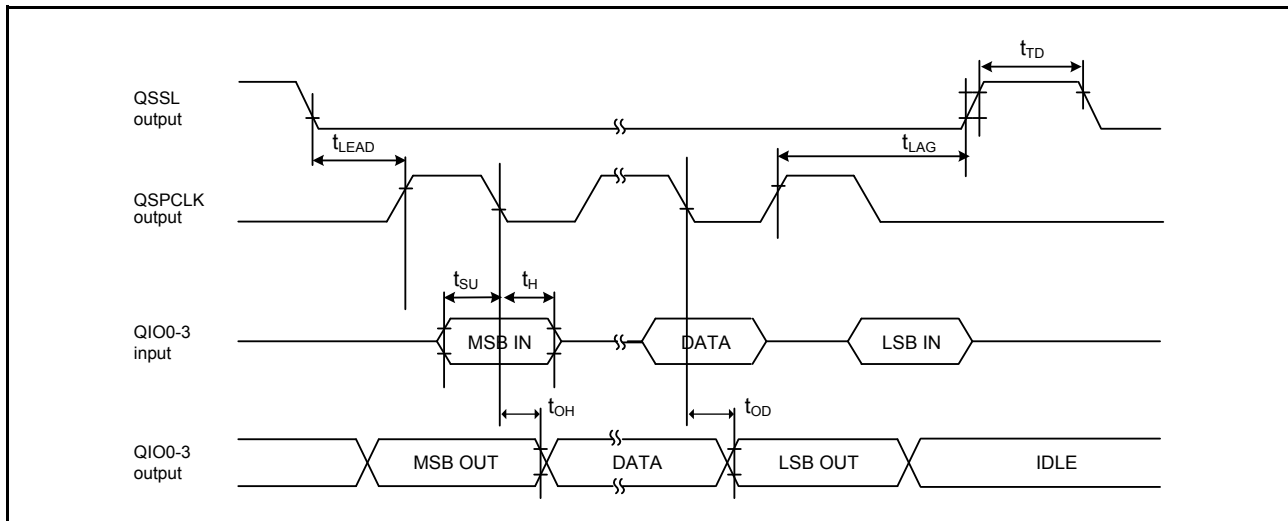


Figure 2.50 QSPI clock timing



**Figure 2.51 Transmit and receive timing**

### 2.3.13 IIC Timing

**Table 2.27 IIC timing (1) (1/2)**

Conditions: Middle drive output is selected in the port drive capability bit in the PmnPFS register for the following pins: SDA0\_B, SCL0\_B, SDA1\_A, SCL1\_A, SDA1\_B, SCL1\_B.

The following pins do not require setting: SCL0\_A, SDA0\_A, SCL2, SDA2.

Item	Symbol	Min*1, *2	Max	Unit	Test conditions	
IIC (Standard mode, SMBus) ICFER.FMPE = 0	SCL input cycle time	$t_{SCL}$	$6 (12) \times t_{IICcyc} + 1300$	-	ns	Figure 2.52
	SCL input high pulse width	$t_{SCLH}$	$3 (6) \times t_{IICcyc} + 300$	-	ns	
	SCL input low pulse width	$t_{SCLL}$	$3 (6) \times t_{IICcyc} + 300$	-	ns	
	SCL, SDA input rise time	$t_{Sr}$	-	1000	ns	
	SCL, SDA input fall time	$t_{Sf}$	-	300	ns	
	SCL, SDA input spike pulse removal time	$t_{SP}$	0	$1 (4) \times t_{IICcyc}$	ns	
	SDA input bus free time when wakeup function is disabled	$t_{BUF}$	$3 (6) \times t_{IICcyc} + 300$	-	ns	
	SDA input bus free time when wakeup function is enabled	$t_{BUF}$	$3 (6) \times t_{IICcyc} + 4 \times t_{Pcyc} + 300$	-	ns	
	START condition input hold time when wakeup function is disabled	$t_{STAH}$	$t_{IICcyc} + 300$	-	ns	
	START condition input hold time when wakeup function is enabled	$t_{STAH}$	$1 (5) \times t_{IICcyc} + t_{Pcyc} + 300$	-	ns	
	Repeated START condition input setup time	$t_{STAS}$	1000	-	ns	
	STOP condition input setup time	$t_{STOS}$	1000	-	ns	
	Data input setup time	$t_{SDAS}$	$t_{IICcyc} + 50$	-	ns	
	Data input hold time	$t_{SDAH}$	0	-	ns	
SCL, SDA capacitive load	$C_b$	-	400	pF		

**Table 2.27 IIC timing (1) (2/2)**

Conditions: Middle drive output is selected in the port drive capability bit in the PmnPFS register for the following pins: SDA0\_B, SCL0\_B, SDA1\_A, SCL1\_A, SDA1\_B, SCL1\_B.

The following pins do not require setting: SCL0\_A, SDA0\_A, SCL2, SDA2.

Item	Symbol	Min*1, *2	Max	Unit	Test conditions	
IIC (Fast mode)	SCL input cycle time	$t_{SCL}$	$6 (12) \times t_{IICcyc} + 600$	-	ns	Figure 2.52
	SCL input high pulse width	$t_{SCLH}$	$3 (6) \times t_{IICcyc} + 300$	-	ns	
	SCL input low pulse width	$t_{SCLL}$	$3 (6) \times t_{IICcyc} + 300$	-	ns	
	SCL, SDA input rise time	$t_{Sr}$	$20 \times (\text{external pullup voltage}/5.5V)^2$	300	ns	
	SCL, SDA input fall time	$t_{Sf}$	$20 \times (\text{external pullup voltage}/5.5V)^2$	300	ns	
	SCL, SDA input spike pulse removal time	$t_{SP}$	0	$1 (4) \times t_{IICcyc}$	ns	
	SDA input bus free time when wakeup function is disabled	$t_{BUF}$	$3 (6) \times t_{IICcyc} + 300$	-	ns	
	SDA input bus free time when wakeup function is enabled	$t_{BUF}$	$3 (6) \times t_{IICcyc} + 4 \times t_{Pcyc} + 300$	-	ns	
	START condition input hold time when wakeup function is disabled	$t_{STAH}$	$t_{IICcyc} + 300$	-	ns	
	START condition input hold time when wakeup function is enabled	$t_{STAH}$	$1(5) \times t_{IICcyc} + t_{Pcyc} + 300$	-	ns	
	Repeated START condition input setup time	$t_{STAS}$	300	-	ns	
	STOP condition input setup time	$t_{STOS}$	300	-	ns	
	Data input setup time	$t_{SDAS}$	$t_{IICcyc} + 50$	-	ns	
	Data input hold time	$t_{SDAH}$	0	-	ns	
SCL, SDA capacitive load	$C_b$	-	400	pF		

Note:  $t_{IICcyc}$ : IIC internal reference clock (IIC $\phi$ ) cycle,  $t_{Pcyc}$ : PCLKB cycle.

Note 1. Values in parentheses apply when ICMR3.NF[1:0] is set to 11b while the digital filter is enabled with ICFER.NFE set to 1.

Note 2. Only supported for SCL0\_A, SDA0\_A, SCL2, and SDA2.

**Table 2.28 IIC timing (2)**

(1) Setting of the SCL0\_A, SDA0\_A pins is not required with the port drive capability bit in the PmnPFS register.

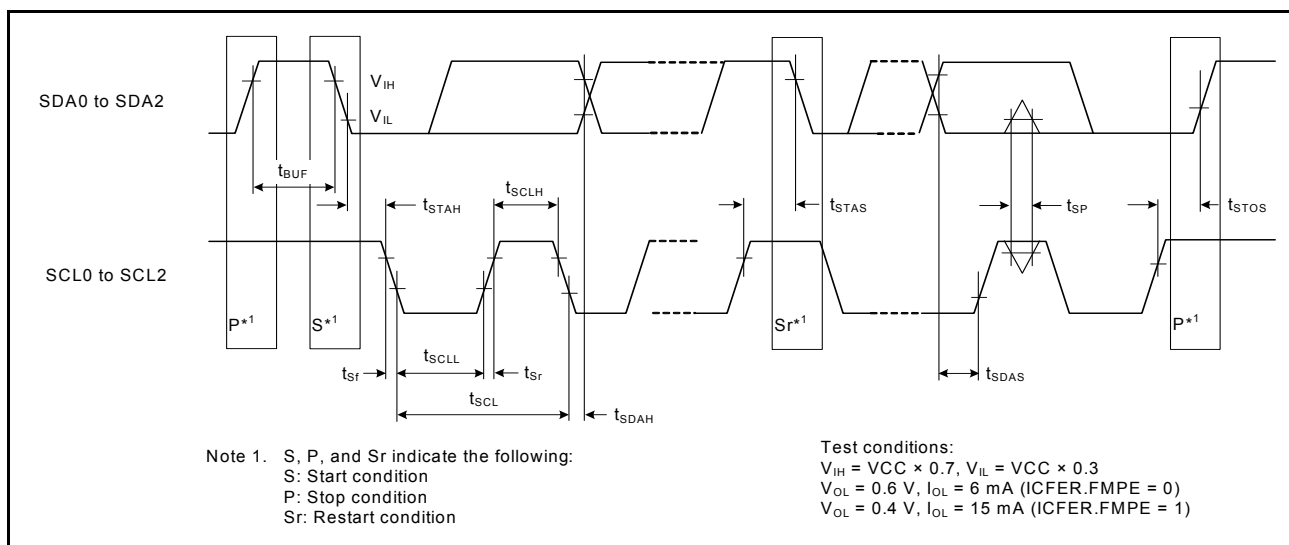
(2) Use pins that have a letter appended to their names, for instance “\_A” or “\_B”, to indicate group membership. For the IIC interface, the AC portion of the electrical characteristics is measured for each group.

Item	Symbol	Min <sup>*1,*2</sup>	Max	Unit	Test conditions	
IIC (Fast-mode+) ICFER.FMPE = 1	SCL input cycle time	$t_{SCL}$	$6 (12) \times t_{IICcyc} + 240$	-	ns	Figure 2.52
	SCL input high pulse width	$t_{SCLH}$	$3 (6) \times t_{IICcyc} + 120$	-	ns	
	SCL input low pulse width	$t_{SCLL}$	$3 (6) \times t_{IICcyc} + 120$	-	ns	
	SCL, SDA input rise time	$t_{Sr}$	-	120	ns	
	SCL, SDA input fall time	$t_{Sf}$	-	120	ns	
	SCL, SDA input spike pulse removal time	$t_{SP}$	0	$1 (4) \times t_{IICcyc}$	ns	
	SDA input bus free time when wakeup function is disabled	$t_{BUF}$	$3 (6) \times t_{IICcyc} + 120$	-	ns	
	SDA input bus free time when wakeup function is enabled	$t_{BUF}$	$3(6) \times t_{IICcyc} + 4 \times t_{Pcyc} + 120$	-	ns	
	Start condition input hold time when wakeup function is disabled	$t_{STAH}$	$t_{IICcyc} + 120$	-	ns	
	START condition input hold time when wakeup function is enabled	$t_{STAH}$	$1(5) \times t_{IICcyc} + t_{Pcyc} + 120$	-	ns	
	Restart condition input setup time	$t_{STAS}$	120	-	ns	
	Stop condition input setup time	$t_{STOS}$	120	-	ns	
	Data input setup time	$t_{SDAS}$	$t_{IICcyc} + 30$	-	ns	
	Data input hold time	$t_{SDAH}$	0	-	ns	
SCL, SDA capacitive load	$C_b$	-	550	pF		

Note:  $t_{IICcyc}$ : IIC internal reference clock (IIC $\phi$ ) cycle,  $t_{Pcyc}$ : PCLKB cycle.

Note 1. Values in parentheses apply when ICMR3.NF[1:0] is set to 11b while the digital filter is enabled with ICFER.NFE set to 1.

Note 2.  $C_b$  indicates the total capacity of the bus line.

**Figure 2.52 I<sup>2</sup>C bus interface input/output timing**

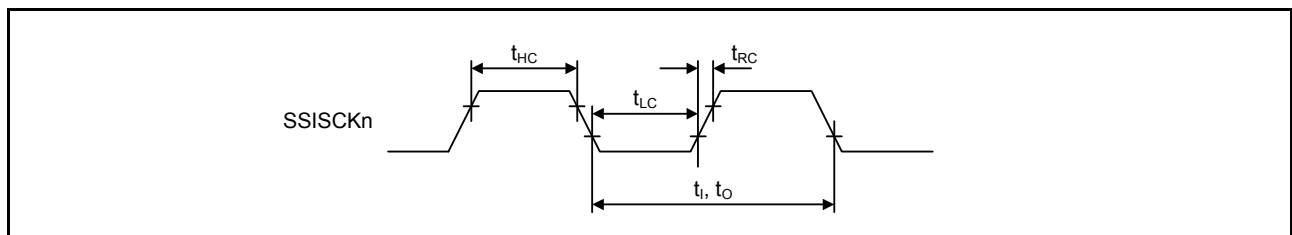
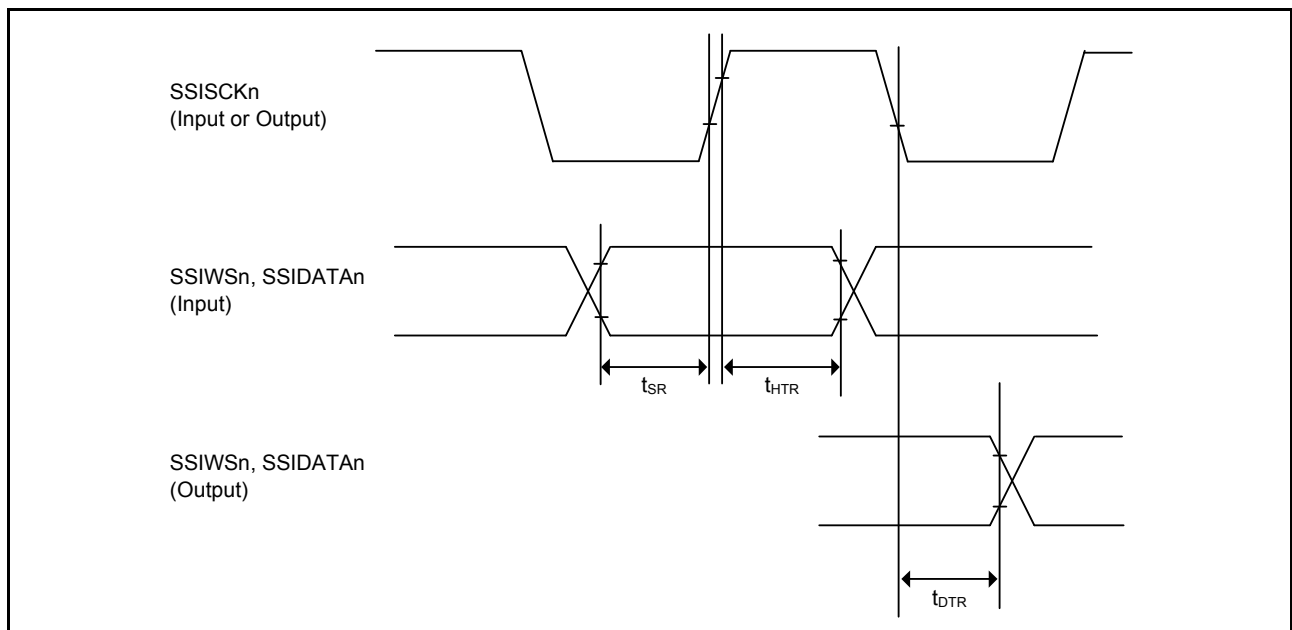
## 2.3.14 SSI Timing

**Table 2.29 SSI timing**

(1) Middle drive output is selected with the port drive capability bit in the PmnPFS register.

(2) Use pins that have a letter appended to their names, for instance “\_A” or “\_B”, to indicate group membership. For the SSI interface, the AC portion of the electrical characteristics is measured for each group.

Item	Symbol	Min	Max	Unit	Test conditions	
SSI	AUDIO_CLK input frequency	$t_{\text{AUDIO}}$	-	50	MHz	-
	Output clock period	$t_{\text{O}}$	150	64000	ns	Figure 2.53
	Input clock period	$t_{\text{I}}$	150	64000	ns	
	Clock high pulse width	$t_{\text{HC}}$	60	-	ns	
	Clock low pulse width	$t_{\text{LC}}$	60	-	ns	
	Clock rise time	$t_{\text{RC}}$	-	25	ns	
	Data delay	$t_{\text{DTR}}$	-5	25	ns	
	Set-up time	$t_{\text{SR}}$	25	-	ns	
	Hold time	$t_{\text{HTR}}$	25	-	ns	Figure 2.56
	SSIDATA output delay from WS change time	$T_{\text{DTRW}}$	-	25	ns	

**Figure 2.53 SSI clock input/output timing****Figure 2.54 SSI data transmit and receive timing when SSICR.SCKP = 0**

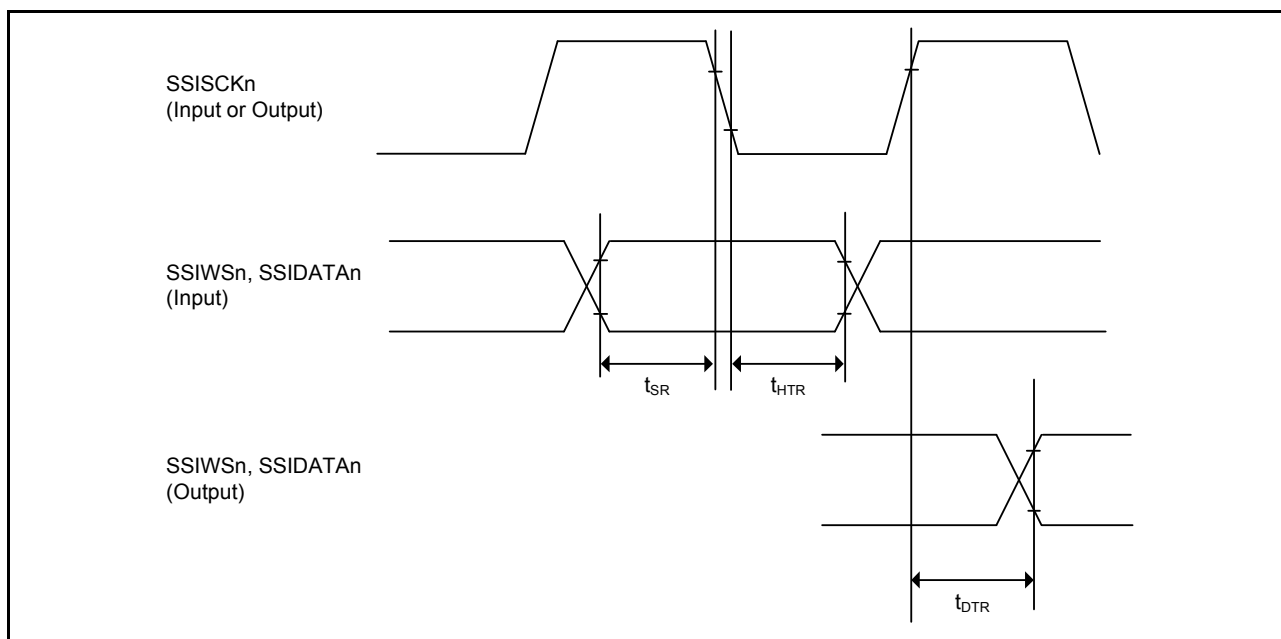


Figure 2.55 SSI data transmit and receive timing when SSICR.SCKP = 1

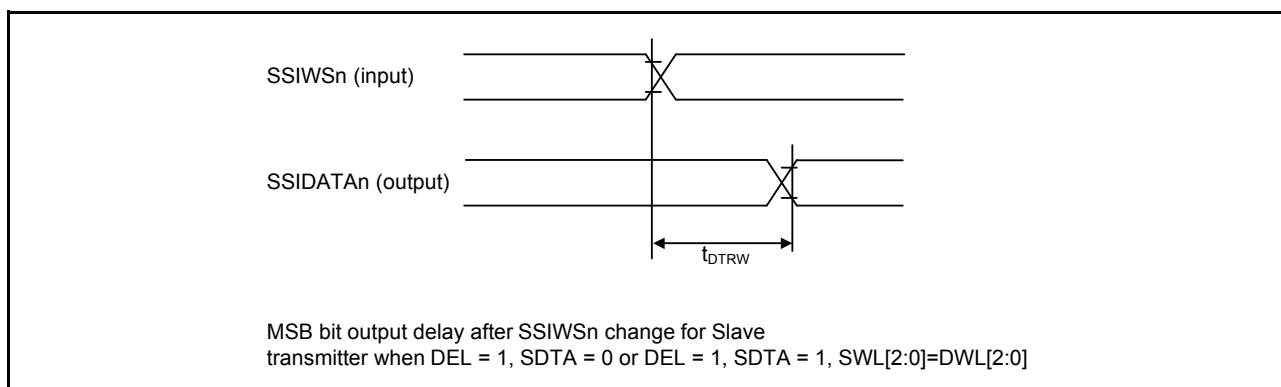


Figure 2.56 SSI data output delay after SSIWSn change

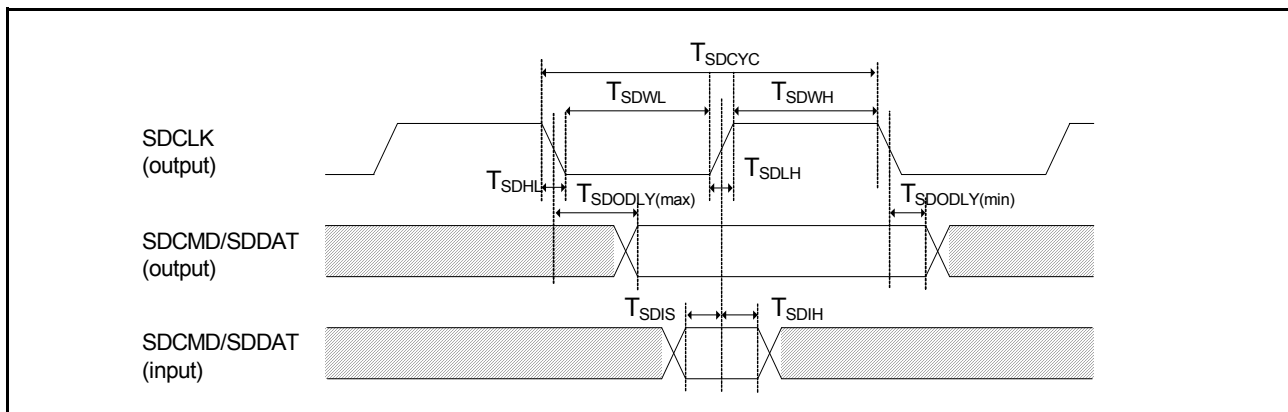
### 2.3.15 SD/MMC Host Interface Timing

Table 2.30 SD/MMC Host Interface signal timing

Conditions: High drive output is selected in the port drive capability bit in the PmnPFS register.  
Clock duty ratio is 50%.

Item	Symbol	Min	Max	Unit	Test conditions
SDCLK clock cycle	$T_{SDCYC}$	20	-	ns	Figure 2.57
SDCLK clock high pulse width	$T_{SDWH}$	6.5	-	ns	
SDCLK clock low pulse width	$T_{SDWL}$	6.5	-	ns	
SDCLK clock rise time	$T_{SDLH}$	-	3	ns	
SDCLK clock fall time	$T_{SDHL}$	-	3	ns	
SDCMD/SDDAT output data delay	$T_{SDODLY}$	-6	5	ns	
SDCMD/SDDAT input data setup	$T_{SDIS}$	4	-	ns	
SDCMD/SDDAT input data hold	$T_{SDIH}$	2	-	ns	





**Figure 2.57** SD/MMC Host Interface signal timing

### 2.3.16 ETHERC Timing

**Table 2.31** ETHERC timing

Conditions: ETHERC (RMII): Middle drive output is selected in the port drive capability bit in the PmnPFS register for the following pins: ET0\_MDC, ET0\_MDIO, ET1\_MDC, and ET1\_MDIO

For other pins, high drive output is selected in the port drive capability bit in the PmnPFS register.

ETHERC (MII): Middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Max	Unit	Test conditions	
ETHERC (RMII)	REF50CK cycle time	$T_{ck}$	20	-	ns	Figure 2.58 to Figure 2.61
	REF50CK frequency, typical 50 MHz	-	-	50 + 100 ppm	MHz	
	REF50CK duty	-	35	65	%	
	REF50CK rise/fall time	$T_{ckr/ckf}$	0.5	3.5	ns	
	RMII_XXXX*1 output delay	$T_{co}$	2.5	12.0	ns	
	RMII_XXXX*2 setup time	$T_{su}$	3	-	ns	
	RMII_XXXX*2 hold time	$T_{hd}$	1	-	ns	
	RMII_XXXX*1, *2 rise/fall time	$T_r/T_f$	0.4	4	ns	
	ET_WOL output delay	$t_{WOLd}$	1	23.5	ns	Figure 2.62
ETHERC (MII)	ET_TX_CLK cycle time	$t_{Tcyc}$	40	-	ns	-
	ET_TX_EN output delay	$t_{TENd}$	1	20	ns	Figure 2.63
	ET_ETXD0 to ET_ETXD3 output delay	$t_{MTDd}$	1	20	ns	Figure 2.64
	ET_CRs setup time	$t_{CRSs}$	10	-	ns	
	ET_CRs hold time	$t_{CRSh}$	10	-	ns	
	ET_COL setup time	$t_{COLs}$	10	-	ns	
	ET_COL hold time	$t_{COLh}$	10	-	ns	
	ET_RX_CLK cycle time	$t_{TRcyc}$	40	-	ns	
	ET_RX_DV setup time	$t_{RDVs}$	10	-	ns	Figure 2.65
	ET_RX_DV hold time	$t_{RDVh}$	10	-	ns	Figure 2.66
	ET_ERXD0 to ET_ERXD3 setup time	$t_{MRDs}$	10	-	ns	
	ET_ERXD0 to ET_ERXD3 hold time	$t_{MRDh}$	10	-	ns	
	ET_RX_ER setup time	$t_{RErs}$	10	-	ns	
	ET_RX_ER hold time	$t_{RESh}$	10	-	ns	
	ET_WOL output delay	$t_{WOLd}$	1	23.5	ns	Figure 2.67

Note 1. RMII\_TXD\_EN, RMII\_TXD1, RMII\_TXD0.

Note 2. RMII\_CRs\_DV, RMII\_RXD1, RMII\_RXD0, RMII\_RX\_ER.

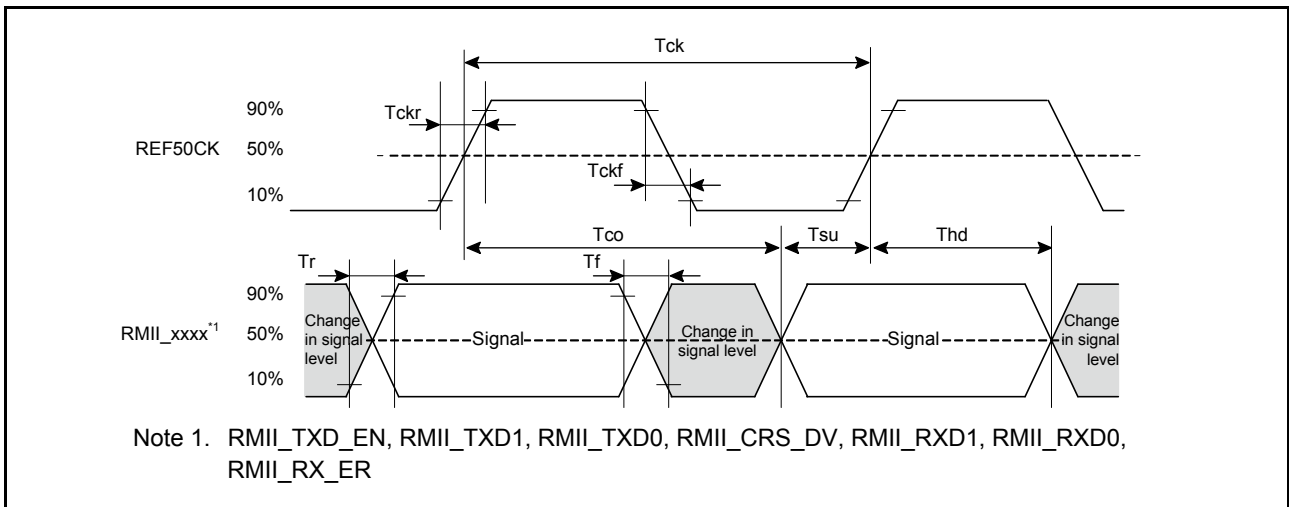


Figure 2.58 REF50CK and RMII signal timing

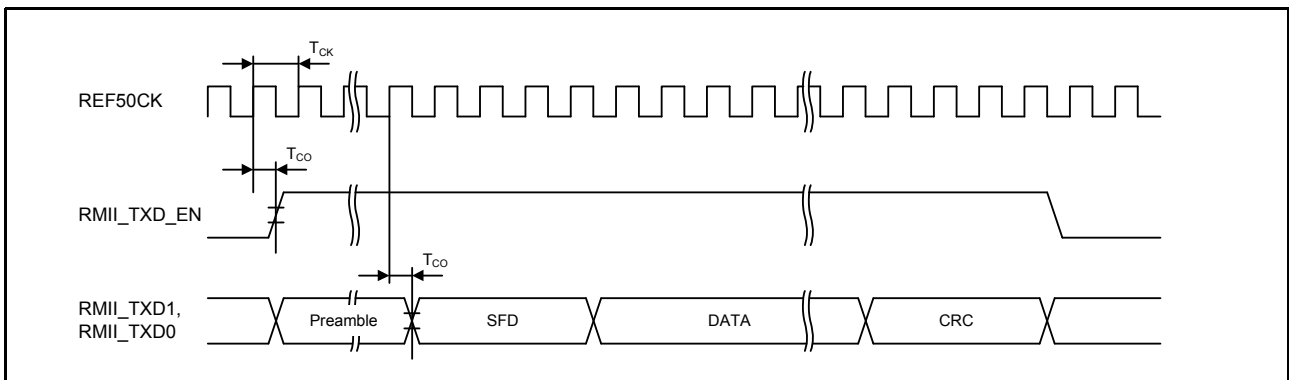


Figure 2.59 RMII transmission timing

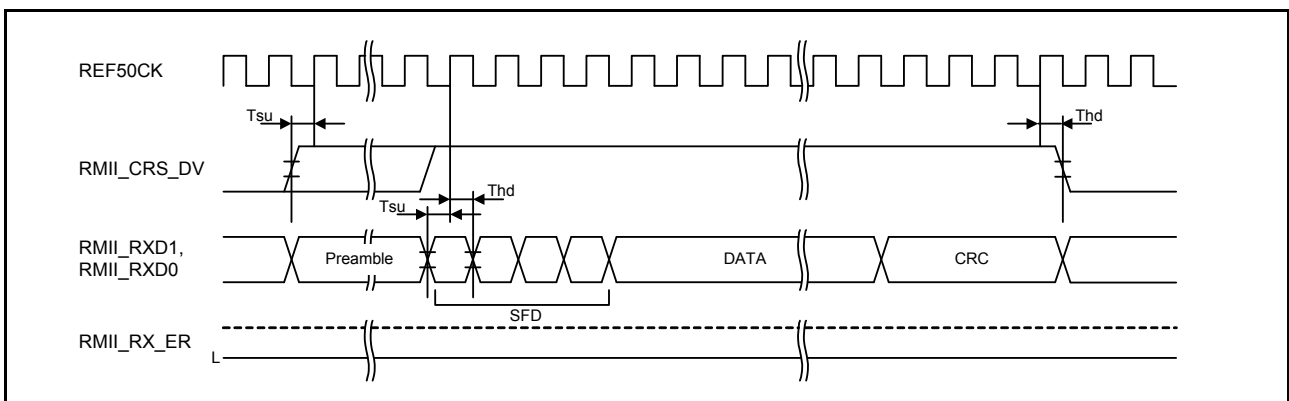


Figure 2.60 RMII reception timing in normal operation

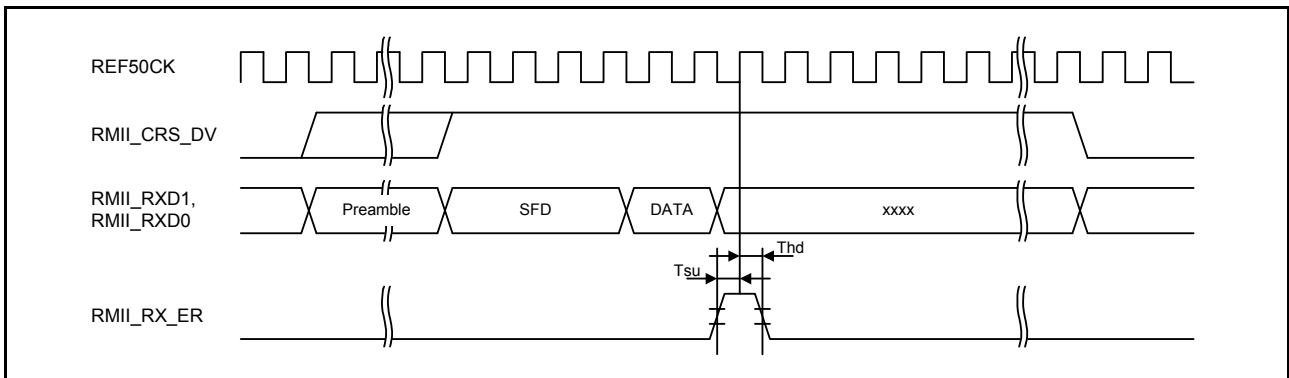


Figure 2.61 RMII reception timing when an error occurs

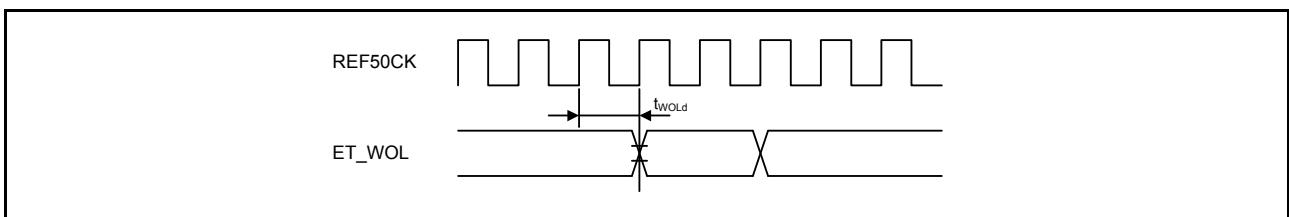


Figure 2.62 WOL output timing for RMII

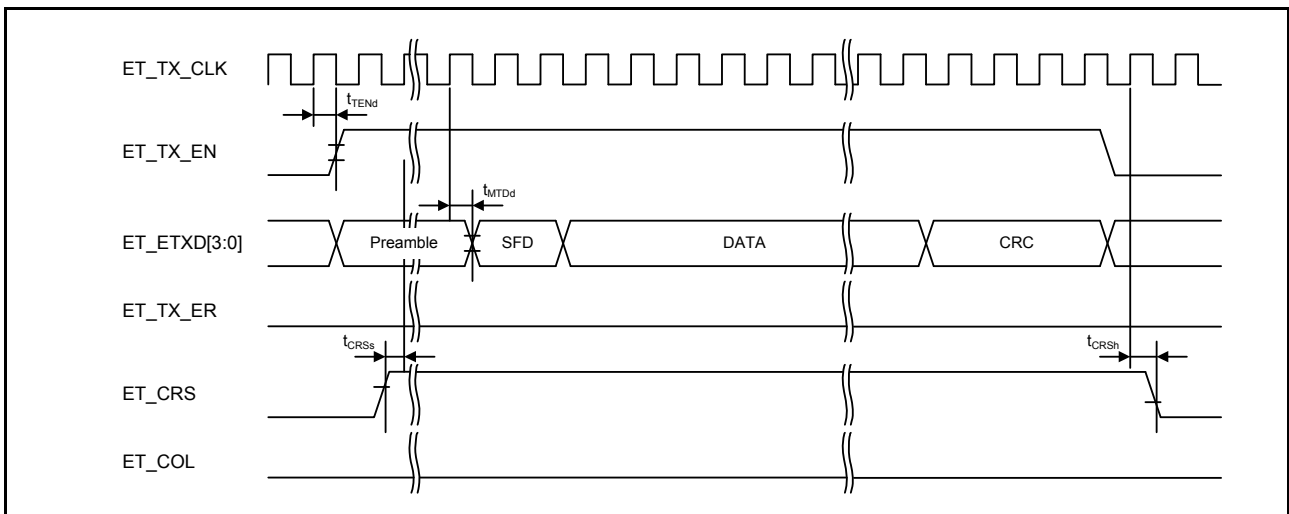


Figure 2.63 MII transmission timing in normal operation

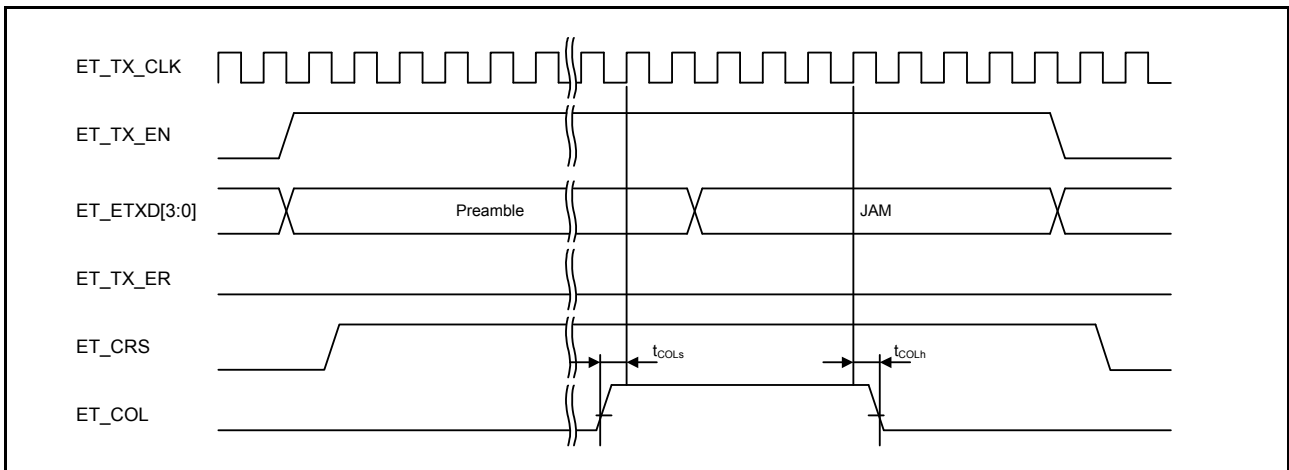


Figure 2.64 MII transmission timing when a conflict occurs

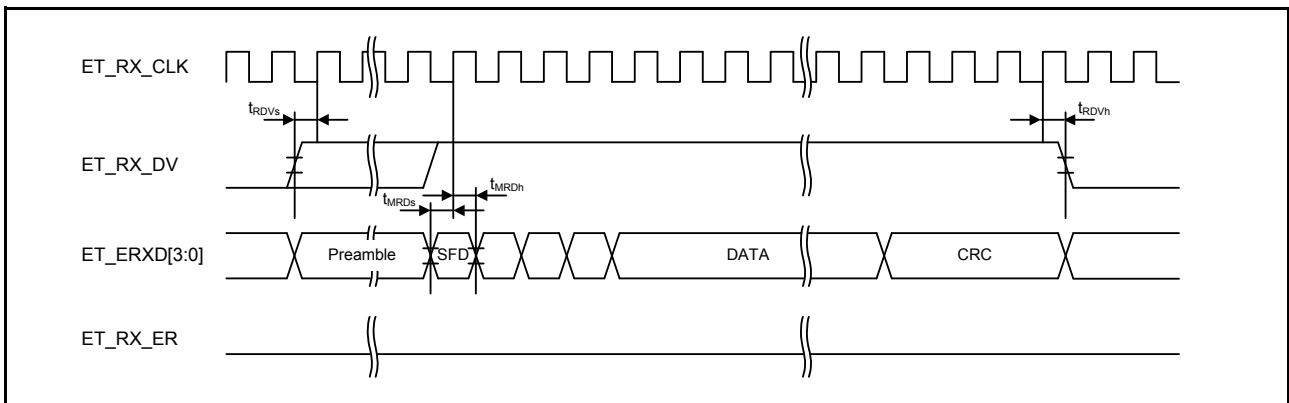


Figure 2.65 MII reception timing in normal operation

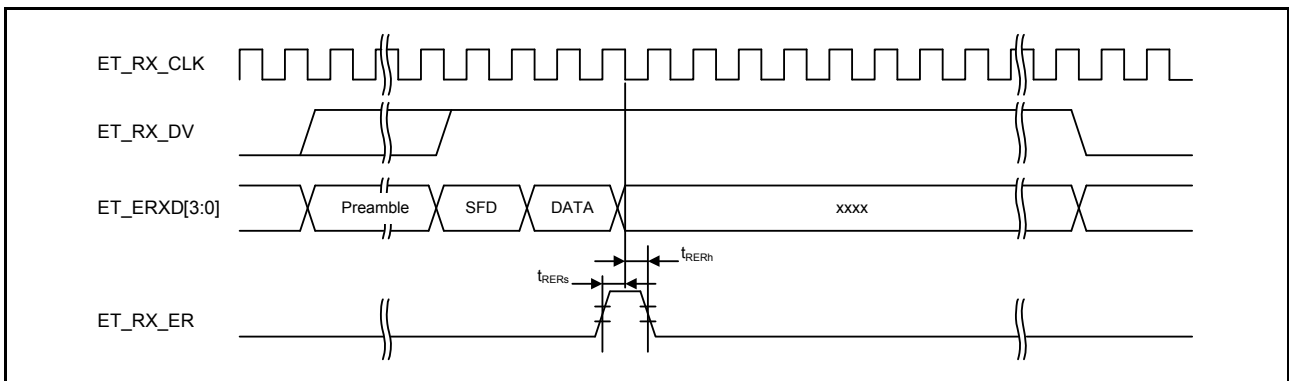


Figure 2.66 MII reception timing when an error occurs

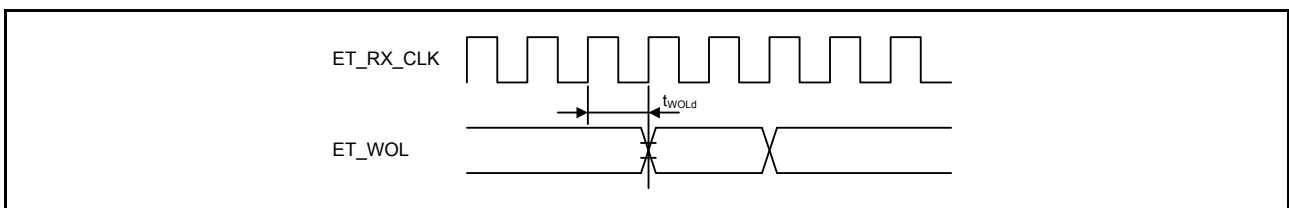


Figure 2.67 WOL output timing for MII

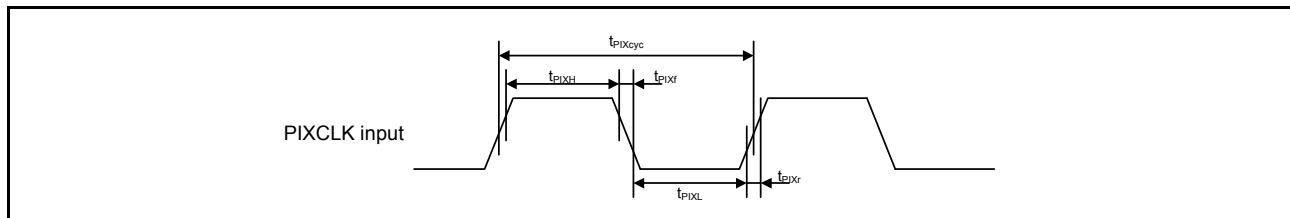
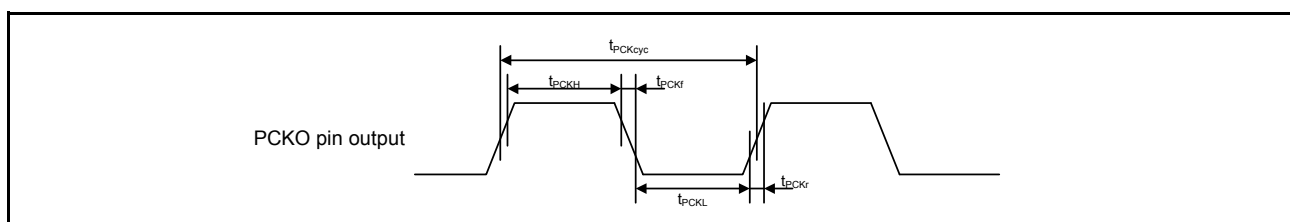
## 2.3.17 PDC Timing

**Table 2.32 PDC timing**

Conditions: Middle drive output is selected in the port drive capability bit in the PmnPFS register.  
Output load conditions:  $V_{OH} = V_{CC} \times 0.5$ ,  $V_{OL} = V_{CC} \times 0.5$ ,  $C = 30$  pF

Item	Symbol	Min	Max	Unit	Test conditions	
PDC	PIXCLK input cycle time	$t_{PIXcyc}$	37	-	ns	Figure 2.68
	PIXCLK input high pulse width	$t_{PIXH}$	10	-	ns	
	PIXCLK input low pulse width	$t_{PIXL}$	10	-	ns	
	PIXCLK rise time	$t_{PIXr}$	-	5	ns	
	PIXCLK fall time	$t_{PIXf}$	-	5	ns	
PDC	PCKO output cycle time	$t_{PCKcyc}$	$2 \times t_{PBcyc}$	-	ns	Figure 2.69
	PCKO output high pulse width	$t_{PCKH}$	$(t_{PCKcyc} - t_{PCKr} - t_{PCKf})/2 - 3$	-	ns	
	PCKO output low pulse width	$t_{PCKL}$	$(t_{PCKcyc} - t_{PCKr} - t_{PCKf})/2 - 3$	-	ns	
	PCKO rise time	$t_{PCKr}$	-	5	ns	
	PCKO fall time	$t_{PCKf}$	-	5	ns	
PDC	VSYNV/HSYNC input setup time	$t_{SYNCS}$	10	-	ns	Figure 2.70
	VSYNV/HSYNC input hold time	$t_{SYNCH}$	5	-	ns	
	PIXD input setup time	$t_{PIXDS}$	10	-	ns	
	PIXD input hold time	$t_{PIXDH}$	5	-	ns	

Note 1.  $t_{PBcyc}$ : PCLKB cycle.

**Figure 2.68 PDC input clock timing****Figure 2.69 PDC output clock timing**

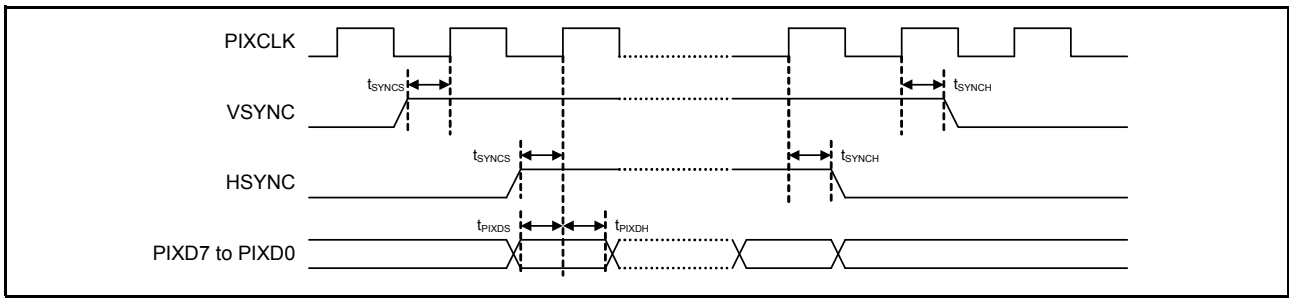


Figure 2.70 PDC AC timing

### 2.3.18 Graphics LCD Controller Timing

Table 2.33 Graphics LCD Controller timing

Conditions:

LCD\_CLK: High drive output is selected in the port drive capability bit in the PmnPFS register.

LCD\_DATA: Middle drive output is selected in the port drive capability bit in the PmnPFS register.

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
LCD_EXTCLK input clock frequency	$t_{Ecyc}$	-	-	60*1	MHz	Figure 2.71	
LCD_EXTCLK input clock low pulse width	$t_{WL}$	0.45	-	0.55	$t_{Ecyc}$		
LCD_EXTCLK input clock high pulse width	$t_{WH}$	0.45	-	0.55	$t_{Ecyc}$		
LCD_CLK output clock frequency	$t_{Lcyc}$	-	-	60*1	MHz	Figure 2.72	
LCD_CLK output clock low pulse width	$t_{LOL}$	0.4	-	0.6	$t_{Lcyc}$	Figure 2.72	
LCD_CLK output clock high pulse width	$t_{LOH}$	0.4	-	0.6	$t_{Lcyc}$	Figure 2.72	
LCD data output delay timing	$t_{DD}$	_A or _B combinations*2	-3.5	-	4	ns	Figure 2.73
		_A and _B combinations*3	-5.0	-	5.5		
LCD data output rise time (0.8 to 2.0 V)	$t_{Dr}$	-	-	2		Figure 2.74	
LCD data output fall time (2.0 to 0.8 V)	$t_{Df}$	-	-	2			

Note 1. Parallel RGB888, 666,565: Maximum 54 MHz  
Serial RGB888: Maximum 60 MHz (4x speed)

Note 2. Use pins that have a letter appended to their names, for instance, “\_A” or “\_B”, to indicate

Note 3. Pins of group “\_A” and “\_B” combinations are used.

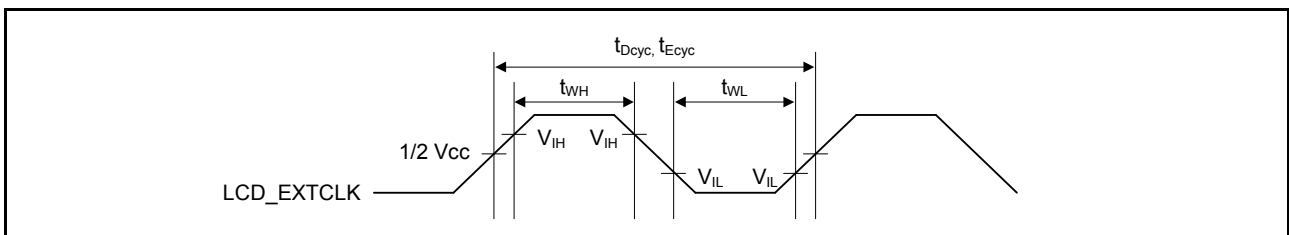


Figure 2.71 LCD\_EXTCLK clock input timing

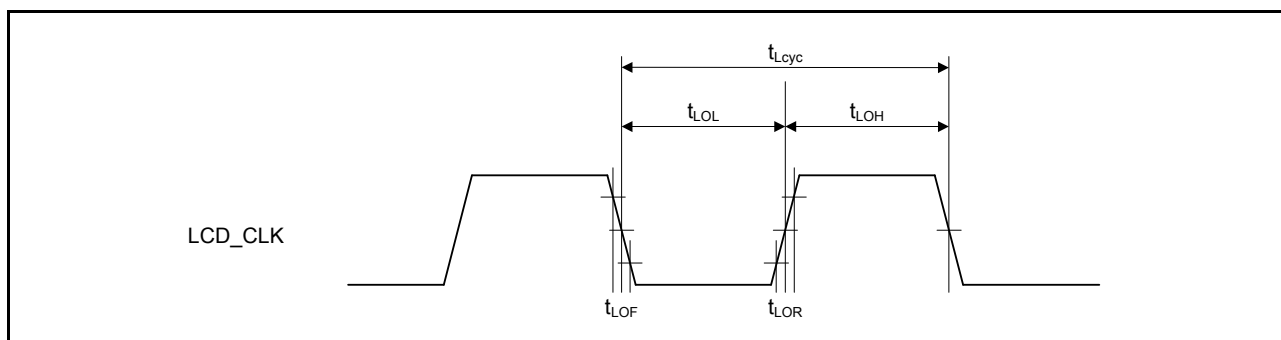


Figure 2.72 LCD\_CLK clock output timing

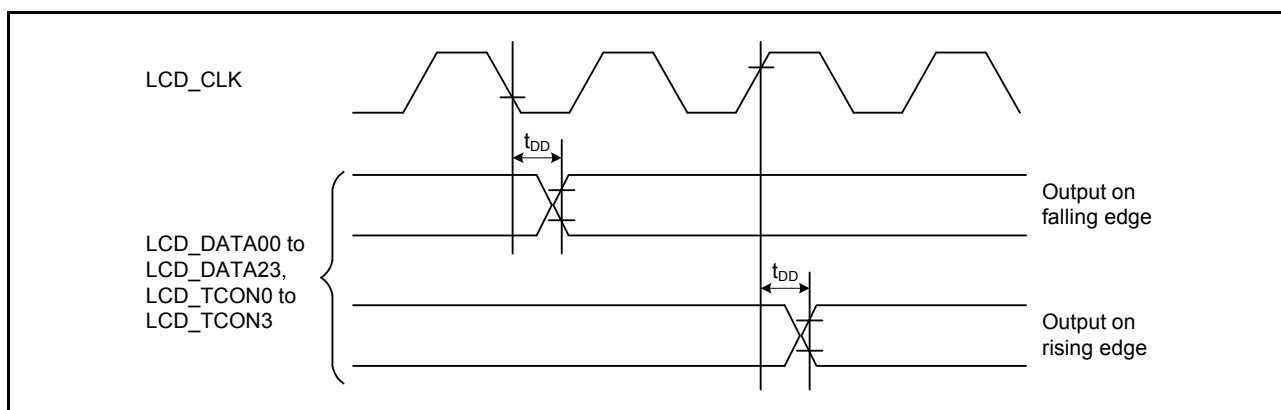


Figure 2.73 Display output timing

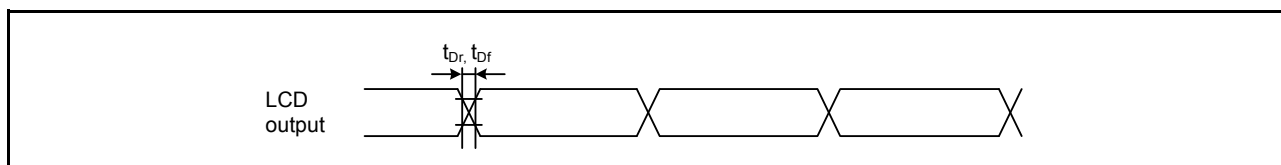


Figure 2.74 LCD output rise and fall times

## 2.4 USB Characteristics

### 2.4.1 USBHS Timing

Table 2.34 USBHS low-speed characteristics for host only (USBHS\_DP and USBHS\_DM pin characteristics) (1/2)

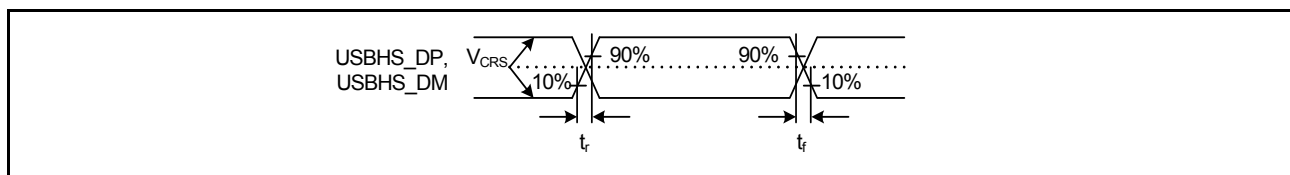
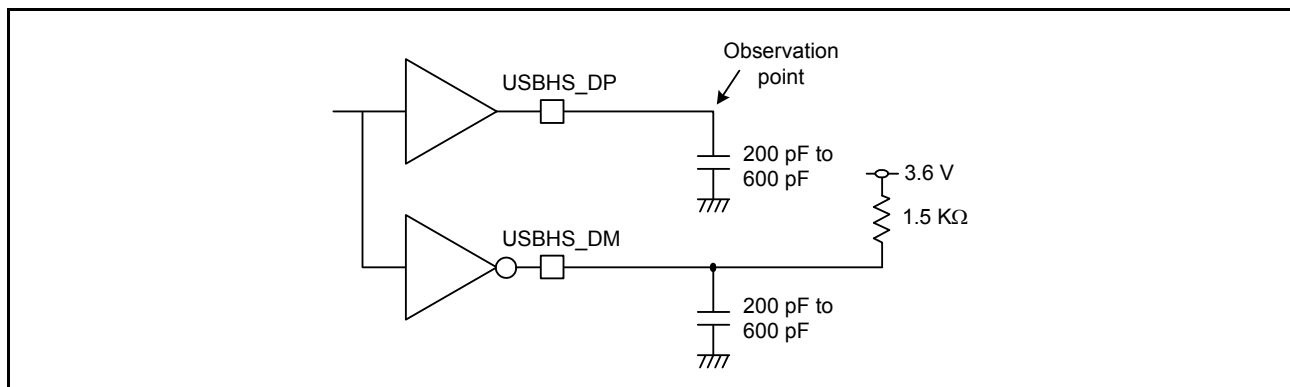
Conditions: USBHS\_RREF = 2.2 kΩ ± 1%, USBMCLK = 20/24 MHz, UCLK = 48 MHz

Item		Symbol	Min	Typ	Max	Unit	Test conditions	
Input characteristics	Input high voltage	$V_{IH}$	2.0	-	-	V	-	-
	Input low voltage	$V_{IL}$	-	-	0.8	V	-	-
	Differential input sensitivity	$V_{DI}$	0.2	-	-	V	USBHS_DP - USBHS_DM	-
	Differential common-mode range	$V_{CM}$	0.8	-	2.5	V	-	-

**Table 2.34 USBHS low-speed characteristics for host only (USBHS\_DP and USBHS\_DM pin characteristics) (2/2)**

Conditions: USBHS\_RREF = 2.2 kΩ ± 1%, USBMCLK = 20/24 MHz, UCLK = 48 MHz

Item		Symbol	Min	Typ	Max	Unit	Test conditions
Output characteristics	Output high voltage	$V_{OH}$	2.8	-	3.6	V	$I_{OH} = -200 \mu A$
	Output low voltage	$V_{OL}$	0.0	-	0.3	V	$I_{OL} = 2 \text{ mA}$
	Cross-over voltage	$V_{CRS}$	1.3	-	2.0	V	-
	Rise time	$t_{LR}$	75	-	300	ns	-
	Fall time	$t_{LF}$	75	-	300	ns	-
	Rise/fall time ratio	$t_{LR} / t_{LF}$	80	-	125	%	$t_{LR} / t_{LF}$
Pull-up, Pull-down characteristics	USBHS_DP and USBHS_DM pull-down resistors (host)	$R_{pd}$	14.25	-	24.80	kΩ	-

**Figure 2.75 USBHS\_DP and USBHS\_DM output timing in low-speed mode****Figure 2.76 Test circuit in low-speed mode****Table 2.35 USBHS full-speed characteristics (USBHS\_DP and USBHS\_DM pin characteristics) (1/2)**

Conditions: USBHS\_RREF = 2.2 kΩ ± 1%, USBMCLK = 20/24 MHz, UCLK = 48 MHz

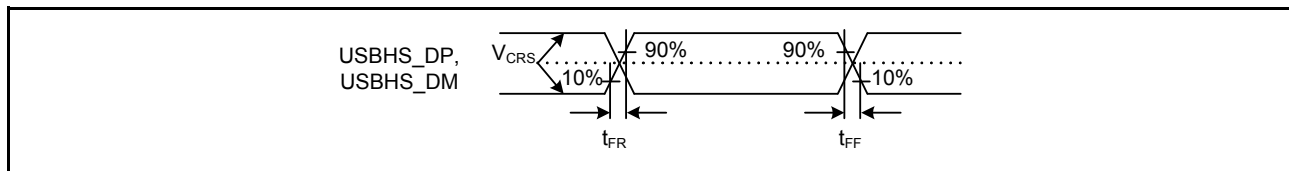
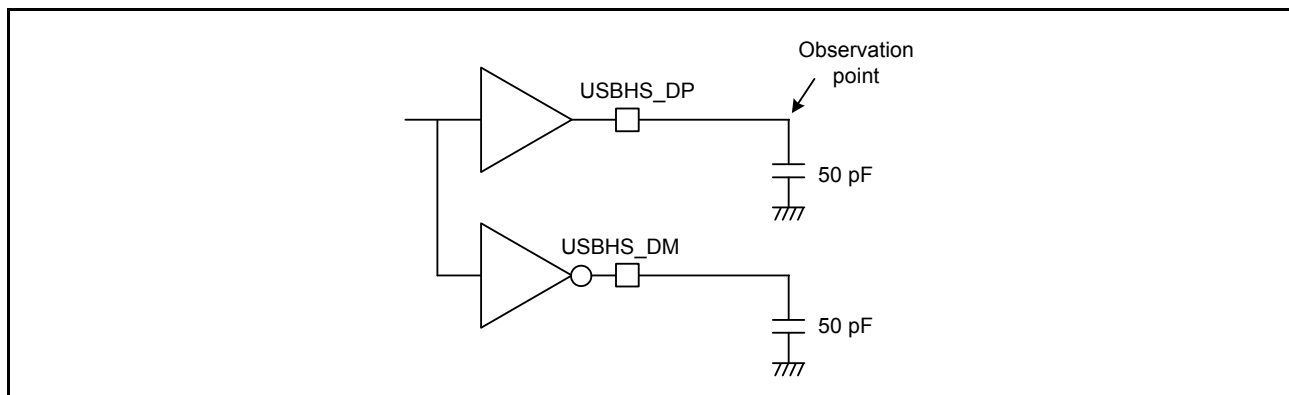
Item		Symbol	Min	Typ	Max	Unit	Test conditions
Input characteristics	Input high voltage	$V_{IH}$	2.0	-	-	V	-
	Input low voltage	$V_{IL}$	-	-	0.8	V	-
	Differential input sensitivity	$V_{DI}$	0.2	-	-	V	$  \text{USBHS\_DP} - \text{USBHS\_DM}  $
	Differential common-mode range	$V_{CM}$	0.8	-	2.5	V	-



**Table 2.35 USBHS full-speed characteristics (USBHS\_DP and USBHS\_DM pin characteristics) (2/2)**

Conditions: USBHS\_RREF = 2.2 kΩ ± 1%, USBMCLK = 20/24 MHz, UCLK = 48 MHz

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
Output characteristics	Output high voltage	$V_{OH}$	2.8	-	3.6	V	$I_{OH} = -200 \mu\text{A}$
	Output low voltage	$V_{OL}$	0.0	-	0.3	V	$I_{OL} = 2 \text{ mA}$
	Cross-over voltage	$V_{CRS}$	1.3	-	2.0	V	-
	Rise time	$t_{LR}$	4	-	20	ns	-
	Fall time	$t_{LF}$	4	-	20	ns	-
	Rise/fall time ratio	$t_{LR} / t_{LF}$	90	-	111.11	%	$t_{FR} / t_{FF}$
	Output resistance	$Z_{DRV}$	40.5	-	49.5	Ω	Rs Not used (PHYSET.REPSEL[1:0] = 01b and PHYSET.HSEB = 0)
DC characteristics	USBHS_DM pull-up resistor (device)	$R_{pu}$	0.900	-	1.575	kΩ	During idle state
			1.425	-	3.090	kΩ	During transmission and reception
	USBHS_DP/USBHS_DM pull-down resistor (host)	$R_{pd}$	14.25	-	24.80	kΩ	-

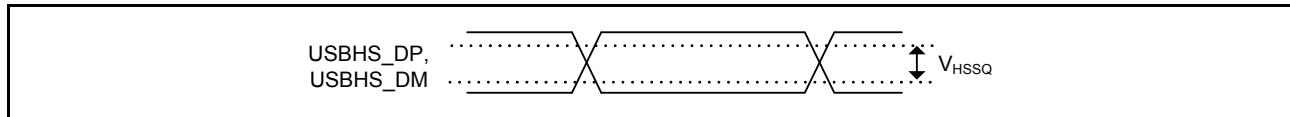
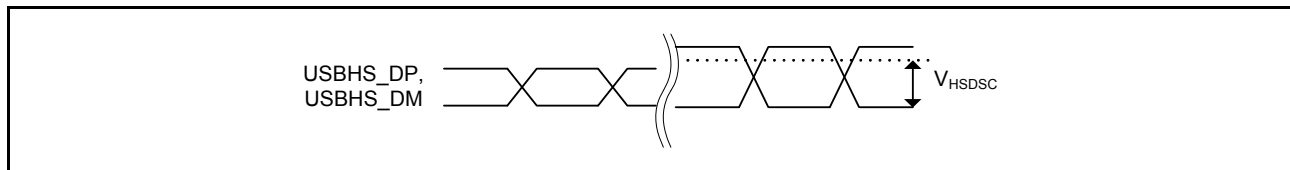
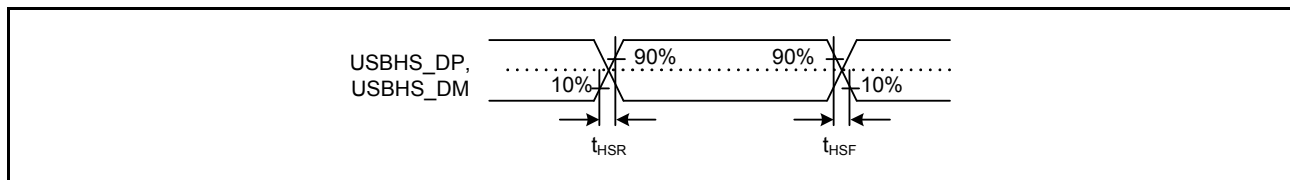
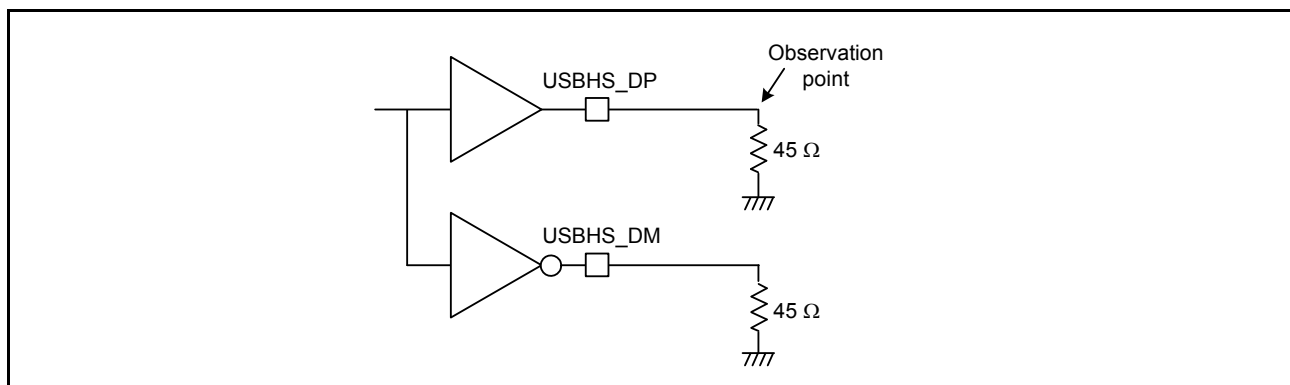
**Figure 2.77 USBHS\_DP and USBHS\_DM output timing in full-speed mode****Figure 2.78 Test circuit in full-speed mode****Table 2.36 USBHS high-speed characteristics (USBHS\_DP and USBHS\_DM pin characteristics) (1/2)**

Conditions: USBHS\_RREF = 2.2 kΩ ± 1%, USBMCLK = 20/24 MHz

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
Input characteristics	Squelch detect sensitivity	$V_{HSSQ}$	100	-	150	mV	Figure 2.79
	Disconnect detect sensitivity	$V_{HSDSC}$	525	-	625	mV	Figure 2.80
	Common-mode voltage	$V_{HSCM}$	-50	-	500	mV	-
Output characteristics	Idle state	$V_{HSOI}$	-10.0	-	10	mV	-
	Output high voltage	$V_{HSOH}$	360	-	440	mV	-
	Output low voltage	$V_{HSOL}$	-10.0	-	10	mV	-
	Chirp J output voltage (difference)	$V_{CHIRPJ}$	700	-	1100	mV	-
	Chirp K output voltage (difference)	$V_{CHIRPK}$	-900	-	-500	mV	-

**Table 2.36 USBHS high-speed characteristics (USBHS\_DP and USBHS\_DM pin characteristics) (2/2)**Conditions: USBHS\_RREF = 2.2 k $\Omega$   $\pm$  1%, USBMCLK = 20/24 MHz

Item		Symbol	Min	Typ	Max	Unit	Test conditions
AC characteristics	Rise time	$t_{HSR}$	500	-	-	ps	Figure 2.81
	Fall time	$t_{HSF}$	500	-	-	ps	
	Output resistance	$Z_{HSDRV}$	40.5	-	49.5	$\Omega$	-

**Figure 2.79 USBHS\_DP and USBHS\_DM squelch detect sensitivity in high-speed mode****Figure 2.80 USBHS\_DP and USBHS\_DM disconnect detect sensitivity in high-speed mode****Figure 2.81 USBHS\_DP and USBHS\_DM output timing in high-speed mode****Figure 2.82 Test circuit in high-speed mode****Table 2.37 USBHS high-speed characteristics (USBHS\_DP and USBHS\_DM pin characteristics)**Conditions: USBHS\_RREF = 2.2 k $\Omega$   $\pm$  1%, USBMCLK = 20/24 MHz

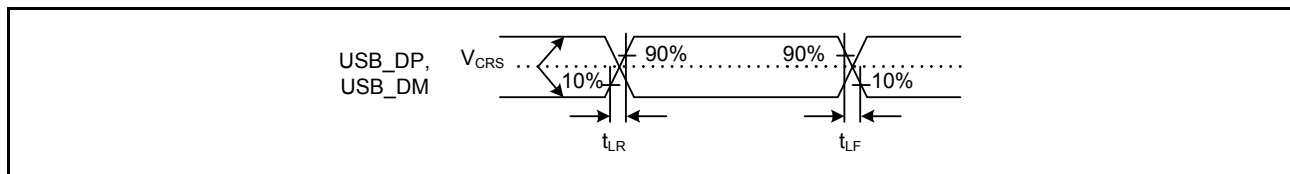
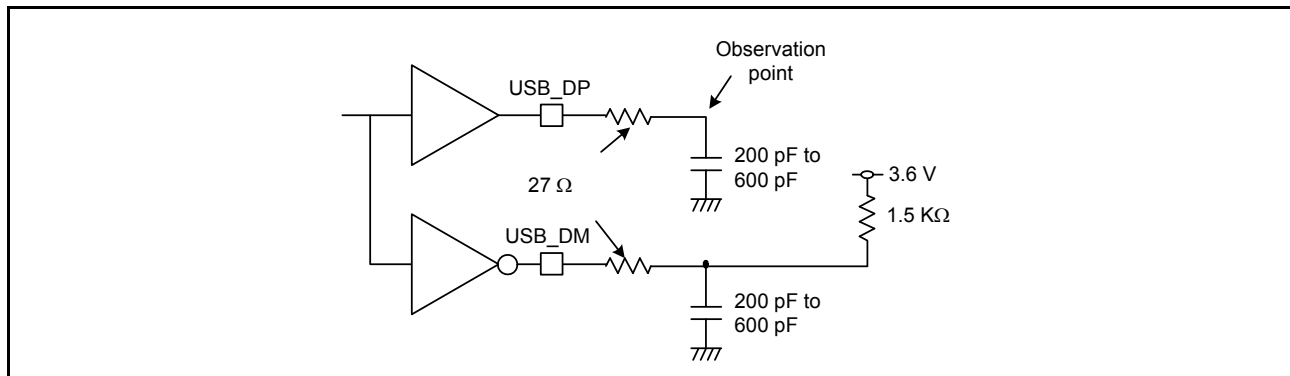
Item		Symbol	Min	Max	Unit	Test conditions
Battery Charging Specification	D+ sink current	$I_{DP\_SINK}$	25	175	$\mu$ A	-
	D- sink current	$I_{DM\_SINK}$	25	175	$\mu$ A	-
	DCD source current	$I_{DP\_SRC}$	7	13	$\mu$ A	-
	Data detection voltage	$V_{DAT\_REF}$	0.25	0.4	V	-
	D+ source voltage	$V_{DP\_SRC}$	0.5	0.7	V	Output current = 250 $\mu$ A
	D- source voltage	$V_{DM\_SRC}$	0.5	0.7	V	Output current = 250 $\mu$ A

## 2.4.2 USBFS Timing

**Table 2.38 USBFS low-speed characteristics for host only (USB\_DP and USB\_DM pin characteristics)**

Conditions:  $V_{CC} = AV_{CC0} = V_{CC\_USB} = V_{BATT} = 3.0$  to  $3.6$  V,  $2.7 \leq V_{REFH0}/V_{REFH} \leq AV_{CC0}$ ,  $V_{CC\_USBHS} = AV_{CC\_USBHS} = 3.0$  to  $3.6$  V,  $USBA\_RREF = 2.2$  k $\Omega \pm 1\%$ ,  $USBMCLK = 20/24$  MHz,  $UCLK = 48$  MHz

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
Input characteristics	Input high voltage	$V_{IH}$	2.0	-	-	V	-
	Input low voltage	$V_{IL}$	-	-	0.8	V	-
	Differential input sensitivity	$V_{DI}$	0.2	-	-	V	USB_DP - USB_DM
	Differential common-mode range	$V_{CM}$	0.8	-	2.5	V	-
Output characteristics	Output high voltage	$V_{OH}$	2.8	-	3.6	V	$I_{OH} = -200$ $\mu$ A
	Output low voltage	$V_{OL}$	0.0	-	0.3	V	$I_{OL} = 2$ mA
	Cross-over voltage	$V_{CRS}$	1.3	-	2.0	V	Figure 2.83
	Rise time	$t_{LR}$	75	-	300	ns	
	Fall time	$t_{LF}$	75	-	300	ns	
	Rise/fall time ratio	$t_{LR} / t_{LF}$	80	-	125	%	$t_{LR} / t_{LF}$
Pull-up and pull-down characteristics	USB_DP and USB_DM pull-down resistance in host controller mode	$R_{pd}$	14.25	-	24.80	k $\Omega$	-

**Figure 2.83 USB\_DP and USB\_DM output timing in low-speed mode****Figure 2.84 Test circuit in low-speed mode****Table 2.39 USBFS full-speed characteristics (USB\_DP and USB\_DM pin characteristics) (1/2)**

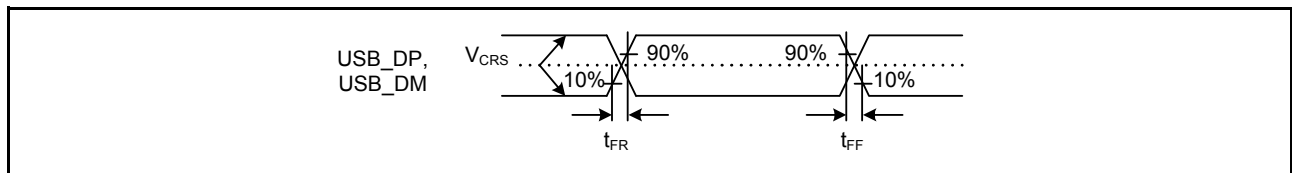
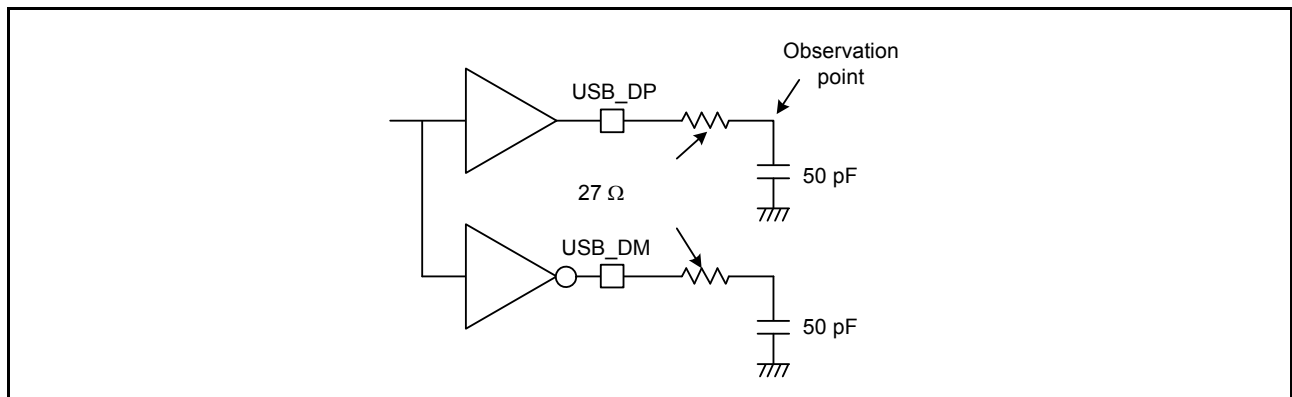
Conditions:  $V_{CC} = AV_{CC0} = V_{CC\_USB} = V_{BATT} = 3.0$  to  $3.6$  V,  $2.7 \leq V_{REFH0}/V_{REFH} \leq AV_{CC0}$ ,  $V_{CC\_USBHS} = AV_{CC\_USBHS} = 3.0$  to  $3.6$  V,  $USBA\_RREF = 2.2$  k $\Omega \pm 1\%$ ,  $USBMCLK = 20/24$  MHz,  $UCLK = 48$  MHz

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
Input characteristics	Input high voltage	$V_{IH}$	2.0	-	-	V	-
	Input low voltage	$V_{IL}$	-	-	0.8	V	-
	Differential input sensitivity	$V_{DI}$	0.2	-	-	V	USB_DP - USB_DM
	Differential common-mode range	$V_{CM}$	0.8	-	2.5	V	-

**Table 2.39 USBFS full-speed characteristics (USB\_DP and USB\_DM pin characteristics) (2/2)**

Conditions:  $V_{CC} = AV_{CC0} = V_{CC\_USB} = V_{BATT} = 3.0$  to  $3.6$  V,  $2.7 \leq V_{REFH0}/V_{REFH} \leq AV_{CC0}$ ,  $V_{CC\_USBHS} = AV_{CC\_USBHS} = 3.0$  to  $3.6$  V,  $USBA\_RREF = 2.2$  k $\Omega \pm 1\%$ ,  $USBMCLK = 20/24$  MHz,  $UCLK = 48$  MHz

Item	Symbol	Min	Typ	Max	Unit	Test conditions	
Output characteristics	Output high voltage	$V_{OH}$	2.8	-	3.6	V	$I_{OH} = -200 \mu A$
	Output low voltage	$V_{OL}$	0.0	-	0.3	V	$I_{OL} = 2$ mA
	Cross-over voltage	$V_{CRS}$	1.3	-	2.0	V	Figure 2.85
	Rise time	$t_{LR}$	4	-	20	ns	
	Fall time	$t_{LF}$	4	-	20	ns	
	Rise/fall time ratio	$t_{LR} / t_{LF}$	90	-	111.11	%	$t_{FR} / t_{FF}$
	Output resistance	$Z_{DRV}$	28	-	44	$\Omega$	USBFS: $R_s = 27 \Omega$ included
Pull-up and pull-down characteristics	DM pull-up resistance in device controller mode	$R_{pu}$	0.900	-	1.575	k $\Omega$	During idle state
			1.425	-	3.090	k $\Omega$	During transmission and reception
	USB_DP and USB_DM pull-down resistance in host controller mode	$R_{pd}$	14.25	-	24.80	k $\Omega$	-

**Figure 2.85 USB\_DP and USB\_DM output timing in full-speed mode****Figure 2.86 Test circuit in full-speed mode**

## 2.5 ADC12 Characteristics

[Normal-precision channel]

**Table 2.40 A/D conversion characteristics for unit 0 (1/2)**

Conditions:  $PCLKC = 1$  to  $60$  MHz

Item	Min	Typ	Max	Unit	Test conditions
Frequency	1	-	60	MHz	-
Analog input capacitance	-	-	30	pF	-
Quantization error	-	$\pm 0.5$	-	LSB	-
Resolution	-	-	12	Bits	-

**Table 2.40 A/D conversion characteristics for unit 0 (2/2)**

Conditions: PCLKC = 1 to 60 MHz

Item			Min	Typ	Max	Unit	Test conditions
Channel-dedicated sample-and-hold circuits in use (AN000 to AN002)	Conversion time*1 (operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	1.06 (0.4 + 0.25)*2	-	-	μs	<ul style="list-style-type: none"> <li>Sampling of channel-dedicated sample-and-hold circuits in 24 states</li> <li>Sampling in 15 states</li> </ul>
	Offset error		-	±1.5	±3.5	LSB	AN000 to AN002 = 0.25 V
	Full-scale error		-	±1.5	±3.5	LSB	AN000 to AN002 = VREFH0- 0.25 V
	Absolute accuracy		-	±2.5	±5.5	LSB	-
	DNL differential nonlinearity error		-	±1.0	±2.0	LSB	-
	INL integral nonlinearity error		-	±1.5	±3.0	LSB	-
	Holding characteristics of sample-and hold circuits		-	-	20	μs	-
	Dynamic range		0.25	-	VREFH 0-0.25	V	-
Channel-dedicated sample-and-hold circuits not in use (AN000 to AN002)	Conversion time*1 (operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	0.88 (0.667)*2	-	-	μs	Sampling in 40 states
	Offset error		-	±1.0	±2.5	LSB	-
	Full-scale error		-	±1.0	±2.5	LSB	-
	Absolute accuracy		-	±2.0	±4.5	LSB	-
	DNL differential nonlinearity error		-	±0.5	±1.5	LSB	-
	INL integral nonlinearity error		-	±1.0	±2.5	LSB	-
High-precision channels (AN003 to AN006)	Conversion time*1 (operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	0.48 (0.267)*2	-	-	μs	Sampling in 16 states
		Max. = 300Ω	0.40 (0.183)*2	-	-	μs	Sampling in 11 states VCC = AVCC0 = 3.0 to 3.6 V 3.0 V ≤ VREFH0 ≤ AVCC0
	Offset error		-	±1.0	±2.5	LSB	-
	Full-scale error		-	±1.0	±2.5	LSB	-
	Absolute accuracy		-	±2.0	±4.5	LSB	-
	DNL differential nonlinearity error		-	±0.5	±1.5	LSB	-
	INL integral nonlinearity error		-	±1.0	±2.5	LSB	-
Normal-precision channels (AN016 to AN021)	Conversion time*1 (Operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	0.88 (0.667)*2	-	-	μs	Sampling in 40 states
	Offset error		-	±1.0	±5.5	LSB	-
	Full-scale error		-	±1.0	±5.5	LSB	-
	Absolute accuracy		-	±2.0	±7.5	LSB	-
	DNL differential nonlinearity error		-	±0.5	±4.5	LSB	-
	INL integral nonlinearity error		-	±1.0	±5.5	LSB	-

Note: These specification values apply when there is no access to the external bus during A/D conversion. If access occurs during A/D conversion, values might not fall within the indicated ranges.

Note 1. The conversion time includes the sampling and comparison times. The number of sampling states is indicated for the test conditions.

Note 2. Values in parentheses indicate the sampling time.

**Table 2.41 A/D conversion characteristics for unit 1 (1/2)**

Conditions: PCLKC = 1 to 60 MHz

Item	Min	Typ	Max	Unit	Test conditions
Frequency	1	-	60	MHz	-
Analog input capacitance	-	-	30	pF	-

**Table 2.41 A/D conversion characteristics for unit 1 (2/2)**

Conditions: PCLKC = 1 to 60 MHz

Item			Min	Typ	Max	Unit	Test conditions
Quantization error			-	±0.5	-	LSB	-
Resolution			-	-	12	Bits	-
Channel-dedicated sample-and-hold circuits in use (AN100 to AN102)	Conversion time*1 (operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	1.06 (0.4 + 0.25)*2	-	-	μs	<ul style="list-style-type: none"> <li>• Sampling of channel-dedicated sample-and-hold circuits in 24 states</li> <li>• Sampling in 15 states</li> </ul>
	Offset error		-	±1.5	±3.5	LSB	AN100 to AN102 = 0.25 V
	Full-scale error		-	±1.5	±3.5	LSB	AN100 to AN102 = VREFH - 0.25 V
	Absolute accuracy		-	±2.5	±5.5	LSB	-
	DNL differential nonlinearity error		-	±1.0	±2.0	LSB	-
	INL integral nonlinearity error		-	±1.5	±3.0	LSB	-
	Holding characteristics of sample-and hold circuits		-	-	20	μs	-
Dynamic range			0.25	-	VREFH - 0.25	V	-
Channel-dedicated sample-and-hold circuits not in use (AN100 to AN102)	Conversion time*1 (Operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	0.88 (0.667)*2	-	-	μs	Sampling in 40 states
	Offset error		-	±1.0	±2.5	LSB	-
	Full-scale error		-	±1.0	±2.5	LSB	-
	Absolute accuracy		-	±2.0	±4.5	LSB	-
	DNL differential nonlinearity error		-	±0.5	±1.5	LSB	-
	INL integral nonlinearity error		-	±1.0	±2.5	LSB	-
High-precision channels (AN103 to AN106)	Conversion time*1 (Operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	0.48 (0.267)*2	-	-	μs	Sampling in 16 states
		Max. = 300Ω	0.40 (0.183)*2	-	-	μs	Sampling in 11 states VCC = AVCC0 = 3.0 to 3.6 V 3.0 V ≤ VREFH ≤ AVCC0
	Offset error		-	±1.0	±2.5	LSB	-
	Full-scale error		-	±1.0	±2.5	LSB	-
	Absolute accuracy		-	±2.0	±4.5	LSB	-
	DNL differential nonlinearity error		-	±0.5	±1.5	LSB	-
	INL integral nonlinearity error		-	±1.0	±2.5	LSB	-
Normal-precision channels (AN116 to AN120)	Conversion time*1 (Operation at PCLKC = 60 MHz)	Permissible signal source impedance Max. = 1 kΩ	0.88 (0.667)*2	-	-	μs	Sampling in 40 states
	Offset error		-	±1.0	±5.5	LSB	-
	Full-scale error		-	±1.0	±5.5	LSB	-
	Absolute accuracy		-	±2.0	±7.5	LSB	-
	DNL differential nonlinearity error		-	±0.5	±4.5	LSB	-
	INL integral nonlinearity error		-	±1.0	±5.5	LSB	-

Note: These specification values apply when there is no access to the external bus during A/D conversion. If access occurs during A/D conversion, values might not fall within the indicated ranges.

Note 1. The conversion time is the sum of the sampling and the comparison times. The number of sampling states is indicated for the test conditions.

Note 2. Values in parentheses indicate the sampling time.

**Table 2.42 A/D internal reference voltage characteristics**

Item	Min	Typ	Max	Unit	Test conditions
A/D internal reference voltage	1.20	1.25	1.30	V	-

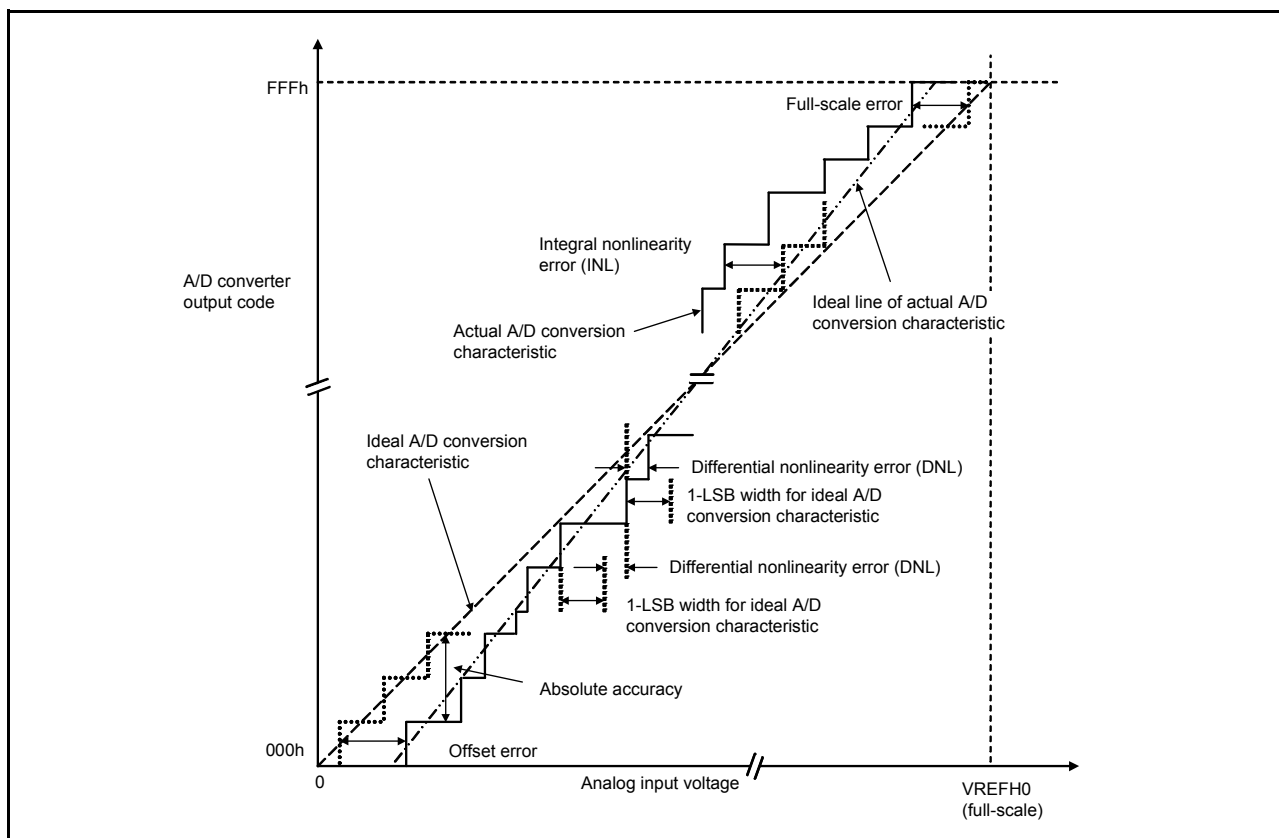


Figure 2.87 Illustration of ADC12 characteristic terms

### Absolute accuracy

Absolute accuracy is the difference between output code based on the theoretical A/D conversion characteristics, and the actual A/D conversion result. When measuring absolute accuracy, the voltage at the midpoint of the width of the analog input voltage (1-LSB width), which can meet the expectation of outputting an equal code based on the theoretical A/D conversion characteristics, is used as an analog input voltage. For example, if 12-bit resolution is used and the reference voltage  $V_{REFH0} = 3.072$  V, then 1-LSB width becomes 0.75 mV, and 0 mV, 0.75 mV, and 1.5 mV are used as the analog input voltages. If the analog input voltage is 6 mV, an absolute accuracy of  $\pm 5$  LSB means that the actual A/D conversion result is in the range of 003h to 00Dh, though an output code of 008h can be expected from the theoretical A/D conversion characteristics.

### Integral nonlinearity error (INL)

Integral nonlinearity error is the maximum deviation between the ideal line when the measured offset and full-scale errors are zeroed, and the actual output code.

### Differential nonlinearity error (DNL)

Differential nonlinearity error is the difference between the 1-LSB width based on the ideal A/D conversion characteristics and the width of the actual output code.

### Offset error

Offset error is the difference between the transition point of the ideal first output code and the actual first output code.

### Full-scale error

Full-scale error is the difference between the transition point of the ideal last output code and the actual last output code.

## 2.6 DAC12 Characteristics

**Table 2.43 D/A conversion characteristics**

Item	Min	Typ	Max	Unit	Test conditions
Resolution	-	-	12	Bits	-
Without output amplifier					
Absolute accuracy	-	-	±24	LSB	Resistive load 2 MΩ
DNL	-	±1.0	±2.0	LSB	Resistive load 2 MΩ
Output impedance	-	7.5	-	kΩ	-
Conversion time	-	-	3.0	μs	Capacitive load 20 pF
With output amplifier					
INL	-	±2.0	±4.0	LSB	-
DNL	-	±1.0	±2.0	LSB	-
Conversion time	-	-	4.0	μs	-
Resistive load	5	-	-	kΩ	-
Capacitive load	-	-	50	pF	-
Output voltage range	0.2	-	VREFH – 0.2	V	-

## 2.7 TSN Characteristics

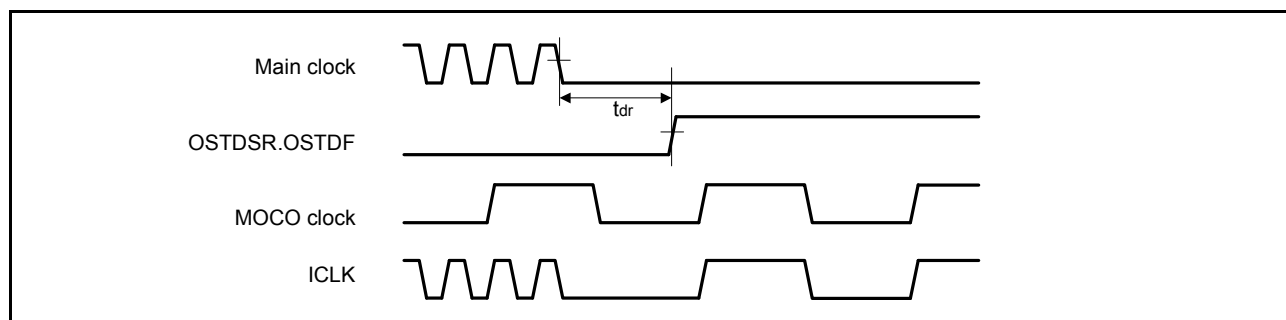
**Table 2.44 TSN characteristics**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
Relative accuracy	-	-	±1.0	-	°C	-
Temperature slope	-	-	4.1	-	mV/°C	-
Output voltage (at 25°C)	-	-	1.24	-	V	-
Temperature sensor start time	t <sub>START</sub>	-	-	30	μs	-
Sampling time	-	4.15	-	-	μs	-

## 2.8 OSC Stop Detect Characteristics

**Table 2.45 Oscillation stop detection circuit characteristics**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
Detection time	t <sub>dr</sub>	-	-	1	ms	Figure 2.88


**Figure 2.88 Oscillation stop detection timing**



## 2.9 POR and LVD Characteristics

Table 2.46 Power-on reset circuit and voltage detection circuit characteristics

Item	Symbol	Min	Typ	Max	Unit	Test conditions		
Voltage detection level	Power-on reset (POR)	Module-stop function disabled*1	$V_{POR}$	2.5	2.6	2.7	V	Figure 2.89
		Module-stop function enabled*2		2.0	2.35	2.7		
	Voltage detection circuit (LVD0)	$V_{det0\_1}$	2.84	2.94	3.04		Figure 2.90	
		$V_{det0\_2}$	2.77	2.87	2.97			
		$V_{det0\_3}$	2.70	2.80	2.90			
	Voltage detection circuit (LVD1)	$V_{det1\_1}$	2.89	2.99	3.09		Figure 2.91	
		$V_{det1\_2}$	2.82	2.92	3.02			
		$V_{det1\_3}$	2.75	2.85	2.95			
	Voltage detection circuit (LVD2)	$V_{det2\_1}$	2.89	2.99	3.09		Figure 2.92	
		$V_{det2\_2}$	2.82	2.92	3.02			
		$V_{det2\_3}$	2.75	2.85	2.95			
	Internal reset time	Power-on reset time	$t_{POR}$	-	4.6	-	ms	Figure 2.89
LVD0 reset time		$t_{LVD0}$	-	0.70	-	Figure 2.90		
LVD1 reset time		$t_{LVD1}$	-	0.57	-	Figure 2.91		
LVD2 reset time		$t_{LVD2}$	-	0.57	-	Figure 2.92		
Minimum VCC down time	$t_{VOFF}$	200	-	-	$\mu$ s	Figure 2.89, Figure 2.90		
Response delay	$t_{det}$	-	-	200	$\mu$ s	Figure 2.89 to Figure 2.92		
LVD operation stabilization time (after LVD is enabled)	$T_{d(E-A)}$	-	-	10	$\mu$ s	Figure 2.91, Figure 2.92		
Hysteresis width (LVD1 and LVD2)	$V_{LVH}$	-	80	-	mV			

Note 1. The minimum VCC down time indicates the time when VCC is below the minimum value of voltage detection levels  $V_{POR}$ ,  $V_{det1}$ , and  $V_{det2}$  for POR and LVD.

Note 2. The low-power function is disabled and DEEPCUT[1:0] = 00b or 01b.

Note 3. The low-power function is enabled and DEEPCUT[1:0] = 11b.

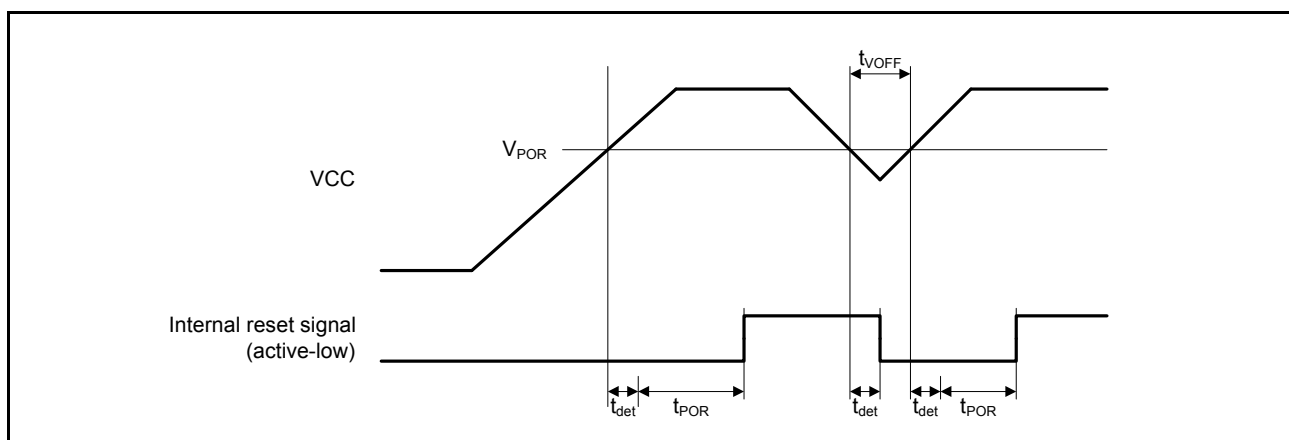


Figure 2.89 Power-on reset timing

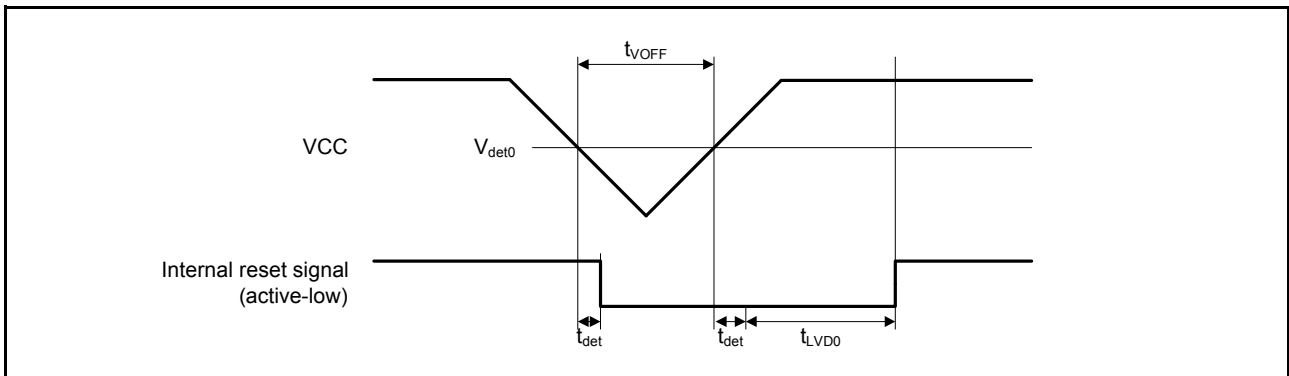


Figure 2.90 Voltage detection circuit timing ( $V_{det0}$ )

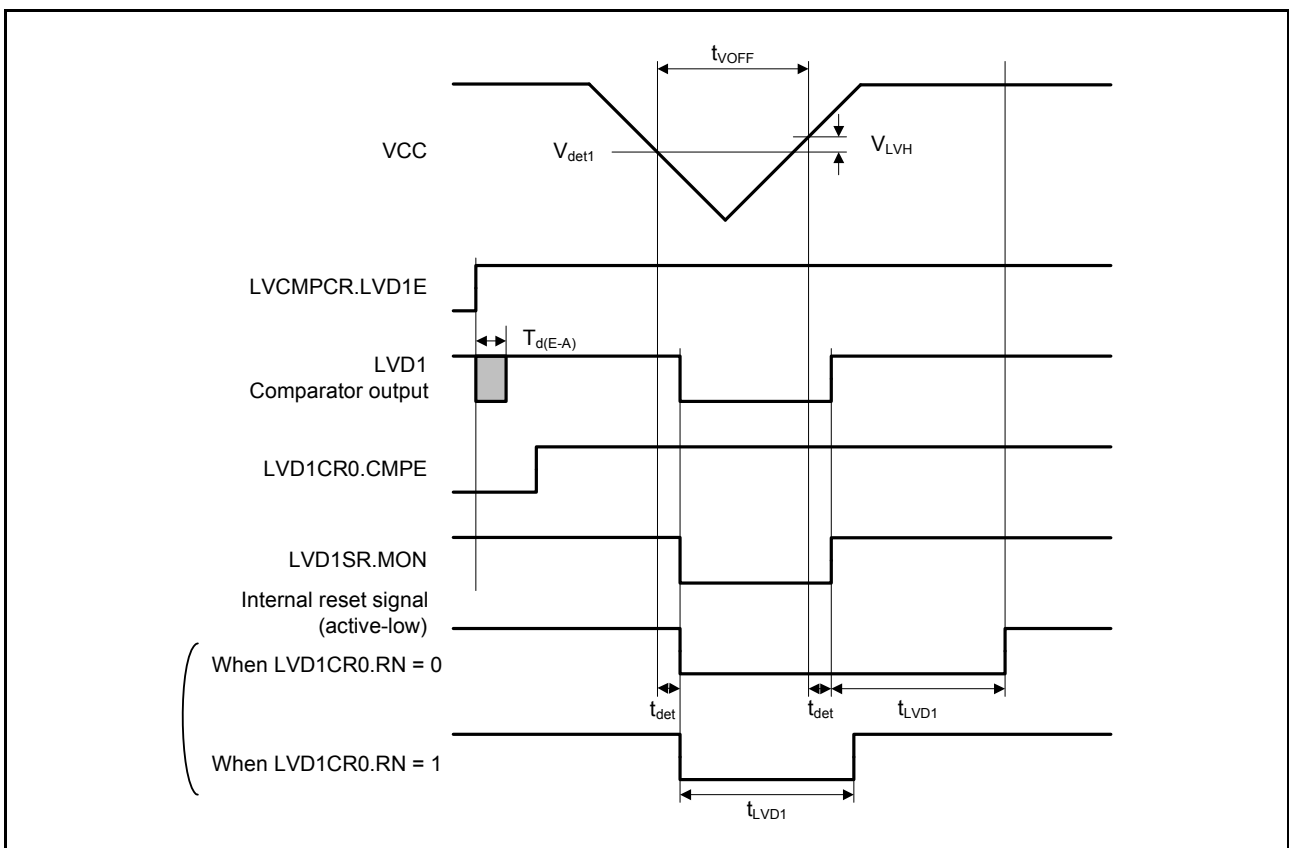


Figure 2.91 Voltage detection circuit timing ( $V_{det1}$ )

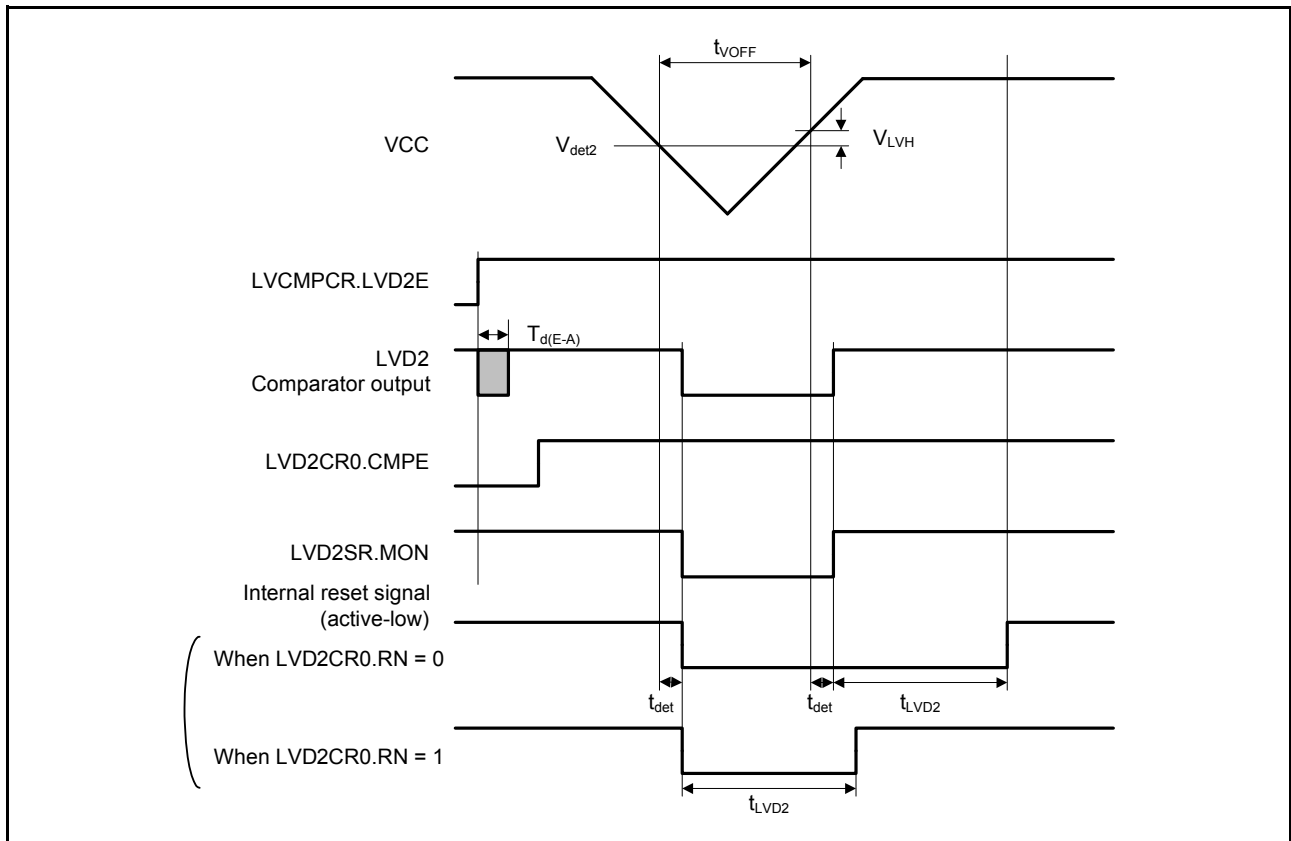


Figure 2.92 Voltage detection circuit timing ( $V_{det2}$ )

### 2.10 VBATT Characteristics

Table 2.47 Battery backup function characteristics

Conditions:  $V_{CC} = AV_{CC0} = V_{CC\_USB} = 2.7$  to  $3.6$  V,  $2.7$  V  $\leq V_{REFH0}/V_{RFEH} \leq AV_{CC0}$ ,  $V_{BATT} = 2.0$  to  $3.6$  V

Item	Symbol	Min	Typ	Max	Unit	Test conditions
Voltage level for switching to battery backup	$V_{DET\ BATT}$	2.50	2.60	2.70	V	Figure 2.93
Lower-limit $V_{BATT}$ voltage for power supply switching caused by $V_{CC}$ voltage drop	$V_{BATT\ SW}$	2.70	-	-	V	
$V_{CC}$ -off period for starting power supply switching	$t_{VOFF\ BATT}$	200	-	-	$\mu$ s	

Note: The  $V_{CC}$ -off period for starting power supply switching indicates the period in which  $V_{CC}$  is below the minimum value of the voltage level for switching to battery backup ( $V_{DET\ BATT}$ ).

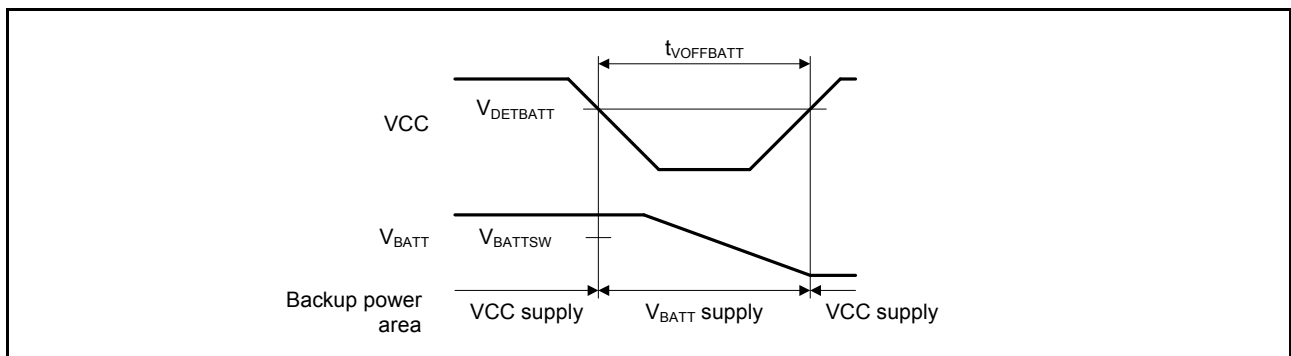


Figure 2.93 Battery backup function characteristics

## 2.11 CTSU Characteristics

**Table 2.48 CTSU characteristics**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
External capacitance connected to TSCAP pin	$C_{tscap}$	9	10	11	nF	-
TS pin capacitive load	$C_{base}$	-	-	50	pF	-
Permissible output high current	$\Sigma_{IoH}$	-	-	-40	mA	When the mutual capacitance method is applied

## 2.12 Comparator Characteristics

**Table 2.49 ACMPHS characteristics**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
Reference voltage range	VREF	0	-	AVCC0	V	-
Input voltage range	VI	0	-	AVCC0	V	-
Output delay*1	Td	-	50	100	ns	VI = VREF ± 100 mV

Note 1. This value is the internal propagation delay.

## 2.13 PGA Characteristics

**Table 2.50 PGA characteristics in single mode (1/2)**

Item	Symbol	Min	Typ	Max	Unit
PGA/VSS input voltage range	PGA/VSS	0	-	0	V
	AIN0 (G = 2.000)	$0.050 \times AVCC0$	-	$0.45 \times AVCC0$	V
	AIN1 (G = 2.500)	$0.047 \times AVCC0$	-	$0.360 \times AVCC0$	V
	AIN2 (G = 2.667)	$0.046 \times AVCC0$	-	$0.337 \times AVCC0$	V
	AIN3 (G = 2.857)	$0.046 \times AVCC0$	-	$0.32 \times AVCC0$	V
	AIN4 (G = 3.077)	$0.045 \times AVCC0$	-	$0.292 \times AVCC0$	V
	AIN5 (G = 3.333)	$0.044 \times AVCC0$	-	$0.265 \times AVCC0$	V
	AIN6 (G = 3.636)	$0.042 \times AVCC0$	-	$0.247 \times AVCC0$	V
	AIN7 (G = 4.000)	$0.040 \times AVCC0$	-	$0.212 \times AVCC0$	V
	AIN8 (G = 4.444)	$0.036 \times AVCC0$	-	$0.191 \times AVCC0$	V
	AIN9 (G = 5.000)	$0.033 \times AVCC0$	-	$0.17 \times AVCC0$	V
	AIN10 (G = 5.714)	$0.031 \times AVCC0$	-	$0.148 \times AVCC0$	V
	AIN11 (G = 6.667)	$0.029 \times AVCC0$	-	$0.127 \times AVCC0$	V
	AIN12 (G = 8.000)	$0.027 \times AVCC0$	-	$0.09 \times AVCC0$	V
	AIN13 (G = 10.000)	$0.025 \times AVCC0$	-	$0.08 \times AVCC0$	V
AIN14 (G = 13.333)	$0.023 \times AVCC0$	-	$0.06 \times AVCC0$	V	

**Table 2.50 PGA characteristics in single mode (2/2)**

Item	Symbol	Min	Typ	Max	Unit
Gain error	Gerr0 (G = 2.000)	-1.0	-	1.0	%
	Gerr1 (G = 2.500)	-1.0	-	1.0	%
	Gerr2 (G = 2.667)	-1.0	-	1.0	%
	Gerr3 (G = 2.857)	-1.0	-	1.0	%
	Gerr4 (G = 3.077)	-1.0	-	1.0	%
	Gerr5 (G = 3.333)	-1.5	-	1.5	%
	Gerr6 (G = 3.636)	-1.5	-	1.5	%
	Gerr7 (G = 4.000)	-1.5	-	1.5	%
	Gerr8 (G = 4.444)	-2.0	-	2.0	%
	Gerr9 (G = 5.000)	-2.0	-	2.0	%
	Gerr10 (G = 5.714)	-2.0	-	2.0	%
	Gerr11 (G = 6.667)	-2.0	-	2.0	%
	Gerr12 (G = 8.000)	-2.0	-	2.0	%
	Gerr13 (G = 10.000)	-2.0	-	2.0	%
Gerr14 (G = 13.333)	-2.0	-	2.0	%	
Offset error	Voff	-8	-	8	mV

**Table 2.51 PGA characteristics in differential mode**

Item	Symbol	Min	Typ	Max	Unit	
PGAVSS input voltage range	PGAVSS	-0.3	-	0.3	V	
Differential input voltage range (G = 1.500)	AIN-PGAVSS	-0.5	-	0.5	V	
Input voltage range (G = 2.333)		-0.4	-	0.4	V	
Input voltage range (G = 4.000)		-0.2	-	0.2	V	
Input voltage range (G = 5.667)		-0.15	-	0.15	V	
Gain error	G = 1.500	Gerr	-2.5	-	2.5	%
	G = 2.333		-2	-	2	
	G = 4.000		-1	-	1	
	G = 5.667		-1	-	1	

## 2.14 Flash Memory Characteristics

### 2.14.1 Code Flash Memory Characteristics

**Table 2.52 Code flash memory characteristics (1/2)**

Conditions: Program or erase: FCLK = 4 to 60 MHz  
Read: FCLK ≤ 60 MHz

Item	Symbol	FCLK = 4 MHz			20 MHz ≤ FCLK ≤ 60 MHz			Unit	
		Min	Typ	Max	Min	Typ	Max		
Programming time $N_{PEC} \leq 100$ times	256-byte	$t_{P256}$	-	0.9	13.2	-	0.4	6	ms
	8-KB	$t_{P8K}$	-	29	176	-	13	80	ms
	32-KB	$t_{P32K}$	-	116	704	-	52	320	ms
Programming time $N_{PEC} > 100$ times	256-byte	$t_{P256}$	-	1.1	15.8	-	0.5	7.2	ms
	8-KB	$t_{P8K}$	-	35	212	-	16	96	ms
	32-KB	$t_{P32K}$	-	140	848	-	64	384	ms
Erasure time $N_{PEC} \leq 100$ times	8-KB	$t_{E8K}$	-	71	216	-	39	120	ms
	32-KB	$t_{E32K}$	-	254	864	-	141	480	ms

**Table 2.52 Code flash memory characteristics (2/2)**

Conditions: Program or erase: FCLK = 4 to 60 MHz

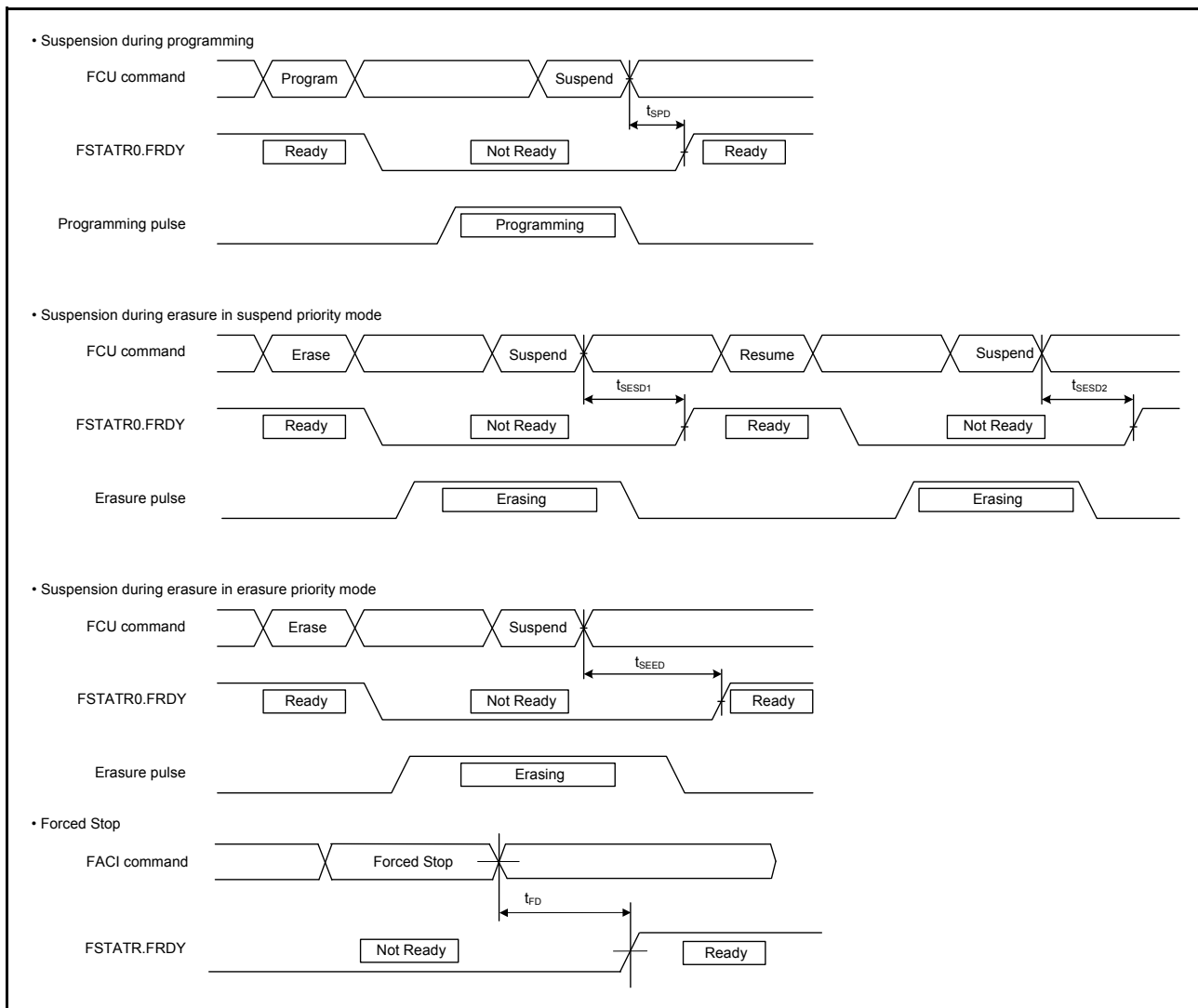
Read: FCLK ≤ 60 MHz

Item		Symbol	FCLK = 4 MHz			20 MHz ≤ FCLK ≤ 60 MHz			Unit
			Min	Typ	Max	Min	Typ	Max	
Erasure time N <sub>PEC</sub> > 100 times	8-KB	t <sub>E8K</sub>	-	85	260	-	47	144	ms
	32-KB	t <sub>E32K</sub>	-	304	1040	-	169	576	ms
Reprogramming/erase cycle*1		N <sub>PEC</sub>	1000*2	-	-	1000*2	-	-	Times
Suspend delay during programming		t <sub>SPD</sub>	-	-	264	-	-	120	μs
First suspend delay during erasure in suspend priority mode		t <sub>SESD1</sub>	-	-	216	-	-	120	μs
Second suspend delay during erasure in suspend priority mode		t <sub>SESD2</sub>	-	-	1.7	-	-	1.7	ms
Suspend delay during erasure in erasure priority mode		t <sub>SEED</sub>	-	-	1.7	-	-	1.7	ms
Forced stop command		t <sub>FD</sub>	-	-	32	-	-	20	μs
Data hold time*3		t <sub>DRP</sub>	20	-	-	20	-	-	Years
FCU reset time		t <sub>FCUR</sub>	35	-	-	35	-	-	μs

Note 1. The reprogram/erase cycle is the number of erasures for each block. When the reprogram/erase cycle is n times (n = 1,000), erasing can be performed n times for each block. For example, when 256-byte programming is performed 32 times for different addresses in 8-KB blocks, and then the entire block is erased, the reprogram/erase cycle is counted as one. However, programming the same address several times as one erasure is not enabled. (Overwriting is prohibited.)

Note 2. This is the minimum number of times to guarantee all the characteristics after reprogramming. The guaranteed range is from 1 to the minimum value.

Note 3. This indicates the characteristics when reprogramming is performed within the specified range, including the minimum value.



**Figure 2.94** Suspension and forced stop timing for flash memory programming and erasure

### 2.14.2 Data Flash Memory Characteristics

**Table 2.53** Data flash memory characteristics (1/2)

Conditions: Program or erase: FCLK = 4 to 60 MHz  
Read: FCLK ≤ 60 MHz

Item	Symbol	FCLK = 4 MHz			20 MHz ≤ FCLK ≤ 60 MHz			Unit	
		Min	Typ	Max	Min	Typ	Max		
Programming time	4-byte	$t_{DP4}$	-	0.36	3.8	-	0.16	1.7	ms
Erase time	64-byte	$t_{DE64}$	-	3.1	18	-	1.7	10	ms
Blank check time	4-byte	$t_{DBC4}$	-	-	84	-	-	30	μs
Reprogramming/erasure cycle*1		$N_{DPEC}$	125000*2	-	-	125000*2	-	-	-
Suspend delay during programming		$t_{DSPD}$	-	-	264	-	-	120	μs
First suspend delay during erasure in suspend priority mode		$t_{DSESD1}$	-	-	216	-	-	120	μs
Second suspend delay during erasure in suspend priority mode		$t_{DSESD2}$	-	-	300	-	-	300	μs
Suspend delay during erasing in erasure priority mode		$t_{DSEED}$	-	-	300	-	-	300	μs

**Table 2.53 Data flash memory characteristics (2/2)**

Conditions: Program or erase: FCLK = 4 to 60 MHz  
Read: FCLK ≤ 60 MHz

Item	Symbol	FCLK = 4 MHz			20 MHz ≤ FCLK ≤ 60 MHz			Unit
		Min	Typ	Max	Min	Typ	Max	
Forced stop command	$t_{FD}$	-	-	32	-	-	20	μs
Data hold time*3	$t_{DDRP}$	20	-	-	20	-	-	Year

Note 1. The reprogram/erase cycle is the number of erasures for each block. When the reprogram/erase cycle is n times (n = 125,000), erasing can be performed n times for each block. For example, when 4-byte programming is performed 16 times for different addresses in 64-byte blocks, and then the entire block is erased, the reprogram/erase cycle is counted as one. However, programming the same address several times as one erasure is not enabled. (Overwriting is prohibited.)

Note 2. This is the minimum number of times to guarantee all the characteristics after reprogramming. The guaranteed range is from 1 to the minimum value.

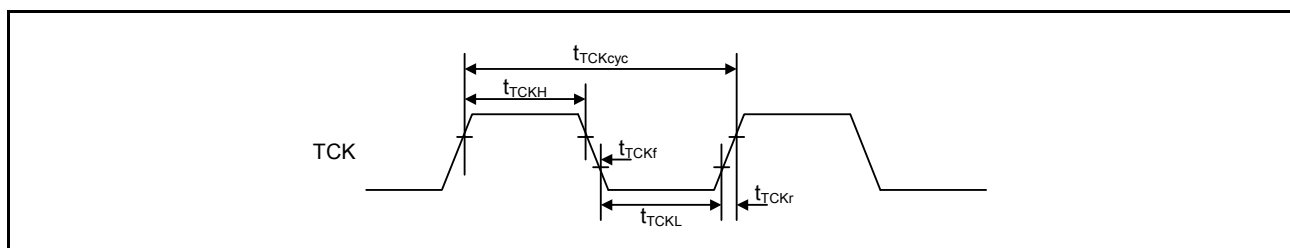
Note 3. This indicates the characteristics when reprogramming is performed within the specified range, including the minimum value.

## 2.15 Boundary Scan

**Table 2.54 Boundary scan characteristics**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
TCK clock cycle time	$t_{TCKcyc}$	100	-	-	ns	Figure 2.95
TCK clock high pulse width	$t_{TCKH}$	45	-	-	ns	
TCK clock low pulse width	$t_{TCKL}$	45	-	-	ns	
TCK clock rise time	$t_{TCKr}$	-	-	5	ns	
TCK clock fall time	$t_{TCKf}$	-	-	5	ns	
TMS setup time	$t_{TMSS}$	20	-	-	ns	Figure 2.96
TMS hold time	$t_{TMSH}$	20	-	-	ns	
TDI setup time	$t_{TDIS}$	20	-	-	ns	
TDI hold time	$t_{TDIH}$	20	-	-	ns	
TDO data delay	$t_{TDOD}$	-	-	40	ns	Figure 2.97
Boundary scan circuit startup time*1	$T_{BSSTUP}$	$t_{RESWP}$	-	-	-	

Note 1. Boundary scan does not function until the power-on reset becomes negative.

**Figure 2.95 Boundary scan TCK timing**



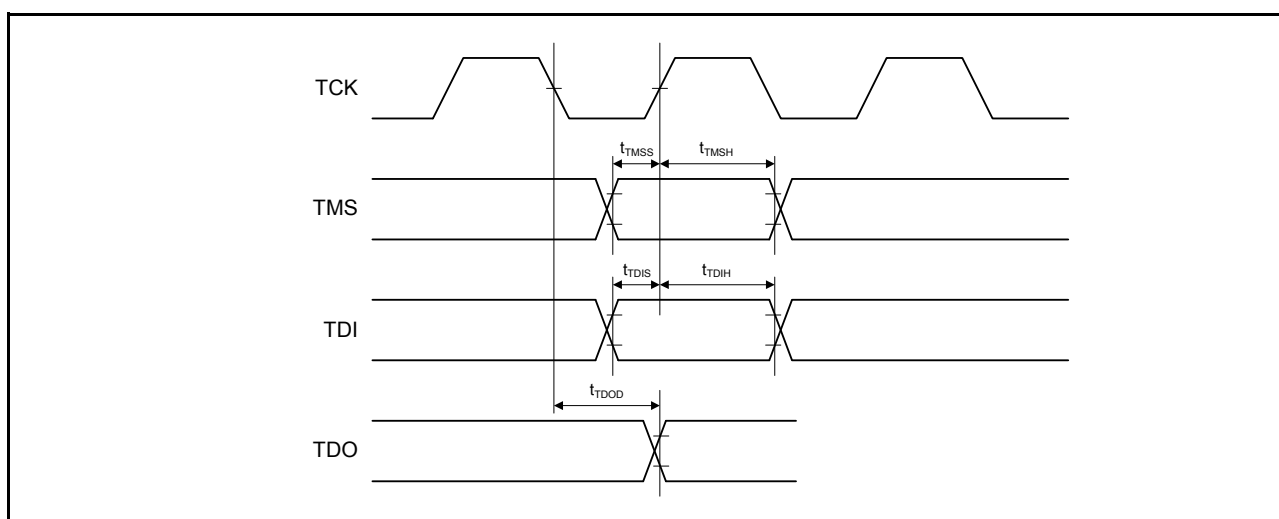


Figure 2.96 Boundary scan input/output timing

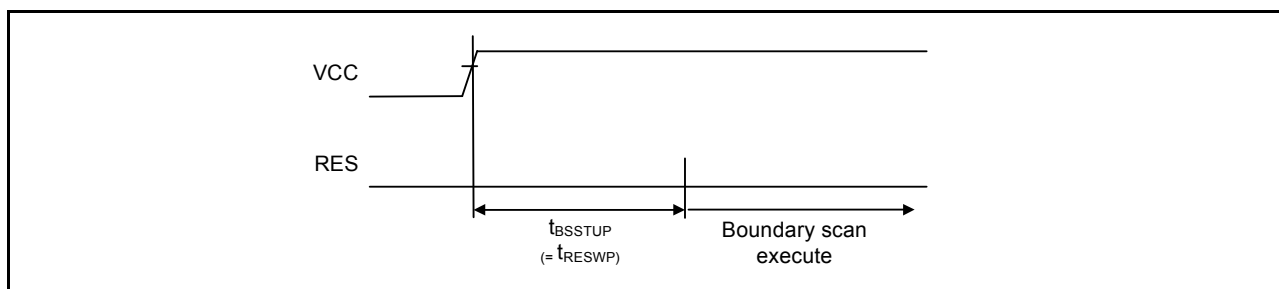


Figure 2.97 Boundary scan circuit startup timing

## 2.16 Joint European Test Action Group (JTAG)

Table 2.55 JTAG

Item	Symbol	Min	Typ	Max	Unit	Test conditions
TCK clock cycle time	$t_{TCKcyc}$	40	-	-	ns	Figure 2.95
TCK clock high pulse width	$t_{TCKH}$	15	-	-	ns	
TCK clock low pulse width	$t_{TCKL}$	15	-	-	ns	
TCK clock rise time	$t_{TCKr}$	-	-	5	ns	
TCK clock fall time	$t_{TCKf}$	-	-	5	ns	
TMS setup time	$t_{TMSS}$	8	-	-	ns	Figure 2.96
TMS hold time	$t_{TMSH}$	8	-	-	ns	
TDI setup time	$t_{TDIS}$	8	-	-	ns	
TDI hold time	$t_{TDIH}$	8	-	-	ns	
TDO data delay time	$t_{TDOD}$	-	-	28	ns	

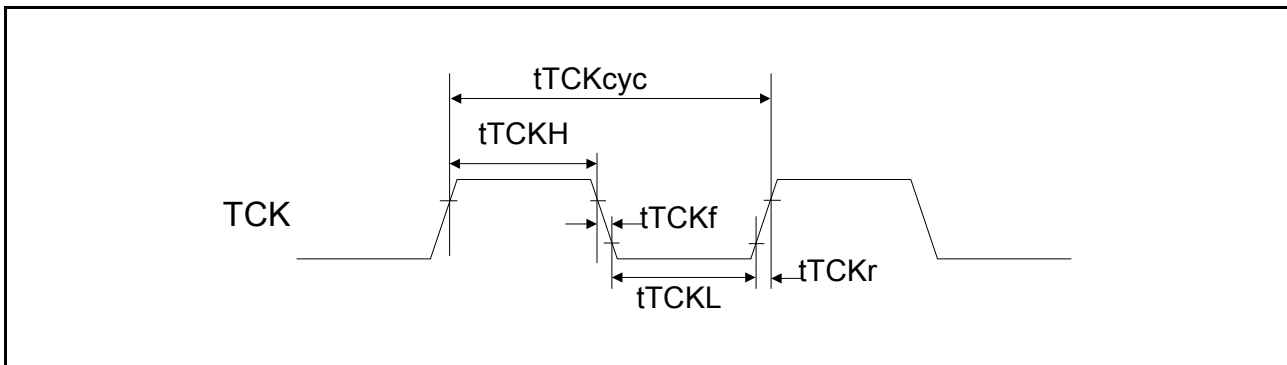


Figure 2.98 JTAG TCK timing

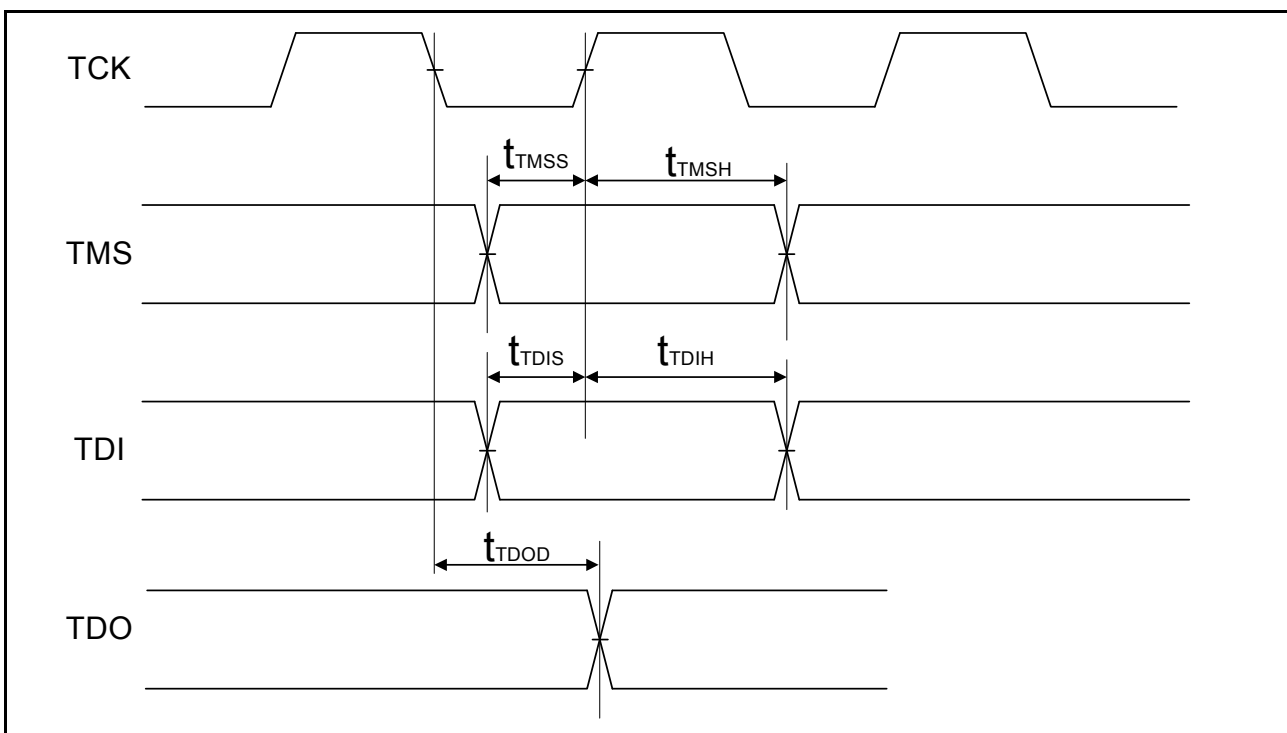


Figure 2.99 JTAG input/output timing

## 2.17 Serial Wire Debug (SWD)

Table 2.56 SWD

Item	Symbol	Min	Typ	Max	Unit	Test conditions
SWCLK clock cycle time	$t_{\text{SWCKcyc}}$	40	-	-	ns	Figure 2.100
SWCLK clock high pulse width	$t_{\text{SWCKH}}$	15	-	-	ns	
SWCLK clock low pulse width	$t_{\text{SWCKL}}$	15	-	-	ns	
SWCLK clock rise time	$t_{\text{SWCKr}}$	-	-	5	ns	
SWCLK clock fall time	$t_{\text{SWCKf}}$	-	-	5	ns	
SWDIO setup time	$t_{\text{SWDS}}$	8	-	-	ns	Figure 2.101
SWDIO hold time	$t_{\text{SWDH}}$	8	-	-	ns	
SWDIO data delay time	$t_{\text{SWDD}}$	2	-	28	ns	

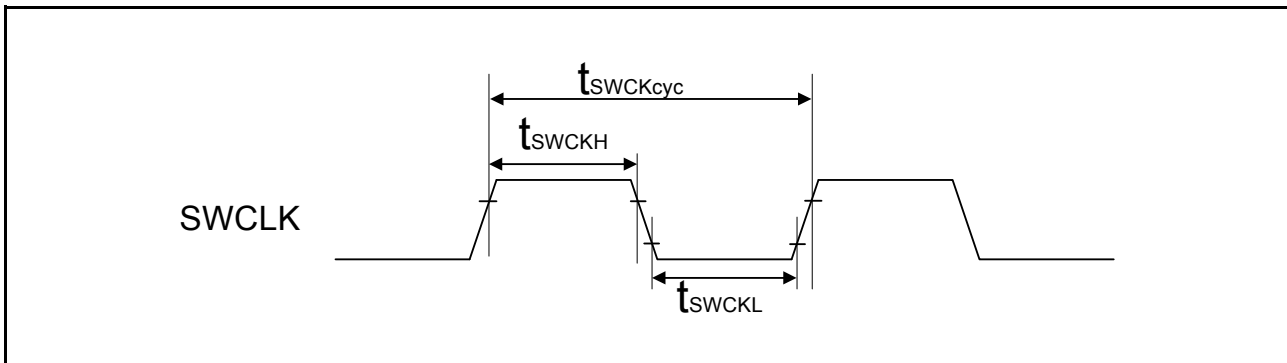


Figure 2.100 SWD SWCLK timing

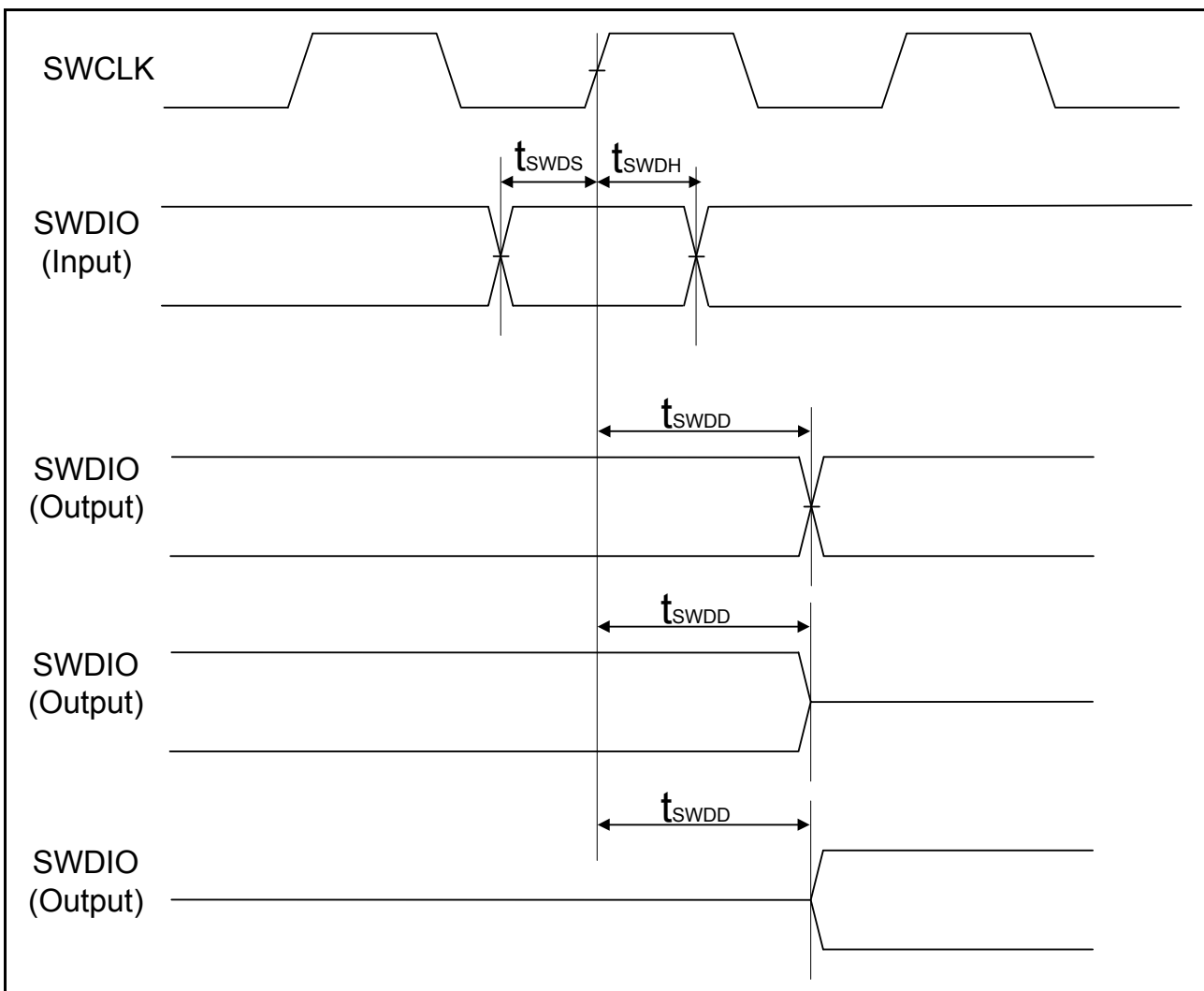
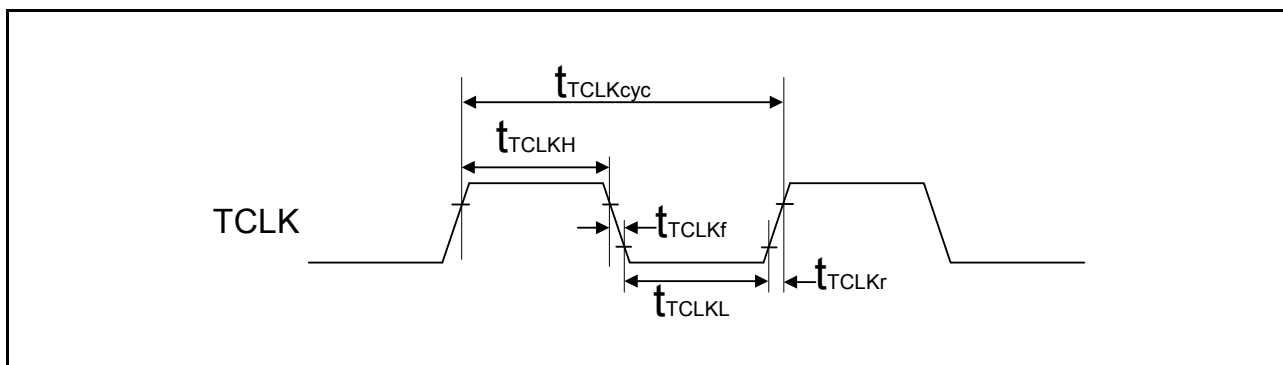


Figure 2.101 SWD input/output timing

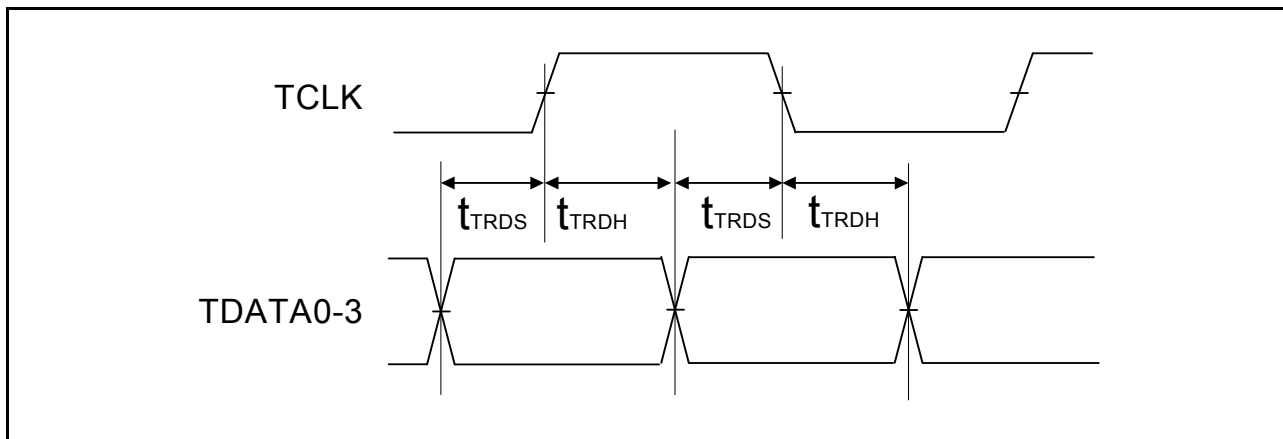
### 2.18 Embedded Trace Macro Interface (ETM)

**Table 2.57 ETM**

Item	Symbol	Min	Typ	Max	Unit	Test conditions
TCLK clock cycle time	$t_{TCLKcyc}$	16.6	-	-	ns	Figure 2.102
TCLK clock high pulse width	$t_{TCLKH}$	5.8	-	-	ns	
TCLK clock low pulse width	$t_{TCLKL}$	5.8	-	-	ns	
TCLK clock rise time	$t_{TCLKr}$	-	-	2.5	ns	
TCLK clock fall time	$t_{TCLKf}$	-	-	2.5	ns	
TDATA0-3 output setup time	$t_{TRDS}$	1.6	-	-	ns	Figure 2.103
TDATA0-3 output hold time	$t_{TRDH}$	1.6	-	-	ns	



**Figure 2.102 ETM TCLK timing**



**Figure 2.103 ETM output timing**

## Appendix 1. Package Dimensions

For information on the latest version of the package dimensions or mountings, go to “Packages” on the Renesas Electronics Corporation website.

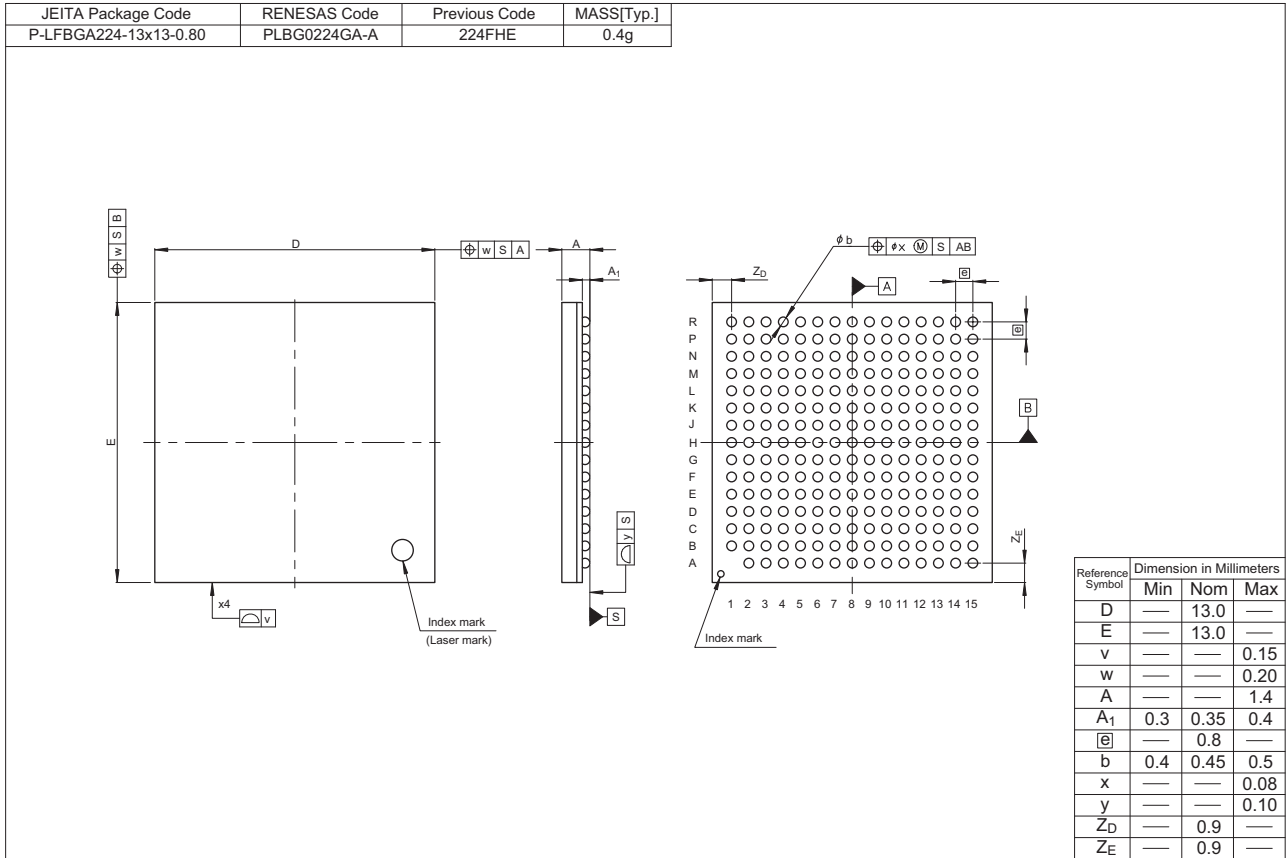


Figure 1.1 224-pin BGA

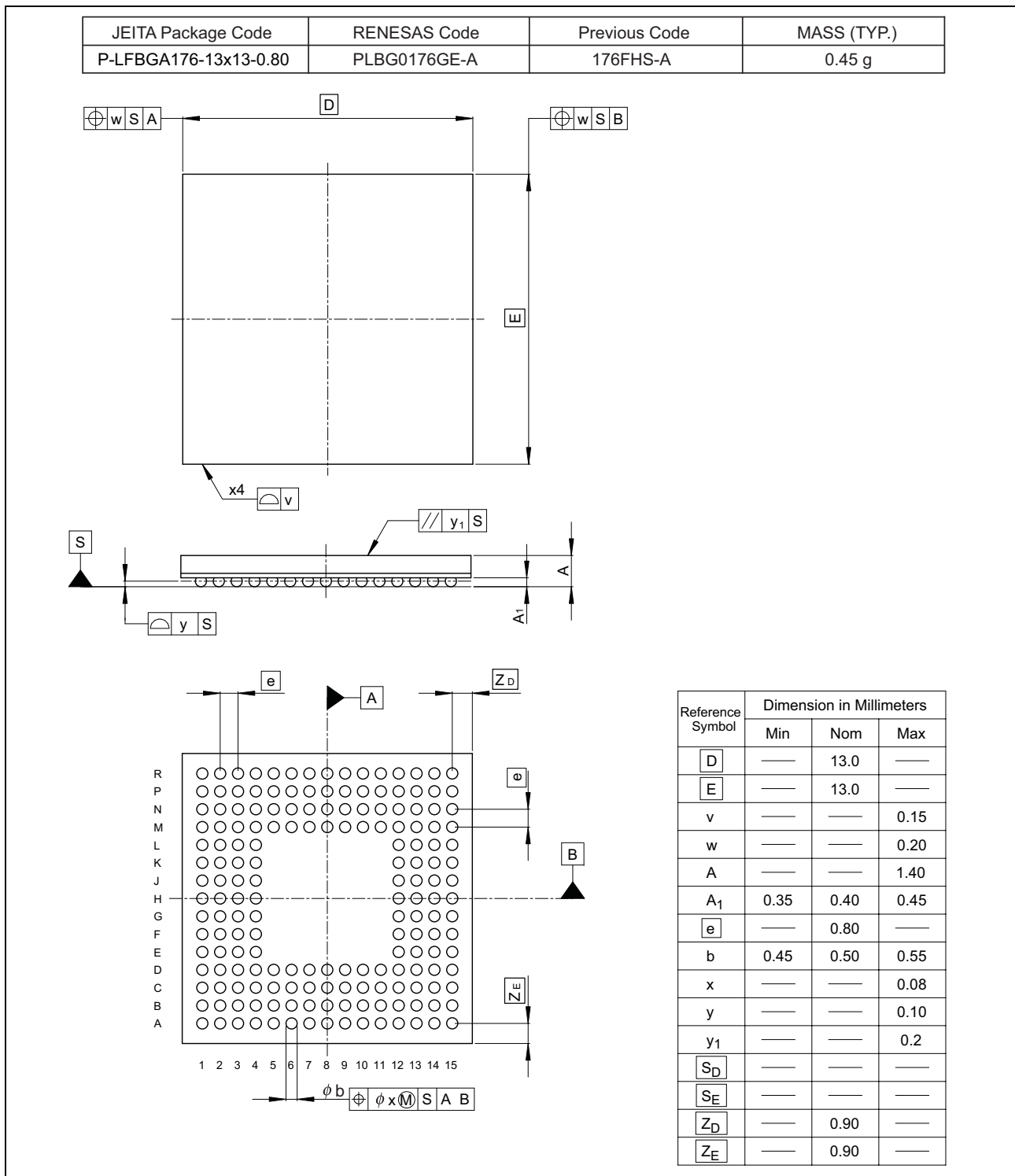


Figure 1.2 176-pin BGA

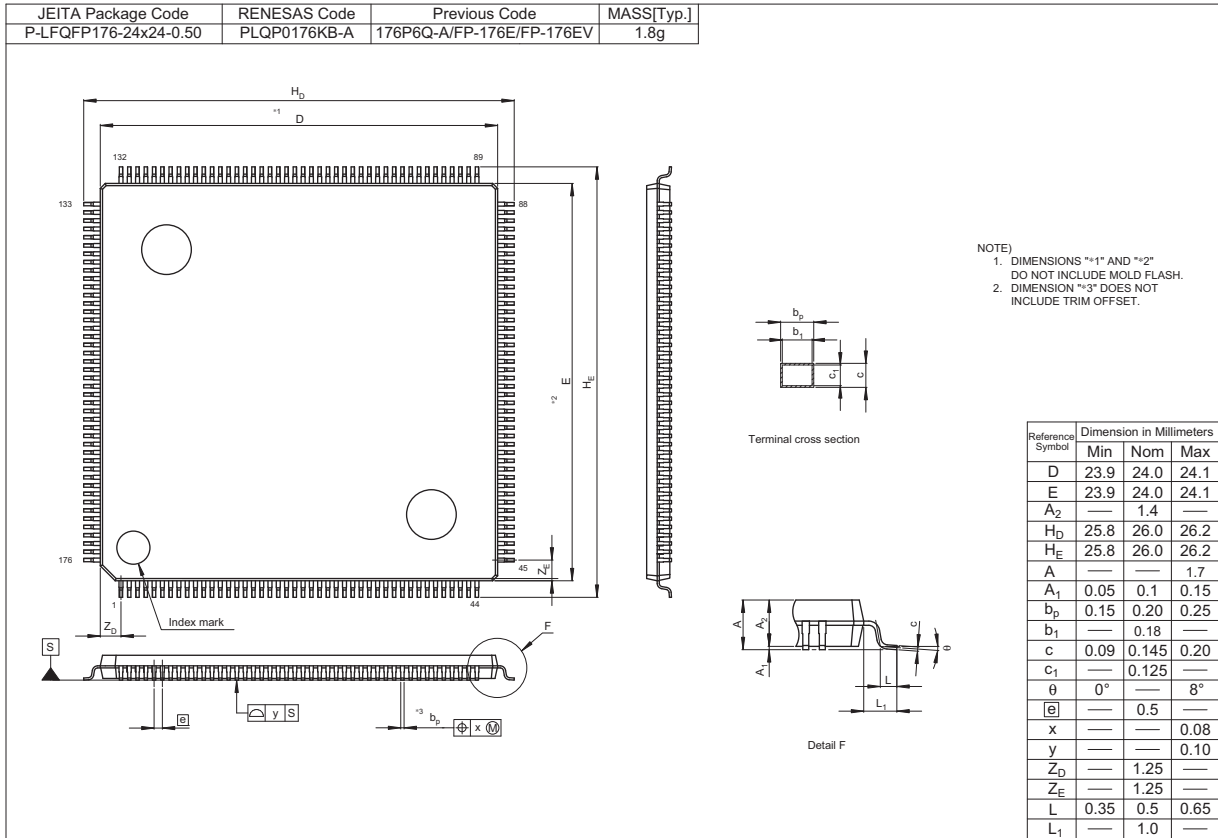


Figure 1.3 176-pin LQFP

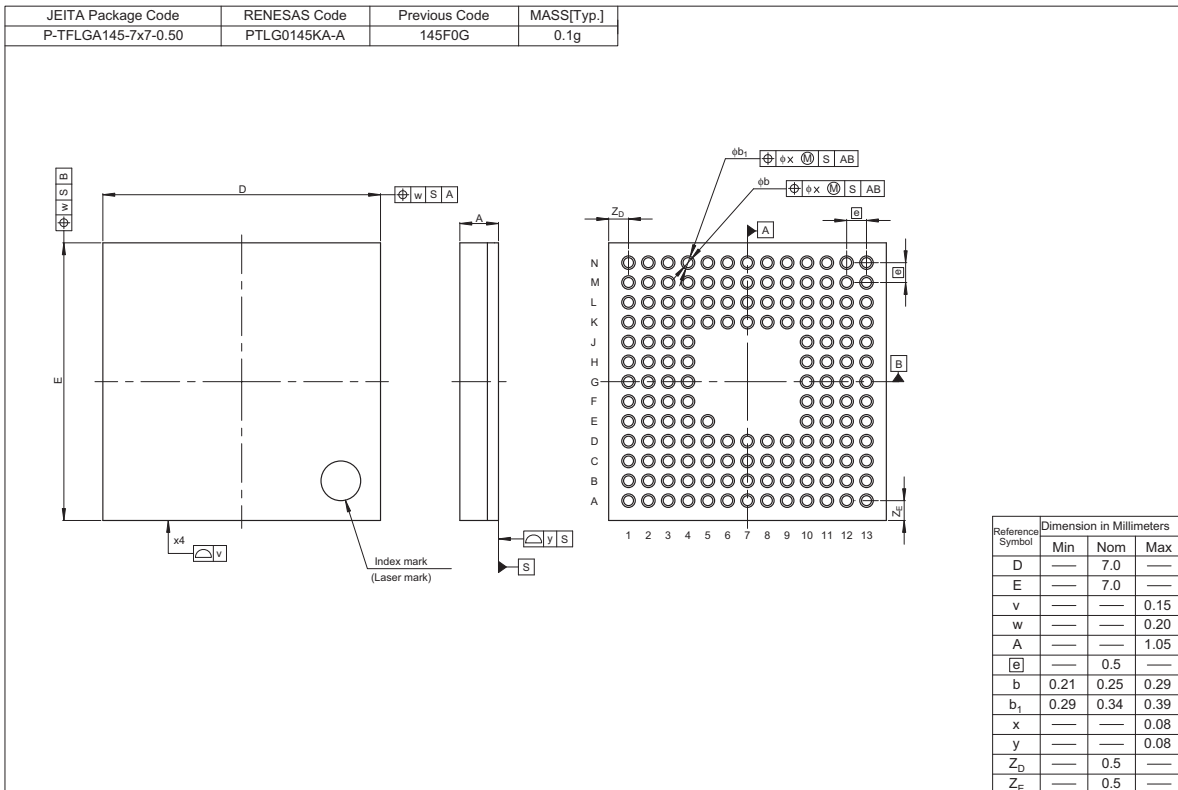


Figure 1.4 145-pin LGA

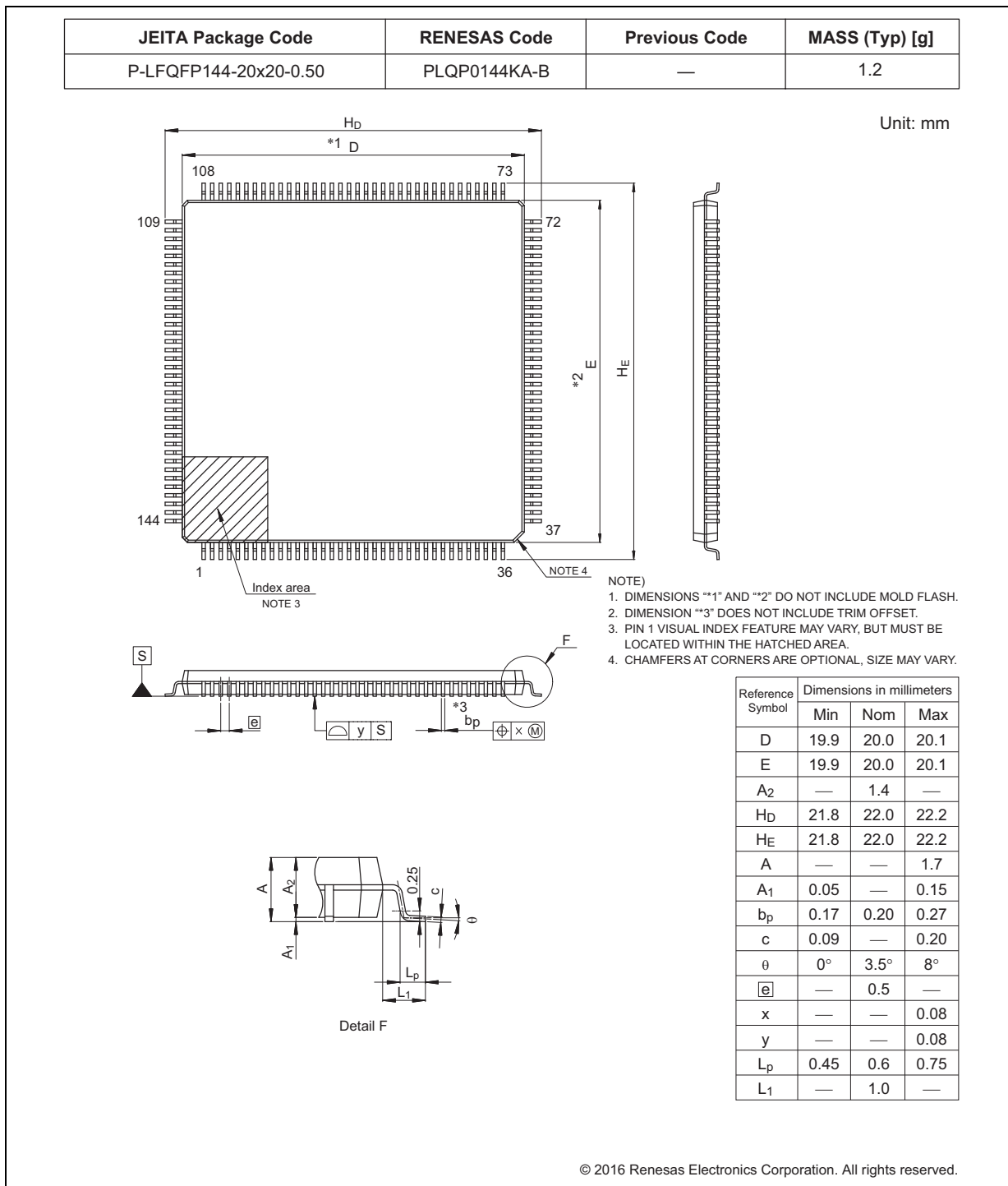
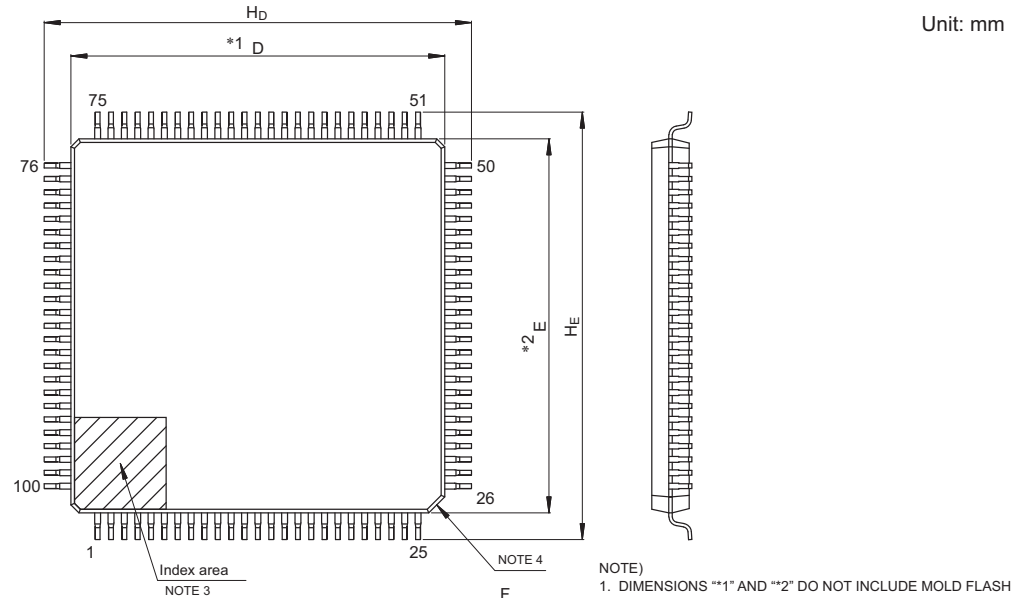


Figure 1.5 144-pin LQFP



JEITA Package Code	RENESAS Code	Previous Code	MASS (Typ) [g]
P-LFQFP100-14x14-0.50	PLQP0100KB-B	—	0.6



Unit: mm

- NOTE)
1. DIMENSIONS \*\*1" AND \*\*2" DO NOT INCLUDE MOLD FLASH.
  2. DIMENSION \*\*3" DOES NOT INCLUDE TRIM OFFSET.
  3. PIN 1 VISUAL INDEX FEATURE MAY VARY, BUT MUST BE LOCATED WITHIN THE HATCHED AREA.
  4. CHAMFERS AT CORNERS ARE OPTIONAL, SIZE MAY VARY.

Reference Symbol	Dimensions in millimeters		
	Min	Nom	Max
D	13.9	14.0	14.1
E	13.9	14.0	14.1
A <sub>2</sub>	—	1.4	—
H <sub>D</sub>	15.8	16.0	16.2
H <sub>E</sub>	15.8	16.0	16.2
A	—	—	1.7
A <sub>1</sub>	0.05	—	0.15
b <sub>p</sub>	0.15	0.20	0.27
c	0.09	—	0.20
θ	0°	3.5°	8°
ⓔ	—	0.5	—
x	—	—	0.08
y	—	—	0.08
L <sub>p</sub>	0.45	0.6	0.75
L <sub>1</sub>	—	1.0	—

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Figure 1.6 100-pin LQFP

Revision History	S7G2 Datasheet
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Rev.	Date	Chapter	Summary
0.80	Oct. 12, 2015	—	First Edition issued
0.85	Dec. 15, 2015	—	Second Edition issued
1.00	Feb. 23, 2016	section 1, Overview	Updated VREFH and VREFL descriptions in Table 1.16, Pin functions
		section 2, Electrical Characteristics	Updated operating and standby current information in section 2.2.5, Operating and Standby Current
			Added section 2.16, Joint European Test Action Group (JTAG)
			Added section 2.17, Serial Wire Debug (SWD)
			Added section 2.18, Embedded Trace Macro Interface (ETM)
			Updated Table 2.13, Clock timing except for sub-clock oscillator
			Updated SPI data in Table 2.25, SPI timing
			Updated Table 2.40, A/D conversion characteristics for unit 0
			Updated Table 2.41, A/D conversion characteristics for unit 1
			Updated SPI data in Figure 2.45, SPI timing for master when CPHA = 0 and the bit rate is set to PCLKA/2
			Updated Table 2.5, I/O IOH, IOL
All	Deleted # from pin names		

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## General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

### 1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

### 2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

### 3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

### 4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

### 5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

### 6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.).

### 7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

### 8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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